

1 ABSTRACT

2 **Introduction**

3 Ankle-foot and knee components are important determinants of mobility for individuals
4 with transfemoral amputation. Individually, advanced ankle-foot and knee components have
5 been shown to benefit mobility in this group of people. However, it is not clear what affect a
6 variety of combinations of ankle-foot and knee components have on mobility test performance.

7

8 **Methods**

9 Nine adults with unilateral transfemoral amputation completed the Two-minute walk
10 test (2MWT), the Timed up-and-go test (TUG), the L-test and a custom locomotion course
11 (Loco) in four randomised prosthetic conditions. These conditions were each a combination of
12 an ankle-foot component (rigid, non-articulating; RIG or a hydraulically articulating; HYD)
13 and a knee component (non-microprocessor-controlled; NMPK or a microprocessor-controlled;
14 MPK). The test-retest reliability and concurrent validity of the custom locomotion course was
15 also established.

16

17 **Results**

18 The best performance in all mobility tests was associated with the MPK+HYD
19 combination, followed by the MPK+RIG, NMPK+HYD and NMPK+RIG combinations. This
20 effect was statistically significant for the Two-minute walk test ($p=0.01$, $\eta_p^2 = 0.36$) and on
21 threshold for the L-test ($p=0.05$, $\eta_p^2 = 0.36$) but not statistically significant for the locomotion
22 course ($p=0.07$, $\eta_p^2 = 0.38$) or the Timed up-and-go test ($p=0.12$, $\eta_p^2 = 0.22$). Locomotion
23 course performance had good to excellent test-retest reliability and strong concurrent validity.

24

25

26 **Conclusion**

27 Using a combination of a hydraulically articulating ankle-foot and a microprocessor-
28 controlled knee resulted in the highest performance in mobility tests. This was observed in
29 contrast to combinations of prosthetic components that included a rigid ankle-foot component
30 and/or a non-microprocessor-controlled knee component.

31

32 **KEYWORDS:** Microprocessor knee; hydraulic ankle; transfemoral; mobility.

33

34 INTRODUCTION

35 The individual components that make up prosthetic limbs vary widely. Components
36 can be quite basic with limited functionality, through to more sophisticated and complex
37 components that use advanced materials and electronics. More advanced componentry is often
38 perceived to be of greater benefit to the individual user in terms of mobility and wider health
39 status. In order to understand and evaluate the effects of a new component on the user,
40 investigators try to experimentally control as many factors as possible between component
41 manipulations. This approach isolates the effects brought about by changing or altering a single
42 component. There are situations however, where multiple functional components are required
43 to interact to form an effective prosthetic limb. Examples of such components used to construct
44 a whole prosthetic limb, include the ankle-foot component for transtibial prosthesis users and
45 additionally, the knee component for transfemoral prosthesis users.

46 In terms of ankle-foot components, previous research has demonstrated many
47 adaptations that occur when individuals with lower limb amputation use more functionally
48 advanced, passive prosthetic ankle-foot components. These include improved push off
49 mechanics and step length symmetry¹⁻⁴ associated with using energy storing and returning feet.
50 Increased walking speed^{5,6}, reduced residuum distal end loading⁷, improved toe clearance
51 during swing⁸ and decreased metabolic cost of walking⁹ have been observed when using
52 hydraulically articulating ankle-foot components. Individuals with lower limb amputation
53 display a preference for these components, when compared to less functionally advanced
54 components^{2,10,11}. Therefore, these adaptations are interpreted as being beneficial to
55 individuals with lower limb amputation.

56 With regards to prosthetic knee componentry, several adaptations are associated with
57 using more functionally advanced microprocessor-controlled knee components (MPK), when
58 compared to non-microprocessor-controlled knee components (NMPK). These include

59 increased physical activity ¹², walking speed ^{13,14} and walking gait kinetic symmetry ¹⁵. The
60 use of MPK components has also been predicted to reduce fall risk ¹⁶. More advanced prosthetic
61 components have been reported to lead to broader social and economic benefits. These include
62 improved quality of life for the user of an MPK and reduced direct and indirect healthcare costs
63 associated with MPK provision ¹⁶. As a result, healthcare policymakers have commissioned
64 such advanced prosthetic components e.g. MPK components, routinely in national healthcare
65 systems ¹⁷.

66 The literature is extensive regarding the benefits of an individual component for
67 individuals with lower limb amputation. However, little is known regarding how combinations
68 of components interact to affect mobility. Identifying the optimal combination of both ankle-
69 foot and knee components for improving mobility in individuals with unilateral transfemoral
70 amputation (IUTF), for example, is critical. At present, it is not clear whether this optimal
71 solution would be exclusively comprised of more advanced componentry or not.
72 Understanding how different combinations of ankle-foot and knee components affect mobility
73 will allow for a more objective selection of prosthetic limb prescription, regardless of how
74 extensive the componentry range available to an individual patient and/or clinician is.

75 Therefore, the purpose of this study was to assess whether varying the combination of
76 ankle-foot and knee components used by unilateral transfemoral prosthesis users, influenced
77 outcomes from tests of mobility. The combinations assessed, comprised of a basic, non-
78 articulating or an advanced, hydraulically articulating ankle-foot component, combined with
79 either a microprocessor-controlled or a non-microprocessor-controlled knee component. Given
80 the benefits associated with advanced component user, we hypothesised that a combination of
81 more advanced components (e.g. hydraulic ankle-foot component and MPK), would result in
82 improved performance in mobility test outcomes.

83

84 **METHODS**

85 **Participants**

86 A group of IUTFs (n=9, ♂ 9) and a group of otherwise healthy control participants
87 (CON, n=10, ♀2, ♂8) were recruited for the current study (Table 1). Inclusion criteria for the
88 IUTF group were; aged 18 or over, able to negotiate obstacles such as ramps and stairs i.e.
89 commensurate with a K3 mobility level¹⁸, able to walk continuously for at least two minutes at
90 a time, had good (corrected, if necessary) vision and had no unresolved cardiovascular
91 complaints. Individuals in the IUTF group were excluded if they; experienced undue
92 musculoskeletal pain causing them to stop and be unable to continue when walking at a self-
93 selected speed, were unable to complete tasks due to disease/illness (e.g. rheumatoid arthritis),
94 had a current neuromuscular or musculoskeletal injury, or fell regularly (>1 a month) as
95 determined using the PROFANE fall definition¹⁹. They were also excluded if their residuum
96 had significant blisters, wounds and/or rashes which prevented the prosthesis, sock and liner
97 being worn comfortably, or they had any other substantial changes to the physical condition of
98 the residuum that required medical attention. The CON group were recruited using the same
99 inclusion/exclusion criteria, excluding criteria specifically related to amputation status. The
100 study was approved by a national healthcare research ethics committee [XXXXXXXXXX] and
101 all participants provided written informed consent prior to participation in the study.

102

103 ***Table 1 here***

104 Table 1. Participant characteristics of individuals with unilateral transfemoral amputation
105 (IUTF) and otherwise healthy controls (CON).

106

107 **Study Design**

108 Individuals in the IUTF group completed the mobility tests described below in four prosthetic
109 conditions. The four conditions were made up of a combination of one of two ankle-foot
110 component options and one of two knee component options. The ankle-foot component options
111 were a rigidly attached, non-articulating ankle-foot component (RIG; Esprit, Blatchford Ltd,
112 Basingstoke, UK) and a hydraulically articulating component (HYD; Echelon, Blatchford Ltd,
113 Basingstoke, UK). The knee component options were a non-microprocessor knee component
114 that each participant had either used previously and/or was currently using (NMPK, see Table
115 1) and a microprocessor-controlled knee component (MPK; Orion3, Blatchford Ltd,
116 Basingstoke, UK). The conditions were abbreviated as; MPK+HYD, MPK+RIG,
117 NMPK+HYD, NMPK+RIG. No other prosthetic components were altered, and all participants
118 had current or prior experience of using all knee and ankle-foot components. The ordering of
119 the four different combinations was randomised via a random number generator. The alteration
120 of prosthetic componentry was conducted by an experienced, licensed prosthetist.

121

122 **Study Protocol**

123 Participants completed the following mobility tests in the same order, on the same day
124 for each prosthetic condition: Two-minute walk test (2MWT), the Timed up-and-go test (TUG),
125 the L-test and a custom locomotion course (Loco), which included stair and ramp ascent and
126 descent, obstacle negotiation and turning (Figure 1). Participants completed a practice trial and
127 then recorded trials of the 2MWT, until consecutive trials were within 10% of each other.
128 Participants completed three trials of the TUG, L-Test and Loco, with rest periods as required.
129 The reliability and validity of the 2MWT^{20,21}, TUG²² and L-Test²³ have been demonstrated
130 previously in individuals with lower limb loss. The test-retest reliability and concurrent validity
131 of the custom locomotion course is reported in the current study.

132

Figure 1 here

133

134 Figure 1. A plan view (A) including walking lengths and representative sketch (B) of the
135 custom locomotion course used in the current study.

136

137 **Data and Statistical Analysis**

138 The final trial from all mobility tests was used to compare the test outcomes obtained
139 when under four different combinations of prosthetic componentry. Initially, the normality of
140 data distribution was assessed using a Shapiro-Wilk test. A one-way repeated measures
141 analysis of variance was conducted and where the assumption of sphericity was violated, a
142 Greenhouse-Geisser correction factor was applied. Multiple post-hoc comparisons were
143 adjusted for using a Sidak correction with effect sizes (partial eta squared) calculated for each
144 statistical comparison. The alpha level of statistical significance was set at $p=0.05$.

145 The test-retest reliability for the Loco outcomes were established for all prosthetic
146 combinations in the IUTF group and for the CON group by calculating intraclass correlation
147 coefficients (ICCs) using a two-way mixed-effects model for absolute levels of agreement. The
148 ICCs were calculated between the first and second and, the second and third trials of the Loco
149 test. The test-retest reliability for the Loco outcomes between trials was then categorised as
150 either poor (<0.5), moderate ($0.5 - 0.75$), good ($0.75 - 0.9$) or excellent (>0.9)²⁴. The
151 concurrent validity between the Loco and the 2MWT, TUG and L-test was assessed using
152 Pearson's Product-Moment Correlation (r). Correlation coefficients were defined as small
153 ($0.1 < |r| < 0.3$), moderate ($0.3 < |r| < 0.5$) or strong ($|r| > 0.5$)²⁵. All statistical analyses were
154 conducted in IBM SPSS software (v.26 IBM, Portsmouth, UK).

155

156 **RESULTS**

157 **Outcomes from mobility tests**

158 Across all mobility tests, an order of performance according to the combination of
159 prosthetic components used was observed. Participants' best performance was observed when
160 using the MPK+HYD combination, followed by the MPK+RIG, NMPK+HYD and finally the
161 NMPK+RIG combination (Figure 2, Table 2). This effect was statistically significant for two-
162 minute walk distance ($F(3,24) = 4.50, p=0.01, \eta_p^2 = 0.36$) and on threshold of significance for
163 the L-test ($F(1.28,10.21) = 4.51, p=0.05, \eta_p^2 = 0.36$) (Table 2), post hoc tests did not reveal
164 which combinations resulted in these significant effects. The effect was not statistically
165 significant for the locomotion course ($F(1.14,7.97) = 4.37, p=0.07, \eta_p^2 = 0.38$) and for the
166 Timed up-and-go test ($F(3,24) = 2.19, p=0.12, \eta_p^2 = 0.22$) (Table 2).

167

168

Figure 2 here

169 Figure 2. Group mean \pm 95% confidence interval and individual participant mobility test
170 outcomes for each combination of prosthetic componentry. Control data is for visual
171 representation only and was not used in within group statistical analyses.

172

173 **Test-retest reliability and concurrent validity of the locomotion course outcomes**

174 The test-retest reliability of the Loco, between trials one and two and between trials two
175 and three, was excellent (>0.9) for all prosthetic combinations in the IUTF group and for the
176 control group (Table 3). In addition, evaluation of the 95% confidence interval range suggested
177 that test-retest reliability might be better between trials two and three, with lower ICC bounds
178 ranging between good (0.76, MPK+RIG) to excellent (0.96, NMPK+RIG) (Table 3). Generally,
179 strong ($r>0.5$) concurrent validity was observed for all prosthetic combinations in the IUTF
180 group and for the control group when contrasting the Loco with the 2MWT, the L-Test and the
181 TUG (Table 3). Exceptions were the relationships between the Loco and the TUG in the CON

182 group ($r = 0.04$, $p=0.91$) and the Loco and 2MWT using the MPK+HYD combination ($r = -$
183 0.53 , $p=0.18$) and the NMPK+HYD combination ($r = -0.63$, $p=0.10$) in the IUTF group.

184

185 ***Table 2 here***

186 Table 2. Full reporting of group means, lower (LL) and upper (UL) bounds of 95% confidence
187 intervals and full statistical analyses with F statistic, p value and effect size (partial eta squared,
188 η_p^2) for each outcome measures' main effects.

189

190 ***Table 3 here***

191 Table 3. Test–retest reliability and concurrent validity for the locomotion course outcomes for
192 the UTF group (all prosthetic combinations) and the CON group. Test-retest reliability is
193 assessed using intraclass correlation coefficients (ICCs), including the lower and upper bound
194 of the 95% confidence interval, between trials one and two, and two and three from the
195 locomotion course. Concurrent validity between the locomotion course and the 2MWT, TUG
196 and L-test is assessed using Pearson's Product-Moment Correlation (r).

197

198 DISCUSSION

199 The current study assessed whether varying the combination of ankle-foot and knee
200 components used by unilateral transfemoral prosthesis users, influenced outcomes from tests
201 of mobility. Results show that the combination of prosthetic components used in mobility tests,
202 has a significant bearing on the test outcomes.

203 In all four mobility tests undertaken in the current study, the order of performance, from
204 best to worst, was MPK+HYD, MPK+RIG, NMPK+HYD and finally NMPK+RIG. This
205 prosthetic combination effect was statistically significant for the 2MWT ($p = 0.01$) and on the
206 threshold of statistical significance for the L-test ($p = 0.05$). Given that the order of performance

207 between prosthetic conditions was consistent across all mobility tests, it seems reasonable to
208 posit that, despite the lack of statistical significance in some instances, the results reflect a
209 general benefit to mobility of using a combination of more advanced prosthetic components.
210 A clear implication of this is that where there is the option, a more advanced combination of
211 prosthetic components should be selected/prescribed, if increased mobility is the objective.
212 During locomotion, intact biological limbs have been conceptually modelled a single ‘limb’
213 system^{26–28}. In addition, it has been shown that the ankle, knee and hip joints function in a
214 complimentary and compensatory fashion during locomotion in people without limb loss^{29–31}.
215 Therefore, it may seem unsurprising that the use of a combination of more advanced prosthetic
216 components with greater mechanical functionality would lead to improvements in mobility.
217 However, establishing the effects of an MPK and hydraulically articulating ankle-foot
218 component is relevant as these combinations are realistic and commonly prescribed options in
219 national healthcare systems. It must be noted that advanced prosthetic components are also
220 often prescribed for reasons not necessarily directly related to mobility e.g. safety and quality
221 of life. The current data do not speak to these issues, nor the underlying biomechanical basis
222 for the changes in mobility observed. Future research should seek to clarify the underlying
223 mechanisms for these changes in mobility, to understand where and how these components
224 benefit mobility in IUTFs. The clinical relevance of the differences observed must also be
225 considered. For example, the minimal clinically important difference (MCID) for the L-test
226 (4.5 seconds)³², exceeds the range of scores from the current study, suggesting reduced clinical
227 importance of the observed differences. However, this MCID threshold was determined in a
228 different sample with very different characteristics, potentially limiting this interpretation.

229 The observation that performance is improved in IUTFs when completing mobility tests
230 when using one advanced component alongside a more basic component, also builds on
231 previous reports of these components’ efficacy in terms of mobility^{14,16}. Outcomes from all

232 four of the tests completed in the current study suggested that when individuals used an MPK,
233 in combination with a rigid ankle-foot component, their performance was better than when
234 using a NMPK in combination with a hydraulically articulating ankle-foot component (Figure
235 2). This highlights a key point related to prosthetic knee provision. For the IUTFs in the current
236 study, prosthetic knee functionality was seemingly more influential than prosthetic ankle-foot
237 function. This supports the current focus on commissioning and/or reimbursement of MPKs in
238 healthcare systems ^{16,17}, as knee component functionality seems to be an appropriate initial
239 focus for improving mobility in IUTFs. This data also supports previous findings that MPKs
240 enhance the ability of IUTFs to perform activities of daily living ¹²⁻¹⁵. Interestingly, the
241 provision of an advanced ankle-foot component with both an MPK and NMPK had positive
242 influences on mobility, which has implications for prosthetic prescription and patient selection.
243 As described above, where an MPK is prescribed, the addition of an advanced ankle-foot
244 component may afford an additional benefit to mobility. Furthermore, where MPK components
245 are not available, feasible or desirable, for cost or practicality reasons, the mechanical function
246 of an advanced ankle-foot component, such as the hydraulic ankle-foot components assessed
247 in the current study, could also provide additional mobility benefits ³³. This may be of particular
248 use to IUTFs in low resource settings or with multiple options for prosthetic limbs. Of course,
249 the data from the current study must be viewed in the context of the ability of the participants
250 recruited. Even with a rigid ankle-foot and NMPK combination, all participants were able to
251 safely and effectively complete several challenging mobility tests, suggesting even the more
252 basic components allow for effective locomotion.

253 The custom locomotion test designed as part of the current study was found to have
254 good to excellent test-retest reliability and strong concurrent validity. The dimensions of the
255 walking course may restrict its use to larger research centres. Also, its set-up may not reflect
256 realistic environmental situations people may find themselves for example, climbing stairs

257 using handrails. However, the locomotion course may provide information regarding mobility
258 in general, whilst also enabling researchers to segment relevant tasks for further investigation
259 e.g. stair negotiation. The addition of instrumentation e.g. force-sensing capabilities in the
260 staircase, would further increase researchers' ability to interrogate the underlying
261 biomechanics in studies such as those presented here.

262 There were a few important limitations in the current study. The first, and likely most
263 common issue with such experimental designs, is that it was not possible to blind participants
264 to the prosthetic component manipulations. This was due to the differing requirements of each
265 component during the fitting and set-up procedures. Thus, it is highly possible that our results
266 were affected by individuals' preconceptions and/or preferences towards certain component
267 combinations. Another key limitation was the acute nature of the prosthetic manipulations.
268 Although the test data suggested a good level of familiarisation with each combination of
269 prosthetic components, results may have been accentuated had participants been afforded a
270 longer accommodation period. This was not possible in the current study, as in some cases,
271 longer term change to participants' prosthetic prescription would have negatively affected
272 adherence, given lack of flexibility and deviation from the prosthetic prescription provided by
273 their national healthcare provider. A final key limitation of the current study were the sample
274 characteristics (all male participants secondary to trauma) and size, leading to limited
275 generalisability and potential under powering of the study. We aimed to recruit individuals
276 from local limb centres who possessed both MPK and NMPK components to reduce
277 accommodation effects of these manipulations. Alongside health concerns of human testing
278 owing to the COVID-19 pandemic from February 2020, participant recruitment was curtailed.
279 Notwithstanding, we feel that the consistency of our results across prosthetic component
280 combinations and mobility tests, support our conclusions.

281

282 CONCLUSION

283 The use of more functionally advanced prosthetic knee and ankle-foot componentry,
284 particularly when used in combination, have a positive effect on mobility in individuals with
285 unilateral transfemoral amputation. This information may inform decisions around prosthetic
286 prescription and policymaking, where varied options for prosthetic components are available.

287

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406 Figure 1. A plan view (A) including walking lengths and representative sketch (B) of the
407 custom locomotion course used in the current study.

408

409 Figure 2. Group mean \pm 95% confidence interval and individual participant mobility test
410 outcomes for each combination of prosthetic componentry. Control data is for visual
411 representation only and was not used in within group statistical analyses.

412