Immiscible fluid displacement in porous media with spatially correlated particle sizes

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Abstract

Immiscible fluid displacement in porous media is fundamental for many environmental processes, including infiltration of water in soils, groundwater remediation, enhanced recovery of hydrocarbons and CO_2 geosequestration. Microstructural heterogeneity, in particular of particle sizes, can significantly impact immiscible displacement. For instance, it may lead to unstable flow and preferential displacement patterns. We present a systematic, quantitative pore-scale study of the impact of spatial correlations in particle sizes on the drainage of a partially-wetting fluid. We perform pore-network simulations with varying flow rates and different degrees of spatial correlation, complemented with microfluidic experiments. Simulated and experimental displacement patterns show that spatial correlation leads to more preferential invasion, with reduced trapping of the defending fluid, especially at low flow rates. Numerically, we find that increasing the correlation length reduces the fluid-fluid interfacial area and the trapping of the defending fluid, and increases the invasion pattern asymmetry and selectivity. Our experiments, conducted for low capillary numbers, support these findings. Our results delineate the significant effect of spatial correlations on fluid displacement in porous media, of relevance to a wide range of natural and engineered processes.

Keywords: Porous media, Immiscible displacement, Heterogeneity, Spatial correlation, Pore-scale model, Microfluidic experiments

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1 1. Introduction

Fluid displacement plays a key role in many natural and engineered environmental applica-2 tions [1], for example the infiltration of water into soil [2], groundwater contamination and soil 3 remediation [3, 4], enhanced hydrocarbon recovery [5] and CO_2 sequestration [6]. While these processes are typically observed and modeled over large spatial scales (meters and above), the 5 physical behavior at the pore-scale is crucial to understanding and predicting emergent behavior 6 and the selection of particular flow patterns, such as fingering [7, 8]. Structural heterogeneity an inherent feature of porous and fractured media such as soils, sediments and rocks [9, 10, 11]— 8 strongly impacts fluid displacement. Specifically, it can lead to unstable or preferential flows, 9 which affect processes such as water redistribution in soil [12], pressure-saturation relationships 10 in granular media [13], evaporative drying [14], solute transport [15] and even the distribution of 11 fresh and saline groundwater at the continental shelf [16]. Recent works indicate the increasing 12 interest in the role of the microstructure of a porous medium in fluid displacement and transport 13 processes within it [17, 14, 18, 19]. For instance, it has been shown that the local correlations 14 between pore sizes can have a greater effect on flow velocities than the pore size distribution 15 itself [17]. 16

Fluid invasion patterns are determined by the competition between a number of processes and 17 flow parameters, including gravity, the fluid viscosity and the wettability of the solid material, 18 as well as pore sizes and internal topology [20, 7, 21]. Here, in the absence of gravity and 19 wettability effects (namely, for a strongly wetting defending fluid), the displacement patterns are 20 controlled by two dimensionless groups: the viscosity ratio $\mathcal{M} = \mu_i / \mu_d$, where μ_i and μ_d are 21 the viscosities of the invading and defending fluid, respectively, and the capillary number Ca = 22 $\mu_d v / \sigma$, where v and σ are the characteristic liquid velocity and interfacial tension, respectively 23 [1]. In drainage, for $\mathcal{M} < 1$, displacement patterns vary from capillary fingering (CF) at low 24 Ca to viscous fingering (VF) at high Ca. When $\mathcal{M} \ll 1$, viscous instabilities dominate and 25 VF patterns are formed regardless of the flow rate [22]. Morphologically, CF patterns approach 26 a fractal shape, and are characterized by many trapped defending fluid clusters, whereas VF 27 patterns exhibit thin, branching fingers, with fewer interconnections and, hence, reduced trapping 28 [23, 24]. Reducing the wettability of the defending fluid leads to cooperative pore filling, which 29 results in a more compact pattern with a smoother fluid-fluid interface at low Ca and $\mathcal{M} < 1$ 30 31 [25, 21, 24].

The microstructure of a porous medium, characterized by both the distribution and the spatial 32 arrangement of pores of various sizes, also has a substantial impact on fluid displacement pat-33 terns [26, 27, 24, 28]. For example, the transition between VF and CF depends on the statistical 34 distribution of pore sizes. A broader pore-size distribution increases local differences in capil-35 lary thresholds, thus overcoming the viscous pressure drop for longer ranges, and maintaining 36 CF patterns for higher flow rates [29, 26]. High disorder also leads to a larger interfacial area 37 between the fluids during both drainage and weak imbibition, with more trapping of the defend-38 ing fluid [24]. In other words, disorder works to stabilize the invasion front. Even for unstable 39 viscosity ratio $\mathcal{M} < 1$, changing the pore geometry, for example by introducing a gradient in 40 pore size, can stabilize the displacement front [30, 31]. 41

An important feature of the microstructure of many types of porous media such as soils and rocks is the existence of spatial correlations in pore sizes, such as when pores of similar size are clustered together, creating distinct regions with different hydraulic properties. The impact of these correlations on drainage patterns has been studied mainly in the context of quasistatic displacement, where it was shown to cause a smoother displacement front [32, 9]. In

addition, long-range correlations lower the percolation threshold [33] and the saturation of the 47 invading phase at breakthrough [32], decrease the residual saturation thus altering the pressure-48 saturation relationship [34, 9], and increase the relative permeability of both the wetting and non-49 wetting phases [35]. Furthermore, we recently demonstrated the impact of spatial correlations 50 on drying—a fluid displacement process driven by the evaporation of the defending liquid– 51 showing that pore-size correlations lead to the preferential invasion of connected regions of large 52 pores, and a prolonged high-drying-rate period [14], with more pronounced and intermittent 53 pressure fluctuations [36]. While these studies shed important light on correlation effects at the 54 quasi-static limit, their interplay with rates, namely dynamic (or viscous) effects, have not yet 55 been considered. 56

Here, we systematically study the impact of spatial correlations in the particle (and hence pore) sizes on fluid displacement, using pore-scale simulations combined with state-of-the-art microfluidic experiments. We show that increasing the correlation length (the characteristic size of patches of particles with similar sizes) leads to more preferential invasion, reduced trapping, a smoother fluid-fluid interfacial area and reduced sweep efficiency. We also show that these effects diminish at high flow rates, when viscous forces become dominant.

63 2. Methods

The complexity of flows in natural porous materials, such as soils and rocks, makes under-64 standing their underlying physics a challenging task. Thus, we consider-experimentally and 65 numerically-an analog porous medium with a simplified geometry: an array of solid, cylindri-66 cal pillars on a triangular lattice, where heterogeneity is provided by variations in the pillar radii 67 (Fig. 1). Specifically, we investigate the radial invasion patterns of fluids flowing into circular 68 patches of such pillars, in order to simplify the pattern characterization. However, we note that 69 our methodologies could allow for a wide variety of designs, for instance other ordered lattices 70 [28] or random pillar arrangements. 71

Our simulations are based on the model of Holtzman and Segre [21], and are compared with microfluidic experiments of similar pore geometry. The model provides a mechanistic description of partially-wetting fluid-fluid displacement, and represents the basic interplay between capillary and viscous forces, invasion dynamics and wettability. It is also computationally efficient, allowing us to rapidly conduct many realizations in a large domain size. The experiments provide pore-scale observations of exceptional resolution, which enable us to verify our modeling results and provide better insight on the pore-scale physics.

79 2.1. Pore-scale model

Here we describe our numerical model, as sketched in Fig. 1(a-e); for further details see 80 Holtzman and Segre [21]. The model is a hybridization of two complementary pore-scale mod-81 eling approaches: pore-based and grain-based. Pore-network models resolve pore pressures and 82 interpore fluxes from pore topology and geometry [37], while grain-based models incorporate 83 the different pore filling mechanisms that arise due to wettability effects, by linking the meniscus 84 geometry to the local capillary pressure, grain size and contact angle [38]. An advantage of our 85 model is its ability to capture the impact of flow dynamics (in particular, fluid viscosity effects 86 and meniscus readjustments, as in Furuberg et al. [39]), along with the impact of partial wetta-87 bility on pore-scale displacement mechanisms [21]. The model does not include the effects of 88 additional mechanisms such as droplet fragmentation, snapoff, or film flow. The simulations are 89 done in MATLAB®. 90



Figure 1: Our porous medium is made of variably-sized cylindrical pillars placed on a triangular lattice. (a) Numerically, we track the fluid-fluid interface (black line) and fluid pressures (increasing from blue to red) during immiscible fluid invasion. (b) A close-up view shows the lattice (of spacing *a*) of particles (of variable diameter *d*) and the pores interconnected by throats (of width *w*). The fluid-fluid interface is represented as a sequence of circular menisci, touching particles at contact angle θ , with radii of curvature *R* set by the local capillary pressure. Menisci can be destabilized by: (c) burst, (d) touch, or (e) overlap. In each sketch the brown arrows indicate the direction of advancement of the meniscus, and destabilized menisci are represented by dashed arcs (Reproduced from [21]; Copyright 2015 by the American Physical Society). (f) Experimental microfluidic cell design, showing a central air injection site, and a peripheral boundary zone connected to the liquid outlet ports. A close-up view shows the variation in the solid particles (pillars).

The basic status of each pore is determined by its fluid content, Φ , where $\Phi = 0$ or 1 for 91 a pore which is completely filled by the defending or invading fluid, respectively. The invasion 92 front is defined by the interface separating fully invaded pores, where $\Phi = 1$, from accessible 93 non-invaded ($\phi = 0$) or partially invaded ($0 < \phi < 1$) pores. A pore is considered accessible 94 if it is topologically connected through the defending fluid to the outer boundary; as a result, 95 the volume of the trapped clusters of the defending fluid is fixed, and they cannot be invaded 96 or refilled in our simulations. Note also that with this, we do not consider connectivity of the 97 wetting fluid through films. 98

Along the invasion front the fluid-fluid interface is approximated by a sequence of menisci, shaped as circular arcs. Each arc intersects a pair of particles at the prescribed contact angle θ and has a curvature

$$\kappa = 1/R = \Delta p/\sigma,\tag{1}$$

where R is the radius of curvature of the meniscus, and Δp is the capillary pressure (the pressure 102 jump across the meniscus), computed from the Young-Laplace law. We consider a cell filled 103 with pillars whose height, h, is large compared to the throat aperture w, such that $h \gg w$. Thus, 104 the hydrostatic pressure differences in the liquid associated with gravity are negligible compared 105 to the pressure differences associated with capillarity, which allows us to use a two-dimensional 106 model neglecting gravity effects. The angle θ is measured through the defending fluid (i.e. θ < 107 90° for drainage), and represents an *effective* advancing contact angle, including any dynamic 108 effects [40, 41]. Knowledge of R and θ allows us to analytically resolve the geometry, and 109 hence stability, of each meniscus. Specifically, the menisci are tested for three types of capillary 110 instabilities [38], as sketched in Fig. 1(c-e): (1) a Haines jump or burst, when the curvature 111 κ exceeds a threshold set by the local geometry; (2) touch, when a meniscus makes contact 112

with a downstream particle; and (3) the *overlap* of adjacent menisci, intersecting and hence destabilizing each other.

An unstable meniscus is allowed to advance into its downstream pore, at a rate which depends on the viscous dissipation due to its surrounding pore structure (the hydraulic resistance of the constriction). Here, fluid pressures are evaluated by simultaneously resolving the flow between all pores containing the same phase, and through any throat with an advancing meniscus. We also solve for the flow of both the invading and the defending fluids, at the same time. Mathematically this is done by assuming incompressible flow and enforcing in each pore the conservation of mass,

$$\Sigma_j q_{ij} = 0, \tag{2}$$

by summing the fluxes q_{ij} into pore *i* from all connected pores *j*. This provides a system of linear equations that is solved explicitly at each time step. The volumetric flow rate between neighboring pores is evaluated by

$$q_{ij} = C_{ij} \nabla p_{ij}, \tag{3}$$

where $C_{ij} \sim w_{ij}^4 / \mu_{eff}$ is the conductance of the connecting throat. To simplify the calculation of 125 q_{ij} , we consider the throats as cylindrical tubes, and C_{ij} can be derived directly from the Hagen-126 Poiseuille equation. The effective viscosity $\mu_{eff} = (\mu_i - \mu_d) \Phi + \mu_d$, where μ_i and μ_d are the 127 viscosities of the invading and defending phases, respectively. This provides the flow rate q_{ii} be-128 tween pores containing the same fluid as well as the meniscus advancement rate in partially-filled 129 pores, in which the meniscus is unstable. Note that in pores with stable menisci, we ignore the 130 small volume changes associated with meniscus curvature variations (due to changes in capillary 131 pressure). The local pressure gradient, $\nabla p_{ij} = (p_j - p_i)/\Delta x_{ij}$, is evaluated from the pressure 132 difference between the two neighboring pores. If these pores contain different fluids, the pres-133 sure difference is simply the capillary pressure. In this calculation we rely on the assumption 134 that most of the resistance to flow occurs in the narrow constriction between two pores (i.e., the 135 throat), therefore $\Delta x_{ii} = w_{ii}$. 136

To track the progression of the fluid invasion, at each time step we: (1) locate the position of the invasion front from the filling status Φ and define the connected networks of pores within both fluids; (2) evaluate the pressure *p* in each pore, and calculate the flow rate *q* for each throat; (3) check for new meniscus instabilities and update the flow network accordingly; and (4) update the filling status of each invaded pore by $\Phi(t + \Delta t) = \Phi(t) + q^{inv}(t) \Delta t/V$, where q^{inv} is the inflow of invading fluid, and *V* is the pore volume.

We enforce a constant injection rate by setting the hydraulic resistance of an 'inlet' region-143 a circle with a diameter of about 12 pores, surrounding the centre of the cell-to be orders of 144 magnitude larger than elsewhere. This allows us to use Dirichlet boundary conditions of fixed 145 pressure at the inlet and at the ring of outermost (outlet) pores, hence keeping a fixed pressure 146 drop between the inlet and the outlet. This ensures a practically constant pressure gradient that is 147 maintained throughout the simulation, regardless of the front position, and a nearly constant flux 148 of fluid into the sample. Simulations are terminated by the breakthrough of the invading fluid, 149 i.e. once any pore on the outer boundary is invaded. 150

The time-step Δt is chosen so that only a small fraction of a pore (not more than 30% of any invaded pore) may be filled by the invading fluid, in each step. When a pore invasion ends (i.e. when $\Phi = 1$) the interface configuration is updated by replacing any unstable menisci with new ones that touch the particles upstream from the newly invaded pore. The finite pore filling time in our model, while allowing pores which are partially-filled to re-empty if the direction of meniscus advancement is reversed, enables our model to capture dynamic (viscous) effects, overcoming a long-standing computational challenge [42, 37]. These effects include pressure
 screening [43] and interface readjustments: the non-local decrease in menisci curvature following
 a pore invasion, due to the redistribution of the defending fluid [39, 44].

¹⁶⁰ 2.2. Sample geometry and simulation parameters

Our sample geometry is a circular cell of diameter L = 120a, containing cylindrical pillars on 161 a traingular lattice, where $a = 45 \,\mu\text{m}$ is the lattice length (the distance between the centers of two 162 adjacent pillars). The pillars, as well as the cell, have a height of $h = 65 \ \mu m$. Their diameters d 163 have a mean size $d = 25 \,\mu\text{m}$ and standard deviation $\sigma_d = 5 \,\mu\text{m}$, arranged in a spatially correlated 164 pattern (see below). The values of d are limited to the range $[d(1 - \lambda), d(1 + \lambda)]$, where $\lambda = 0.8$; 165 this constraint prohibits blocked throats due to particle overlaps. A pore is defined as the open 166 volume between a set of three adjacent pillar centers, and a throat is defined as the constriction 167 between two adjacent pillars. The throat apertures thus have a mean size of $\overline{w} = 20 \,\mu\text{m}$, and the 168 pore volumes are related to their surrounding pillar and throat sizes. 169

To introduce spatial correlations in pillar sizes, we generate a random rough surface H(x, y)170 such that its Fourier transform is a Gaussian distribution of intensities, centered around zero, 171 with random phases. This is prepared by summing 10^4 sinusoidal waves, whose amplitude, 172 phase and orientation are selected from random uniform distributions, and whose wave numbers 173 were drawn from a normal distribution. The width of this distribution, in the Fourier domain, is 174 inversely proportional to the correlation length ζ of the surface (in units of the lattice length). For 175 a review of the methods to generate such rough surfaces see Persson et al. [45]. The diameter of 176 each pillar is now defined such that $d_i = d(1+H_i)$, where H_i is the height of the correlated surface 177 at a specific pillar coordinate (x_i, y_i) . To obtain statistically-representative results from the simu-178 lations, averages and deviations for various metrics of the displacement patterns were computed 179 from an ensemble of 10 realizations (namely, samples with the same statistical attributes but with 180 different random seeds), for each $\zeta \in \{1, 2, 3.5, 5, 10\}$. Imposing spatial correlations in *particle* 181 sizes results in spatially-correlated *pore* sizes (see Fig. S1 in the Supplementary Material). 182

We vary the Ca in the simulations by varying the inlet pressure. The average flow rate is 183 calculated as $Q = V_{tot}/t_{tot}$, with V_{tot} and t_{tot} being the total displaced volume and time at break-184 through, respectively. This then provides a characteristic velocity of $v = Q/A_{out}$, where A_{out} 185 is the cross-sectional area of the cell's outer perimeter, which is open to flow (i.e. the sum of 186 cross-sectional area of pore throats on the perimeter). Other parameters used in the simulations 187 are the interfacial tension $\sigma = 71.67 \times 10^{-3}$ N/m, and the viscosities of the invading and defend-188 ing fluids, $\mu_i = 1.8 \times 10^{-5}$ Pa s and $\mu_d = 1 \times 10^{-3}$ Pa s, respectively. These values model the 189 displacement of water by air. Finally, the contact angle in the simulations was set to $\theta = 73^{\circ}$, to 190 match the experimental conditions (see following section). 191

¹⁹² 2.3. Microfluidic displacement experiments

Microfluidic micromodels are produced using soft lithography techniques as detailed further 193 by Madou [46] and Fantinel et al. [28]. We use a high-resolution chrome-quartz photomask and 194 a negative photosresist (SU8 3025) to manufacture reusable templates. Poly(dimethylsiloxane) 195 (PDMS) is poured over these master templates, degassed under vacuum, and cured for 1 h at 196 75°C. The PDMS covering a designed pattern is then cut and peeled off the master, and in-197 let/outlet holes punched. This patterned slab, and a PDMS-coated glass slide, are primed in an 198 oxygen plasma and adhered to one another, forming a microfluidic chip of solid pillars separated 199 200 by open channels with a thickness of 65 μ m \pm 3 μ m. An example design is shown in Fig. 1(f).

The experiments use a similar geometry to the numerical simulations, but are scaled slightly as a result of practical considerations. The lattice length in the experimental cells is $a = 130 \,\mu$ m, the pillar mean diameter $\overline{d} = 80 \,\mu$ m and the pillar size disorder is given by $\lambda = 0.5$, with spatial correlation lengths of $\zeta \in \{1, 2, 3.5, 5, 10\}$. These values allow for a minimum throat width of 10 μ m, which ensures for the reliable fabrication of the prepared designs, while maintaining a high degree of size heterogeneity. By observing the cells under a microscope, we estimate an uncertainty in pillar diameter of ~1.0 μ m (i.e. the pillar is within ~1.25% of the designed size).

PTFE tubes (Adtech Polymer Engineering Ltd) are inserted into the inlet and outlets, and 208 are sealed in place with a UV-curing adhesive (AA 3526, Loctite). A water/glycerol mixture is 209 then pumped through the central inlet to fill the cell. Any trapped air bubbles disappear after a 210 few minutes, leaving the cell saturated with liquid. The cell is then mounted horizontally under 211 a digital camera (Nikon D5100) with the glass slide facing upwards. The entire apparatus is 212 housed in a darkened box, with a low-angle LED strip surrounding the cell to highlight interfacial 213 features. A syringe pump then withdraws liquid out of the cell through the outlet ports on its 214 perimeter, allowing air to invade via the central inlet (see Fig. 1f). Time-lapse images are taken 215 every second until the liquid-air interface reaches breakthrough. The syringe pump withdrawal 216 rate is fixed at $Q = 1.30 \times 10^{-10}$ m³/s, and Ca is varied by changing the composition (and hence 217 viscosity) of the water/glycerol mixture to give Ca values of 1.9×10^{-6} , 3.2×10^{-6} , 1.3×10^{-5} and 218 3.7×10^{-5} . Overall, 24 experiments were performed with various Ca and ζ . The receding contact 219 angle between the water/glycerol mixtures and PDMS was measured as $73^{\circ} \pm 8^{\circ}$ using a drop 220 shape analyzer (DSA-10, Krüss Scientific). 221

A summary of the image analysis process applied to the microfluidic experiments is provided in the Supplementary Material and Fig. S3.

224 3. Results

We find that at low to intermediate capillary numbers Ca (i.e. slow, low viscosity flows), increasing the correlation length of the disorder promotes preferential fluid displacement patterns. Less of the defending fluid is flushed out before breakthrough, but also less volume is trapped behind the invasion front. Essentially, invasion is forced to occur through connected patches of large pores, following the path of least resistance. At high Ca, fluid displacement is instead controlled by viscous dissipation rather than capillary forces, and the impact of the spatial correlation on the invasion patterns is less apparent.

232 3.1. Displacement patterns

Characteristic displacement patterns, both simulated and experimental, are presented in Fig. 2. 233 For the simulations, we show results at various flow rates (i.e. Ca) for one specific realization 234 (sample geometry) of each correlation length ζ . For slow flows (Ca $\leq 1 \times 10^{-4}$), invasion is 235 mostly controlled by the capillary invasion thresholds, determined directly from the sizes of the 236 pore throats throughout the sample. At intermediate rates (Ca = 2×10^{-4} and 5×10^{-4}), fingers 237 of the invading fluid become more apparent, especially for lower ζ , as a result of the stronger vis-238 cous effects [23]. Up to these rates, increasing ζ forces the displacement pattern to more closely 239 follow the underlying pore geometry, invading mostly the patches of smallest pillars (hence, the 240 largest pores). Such similarities between the invasion patterns and maps of the particle sizes are 241 evident in Fig. 2, for example. Increasing ζ also leads to a small increase in the occurrence of 242 243 cooperative pore invasion events, resulting in a smoother interface.



Figure 2: Displacement patterns at breakthrough in samples of various correlation lengths ζ and at different values of the capillary number Ca. Increasing ζ increases the size of regions or patches of similarly-sized pillars (e.g. a patch with larger openings and hence lower capillary thresholds and flow resistance), promoting preferential invasion through these regions, and resulting in patterns which follow more closely the underlying pore geometry. The left-most column shows images of experiments at Ca= 1.3×10^{-5} , where invading fluid (air) appears brighter. The remaining results are from simulations, including representative maps of the relative pillar sizes for each ζ . Here, the invading and defending fluids appear in black and white, respectively, while the solid pillars are not shown. The perimeter of the porous medium is denoted by a blue circle. The same sample geometry, i.e. the set of *relative* pillar sizes, is used for all displacement patterns shown in each row.

The impact of ζ is relatively limited at high Ca, where viscous fingering patterns inevitably 244 emerge, as pressure screening inhibits invasion behind the most advanced edge of the displace-245 ment front [43]. Nevertheless, increasing ζ reduces the number of invading fluid fingers, and 246 lowers the displaced volume at breakthrough. In many ways these invasion patterns resemble a 247 skeleton or backbone of their low-rate analogues, showing that regions of large or small pores 248 remain preferred locations for guiding or inhibiting the invading fingers, respectively. Thus, their 249 number is limited compared to the less correlated samples, in which fingers propagate equally 250 freely in all directions. 251

The microfluidic experiments (Fig. 2, left-most column) confirm our main findings from the simulations, at low Ca. Here, increasing ζ also leads to smoother and more preferential patterns, with reduced trapping of the defending liquid, and lower displaced volume at breakthrough.

255 3.2. Interfacial features

Two prominent characteristics of fluid displacement patterns are the extensive interface between the invading and defending fluids, and the invading fluid's fingers [43]. The interfacial area between the fluids is related to the pressure-saturation relationship [47, 48], and can control the rates of fluid mixing and chemical reactions [49]. Here, we characterise it by A_{inter}^* , which is the ratio of the total interfacial area (including trapped clusters) to the invaded volume, at breakthrough. As shown in Fig. 3a, this relative area consistently decreases as the correlation length is increased, for all flow rates. The largest effect is observed at low flow rates, reflecting a transition from capillary fingering at low ζ to smoother displacement patterns at high ζ . In contrast, the increase in A_{inter}^* with Ca results from the transition towards viscosity-dominated patterns [22, 24].

Another characteristic highlighting the transition from capillary to viscosity-controlled displacement is the increase in the relative *front* area A_{front}^* with Ca; here A_{front}^* is defined as the ratio of the total front area (excluding trapped clusters, cf. Fig. 3c) to the invaded volume, at breakthrough. This behavior occurs in a similar manner across all ζ values, as the increase in pore-size correlation brings the competing contributions of two phenomena—reduction in the invaded volume, and in the interface roughness (see Fig. S2 in the Supplementary Material).



Figure 3: Increasing the correlation length of the particle sizes ζ reduces the relative interfacial area A_{inter}^* and increases the invading finger width W. (a) A_{inter}^* is lower for larger ζ , as displacement patterns become smoother in response to longer-range correlations, and increases with the capillary number Ca, as viscous forces become dominant. (b) The finger width increases with ζ , and decreases with Ca. For each ζ we plot the ensemble average (lines) and the standard error (shading) of 10 independent realizations. (c) We distinguish between the front area (marked in red)—the leading part of the interface only, excluding trapped clusters (green)—and the interfacial area, which is the sum of the front area and the perimeter of the trapped clusters. The effect of front area is shown in the online Supplementary Material (Fig. S2). Here the invading fluid is shown in black, and the cell perimeter in blue.

As shown in Fig. 3b, we find that the mean finger width, W, is generally higher for larger ζ . 272 This reflects the increasing size of the contiguous regions of large pores, through which the inva-273 sion proceeds at low Ca, when capillarity is dominant. At sufficiently high Ca, viscous screening 274 leads to the emergence of thin fingers, and minimizes the impact of the underlying porous mi-275 crostructure (i.e. ζ). Here, W converges to a value similar to that found in simulations of invasion 276 into uncorrelated porous media [24], further exemplifying the reduced effect of microstructure, 277 and specifically of correlations, at higher flow rates. The width of an invading finger of fluid is 278 measured here by averaging the widths of the shortest paths across the finger at each point along 279 its interface (see skeleton-based algorithm in Holtzman [24]). 280

281 3.3. Preferential displacement and invasion selectivity

We now turn to quantify the impact of correlations on how selective and preferential the invasion is. We consider the invasion to be "selective" if it samples only a narrow range of the available pore sizes, as opposed to more randomly invading pores across the entire size distribution. Similarly, we use the term "preferential" to describe a displacement advancing through distinct pathways or channels, rather than in a uniform radial front (i.e. certain routes are *preferred*). Selective invasion can result in preferential patterns, which is the case here for larger ζ : by selectively invading through the connected regions of larger pores, the invading fluid propagates in more preferential patterns.



Figure 4: Spatial correlation leads to more selective, preferential and asymmetric displacement. (a) At larger ζ the invasion is able to *select* for a higher mean invaded throat width $\overline{w_{inv}}/\overline{w}$. (b) This allows for a more *preferential* route of the displacement front to breakthrough, and the mean radius of the displacement front, R_f , decreases with both increasing correlation length ζ and capillary number Ca. (c) Similarly, the displacement front width, given by the standard deviation of the front position, σ_f , increases with both ζ and Ca. (d) Additionally, displacement patterns become less *symmetric* with increasing ζ , as quantified here by the rescaled acylindricity β^* , which is zero for a circular pattern. For each ζ we plot the ensemble average (lines) and standard error (shading) of 10 realizations. Example displacement patterns for $\zeta=1$ (e) and $\zeta = 10$ (f), at Ca = 1×10^{-4} , illustrate the definitions of the mean front radius R_f (dark green circle) and width σ_f (green shading). For $\zeta=1$ the displacement front is further from the injection point on average (large R_f), while the front positions are more narrowly spread out (small σ_f), than for $\zeta=10$.

A selective invasion pattern will tend to favor the largest, easiest-to-invade pore throats. As 290 we show in Fig. 4, the mean width of the invaded throats (normalized by the mean throat width, 291 i.e. $\overline{w_{inv}}/\overline{w}$ increases with ζ for all flow rates, indicating that the correlations result in a more 292 selective invasion. The impact of the capillary number is less clear; while the selectivity does 293 also increase with Ca, it saturates for faster flows, where viscous forces dominate, and may 294 even decrease at the highest Ca studied. As discussed in Section 3.1, viscous fingers at high 295 flow rates will still grow more readily into correlated regions of larger throats, and be inhibited 296 by tighter pores. Once any finger falls behind the main front, pressure screening will further 297 limit its advance. Thus, although finger propagation depends more on the viscous resistance 298 to flow—a nonlocal feature, as opposed to the local capillary resistance—an interplay between 299

these two resistance terms at the leading edge of the invasion front promotes selective invasion 300 of the largest pores. Increasing ζ also promotes more preferential fluid displacement into the 301 connected clusters of larger pores. We characterize this with a series of metrics that describe 302 whether the invasion front is smooth and symmetric (less preferential), or rough and asymmetric 303 (more preferential). For example, the average radius of the displacement front at breakthrough 304 decreases with increasing ζ , as shown in Fig. 4b. A high value of $R_{\rm f}$ (the mean front radius, 305 scaled by the system size — see Fig. 4e,f) indicates that the front has more evenly approached 306 the perimeter in all directions. Hence, a decrease in $R_{\rm f}$ shows that most of the displacement 307 occurred through a smaller part of the cell, e.g. through fewer fingers. Another indication of the 308 more preferential invasion at higher ζ is the increase in front width $\sigma_{\rm f}$ —the standard deviation of 309 the front location around $R_{\rm f}$ [50]—as presented in Fig. 4c. The gradual transition from capillary 310 fingering to viscous fingering, between intermediate and high Ca, results in an increase of $\sigma_{\rm f}$ (i.e. 311 a wider front, which is more pronounced for smaller ζ) and a decrease of $R_{\rm f}$. 312

Another consequence of the more preferential and selective invasion with increasing ζ , is that 313 the patterns also become less symmetric. This is quantified by the pattern acylindricity, β^* , which 314 is calculated from the second moments of a best-fit ellipse to the invaded area [51]. Briefly, for 315 a perfectly circular invasion pattern, $\beta^* = 0$, whereas for a single needle-like growth along one 316 direction, $\beta^* = 1/3$ (for details of the calculation, see Appendix A). The highest values of β^* are 317 obtained for low-to-intermediate Ca and high ζ , when capillary forces dominate pore invasion, 318 and the underlying heterogeneity has the greatest impact (Fig. 4d). In brief, we have shown here 319 that increasing ζ results in more selective fluid invasion, which leads to preferential displacement 320 patterns; these are characterized by lower front radius, higher front width, and lower symmetry. 321

322 3.4. Displacement efficiency

The sweep efficiency is one of the most important aspects of fluid displacement, from a practical standpoint, as it determines the ability to produce or withdraw fluids in applications such as oil production or groundwater remediation [52, 53]. A typical measure of sweep efficiency is the invading fluid saturation at breakthrough, *S*. Increasing ζ forces the displacement into fewer, more preferential pathways, and thus reduces *S* (Fig. 5a). Due to the narrow, extended nature of viscous fingering, their emergence at high Ca also reduces significantly *S*, more sharply at lower ζ .

The displacement efficiency is related to (and affected by) trapping—the isolation of defend-330 ing fluid behind the displacement front in immobile, disconnected patches. The trapped fraction 331 χ_{trap} depends in a complex manner on both the sample geometry and flow rate, leading to a non-332 monotonic dependence on Ca for most ζ values (Fig. 5b). Here, χ_{trap} is defined as the volumetric 333 ratio of the trapped defending fluid to the total injected fluid, at breakthrough. The non-trivial 334 response of χ_{trap} reflects a transition between three distinct trapping modes [24]: (i) For low Ca, 335 the invading fluid efficiently fills the pore space, and trapping is limited (see case in Fig. 5c); 336 (ii) at intermediate Ca, capillary fingering patterns emerge, which trap multiple small islands 337 of defending fluid ("capillary trapping", Fig. 5d); (iii) at high Ca, viscous fingering becomes 338 more dominant and trapping occurs in fewer, but larger, volumes in between distinct fingers 339 (here called "viscous trapping", Fig. 5e). In the transition between capillary and viscous finger-340 ing (between intermediate and high Ca), trapping first decreases as capillary trapping becomes 341 less efficient, and then rises again due to viscous trapping. For the shorter-range correlations, 342 the highest flow rates are characterized by more emerging invading-fluid fingers, compared to 343 intermediate flow rates (see Fig 2). In these cases the higher number of fingers leads to more 344



Figure 5: Effects of correlated heterogeneity on fluid displacement efficiency and trapping. (a) The sweep efficiency i.e. the breakthrough saturation S of the invading phase—is reduced for longer-range correlations, due to the preferential invasion of larger pores. The effect of ζ is less apparent at high Ca, where viscous fingering is responsible for low efficiency. (b) The fraction of trapped defending liquid, χ_{trap} , is higher for shorter-range correlations, at most Ca values. Increasing ζ suppresses trapping under capillary-controlled invasion, as demonstrated by comparing displacement patterns for $\zeta = 10$, Ca = 1×10^{-4} (c) and $\zeta = 1$, Ca = 1×10^{-4} (d). The increase in trapped liquid (blue regions) with Ca at viscous-dominated regime (high Ca) is related to trapping *between* viscous-controlled invading fingers (see panel e, for $\zeta = 1$, Ca = 2×10^{-3}). For each ζ we plot the ensemble average (lines) and standard error (shading) of 10 realizations.

coalescence, and hence more trapping of the defending fluid, as compared to the simulations
 with long-range correlations.

We note that for the sample geometries and flow rates considered here, trapping is not the primary control on displacement efficiency. This is mostly evident at high ζ and low Ca, where the displacement occurs through few distinct regions; while these regions are essentially contiguous, with a few small trapped islands, the preferential nature of the invasion pattern only allows it to explore a smaller section of the porous medium (compared to low ζ) with a much lower overall efficiency.

353 3.5. Comparing experiments and simulations

We used microfluidic experiments to validate our simulations. As was shown in Fig. 2, the 354 impact of the correlation length ζ on the resulting displacement patterns is similar in experi-355 ments and simulations, for the low Ca that are accessible experimentally. Here, and in Fig. 6, 356 we demonstrate how this agreement extends to a quantitative comparison of the following met-357 rics: the interfacial area, A_{inter}^* , trapped fraction, χ_{trap} , sweep efficiency, S and the dimensionless 358 acylindricity, β^* . These metrics are important for flow and transport, and can be reliably and con-359 sistently measured from the experimental images. As shown in Fig. 6, most metrics show similar 360 magnitudes and trends in the experiments and simulations, with two minor exceptions. First, 361 while we find similar values of A_{inter}^* for experiments and simulations for $\zeta = 10$, the decrease in 362



Figure 6: Our microfluidic experiments, conducted at lower Ca, compare favorably with the simulations, in terms of trends as well as values of the following metrics: (a) the interfacial area A_{inter}^* , (b) trapping fraction χ_{trap} , (c) sweep efficiency *S*, and (d) rescaled acylindricity β^* . We note that the simulations slightly overpredict A_{inter}^* (a) and *S* (c). Lines and shading represent averages and standard deviations, respectively, of 3–7 experimental realizations for each ζ (blue, at Ca between 2×10^{-6} and 4×10^{-5}) and 10 numerical realizations at each ζ (red, at Ca = 5×10^{-5}).

 A_{inter}^* with ζ is apparent in the simulations alone (Fig. 6a). The second small discrepancy is the consistently lower S in the experiments vs. the simulations (Fig. 6c).

In calculating the ensemble averages and standard deviation for each ζ in Fig. 6, we average 365 over all experiments in the range of the tested Ca values. The motivation behind this is to increase 366 the number of experimental data values for each ζ , improving the statistical significance of our 367 analysis. This is justified by the small expected effect of Ca in the quasi-static limit (low Ca) 368 where viscous effects are negligible [7]; results from all experiments are individually presented 369 in in the online Supplementary Material (Fig. S4), and confirm this assumption. While our 370 current experimental setup limited us to low Ca, we note that the impact of correlation is most 371 significant at these Ca values, according to our simulations (Figs. 3-5). The close agreement in 372 this limit thus adds particular strength to these results. 373

374 **4. Discussion**

375 4.1. Implications for viscous flow and solute transport

The impact of spatial correlation on fluid displacement patterns, exposed in this study, implies that correlations can strongly influence additional aspects such as flow rates, solute transport and reaction rates. The selective invasion of larger pores is characteristic of better correlated porous media (Fig. 4), and the resulting preferential displacement patterns increase the relative permeability of the invading phase (at a given saturation), as compared with uncorrelated media [34].
This effect is due to the control exerted on relative permeability by the fluids' spatial distribution
and connectivity, changing, for instance, the constitutive relationship between relative permeability and saturation or capillary pressure [34, 1]. This is in line with previous observations of
the effect of pore-size disorder (in uncorrelated samples) on fluid displacement patterns [24] and
its impact on relative permeability [54].

Since solute transport is largely controlled by fluid flow, correlations in the microstructure 386 can also lead to preferential solute transport pathways and localized reaction hotspots. A similar 387 link between flow focusing and transport has been recently shown for uncorrelated heterogeneity 388 [17], and it is to be expected that correlations would intensify this impact. Specifically, our 389 findings of the suppressive effect of pore-size correlations on the creation of fluid-fluid interfacial 390 area (Fig. 3) suggest a consequent effect on solute concentration gradients, solute mixing, and 391 reaction rates [49, 55] between the solutes carried by the invading fluid and those resident in 392 the defending fluid. For instance, in light of the positive effect of viscous fingering on fluid 393 mixing and reaction rates [56, 57, 58], we expect that increasing correlations—by delaying the 394 transition to viscous fingering—would reduce the mixing rate (at a given flow rate). Transport 395 heterogeneity, associated with differences in flow velocities between regions with high and low 396 conductivity, was also shown to influence solute dispersion [59, 60], again suggesting a link 397 between pore-size correlations-and their effect on fluid transport-and solute transport. 398

Finally, the relationship between flow intermittency and pressure fluctuations during immiscible displacement was recently demonstrated in drainage experiments in uncorrelated porous media [61], and in drying experiments and simulations in correlated media [36]. The latter study also shows how increasing the correlation length leads to larger avalanches, as larger patches of similarly-sized pores become accessible per an increase in capillary pressure; this is consistent with our interpretation of increasing invasion selectivity.

405 4.2. Environmental relevance of structural heterogeneity

The effect of spatial correlations on fluid displacement, forcing it to become more prefer-406 ential, has implications for a variety of environmental processes at various length scales. For 407 example, it has been shown that structural heterogeneity can impact water infiltration in soils and 408 the emergence of preferential flow [12], the development of unsaturated zones at the river-aquifer 409 interface [62], and the distribution of saline and fresh water within the continental shelf [16]. The 410 occurrence of structural heterogeneity, in the form of high permeability zones within aquitards, 411 can also compromise their ability to act as barriers for water and contaminant migration [63]. In 412 addition, the contrast in permeability between different geological layers may control the mech-413 anisms for attenuation of CO_2 , when considering leakage from an underground reservoir used 414 for carbon capture and storage [64, 65, 66]. These studies show the importance of considering 415 the structural heterogeneity of porous materials, due to their impact on flow rates and fluid phase 416 distribution. While upscaling pore-scale results to core or field scale remains a significant chal-417 lenge [67], pore-scale studies such as the one presented here serve as important building blocks 418 for simulations of environmental phenomena at regional scales (e.g. [68]). 419

420 5. Summary and conclusions

We have presented a systematic investigation of the impact of correlated heterogeneity on fluid displacement patterns, and its interplay with flow rates, in partially-wettable porous media,

by combining pore-scale simulations with high-resolution microfluidic experiments. We find that 423 at low-to-intermediate flow rates (i.e. low or moderate Ca values, where capillarity dominates 424 pore invasion) increasing the correlation length results in a lower sweep efficiency, reduced trap-425 ping of the defending fluid and lower interfacial area, with displacement patterns that are more 426 preferential, and follow more closely the underlying pore geometry. These patterns are further 427 characterized by wider invading fingers and lower symmetry. At higher Ca, when viscosity dom-428 inates, we find that the impact of correlation becomes relatively limited, although the pattern 429 symmetry and trapped fraction are still lower than for uncorrelated porous media. 430

Our results highlight the importance of the dynamic pore-scale modeling of multi-phase flow 431 in porous media, which allows one to capture complex behavior that cannot be described by 432 quasi-static models [32, 69], and which might otherwise completely evade coarse-grained, con-433 tinuum models [1]. The spatial distribution of pore sizes and their connectivity affects the water 434 distribution in the subsurface [12, 62], transport, mixing and reaction of contaminants and nutri-435 ents [49, 70, 60], and fluid displacement patterns in engineered porous materials [30, 31]. These 436 are merely a few examples of applications in which structural heterogeneity plays a key role in 437 fluid and solute transport across scales, emphasizing the need for models that properly incorpo-438 rate pore-scale heterogeneity. 439

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445 Appendix A. Acylindricity and the gyration tensor

The acylindricity β measures the divergence of a pattern from a circular shape, and is the difference between the eigenvalues *T* of the gyration tensor:

$$\beta = |T_1 - T_2|. \tag{A.1}$$

These eigenvalues give the squares of the lengths of the principal axes of the ellipse which best approximates the shape of the displacement pattern [51]. We thus use the radius of the cell, L/2, as a scale to give a dimensionless acylindricity of $\beta^* = 4\beta/L^2$, which is 0 for a circular invasion pattern, and 1/3 for the extreme case of invasion proceeding along a straight line from the inlet to the outer perimeter. The gyration tensor *S* is itself computed from the locations of the invaded pores, with respect to the inlet (the center of the cell),

$$S = \frac{1}{N} \sum_{i=1}^{N} \begin{pmatrix} x_i^2 & x_i y_i \\ y_i x_i & y_i^2 \end{pmatrix},$$
 (A.2)

where x and y are the spatial coordinates, such that x = 0 and y = 0 at the inlet, and *i* runs over all N invaded pores.

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