

Enhancing Expressivity, Modularity and Rigour of Graphical Data Modelling with Fragmenta

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Graphical data (or conceptual) modelling, software engineering’s most popular application of modelling, needs an uplift. Graphical data models easily become unwieldy, even for trivial medium-sized systems. Practitioners long for improved modelling primitives and mechanisms that improve modelling, namely, its expressiveness, the way it is experienced and its appeal. These are the drivers of FRAGMENTA, a formal data- and meta-modelling framework with advanced means to separate concerns. FRAGMENTA’s novelties include: (i) multilevel modelling through vertical refinement, (ii) improved horizontal decomposition and composition of fragments through proxies, (iii) *virtuals* for lighter inheritance, and (iv) graphical model constraints. FRAGMENTA is the first data modelling framework with a mathematical foundation and a supporting implementation, combining both vertical and horizontal means to separate concerns.

CCS Concepts: • **Software and its engineering** → **Design languages**.

Additional Key Words and Phrases: Model-driven development, modelling, data-modelling, scalability, metamodeling, graphs, Fragmenta, multilevel modelling, model refinement, graphical constraints, OO inheritance

1 INTRODUCTION

Graphical data models easily become large and unwieldy. The more complex the problem the worse it gets. When models become cluttered, in the case of data models this may happen even in simple systems, our capacity to handle them degrades considerably [46]. Such models must be kept tidy with manageable complexity; this requires means to break things apart properly to separate concerns [54, 61]. The effectiveness of the mechanisms that help managing model complexity dictate how scalable a particular language is. Because mainstream graphical languages, such as UML and entity relationship diagrams, lack advanced complexity management means, their scalability is limited [49]. This paper presents FRAGMENTA, the formal data- and meta- modelling graphical framework that provides novel means of expressiveness, abstraction and decomposition.

FRAGMENTA’s class modelling¹ articulates concerns through *vertical* and *horizontal refinement*. Vertical refinement (or layering) is about abstraction; it allows abstract layers to be refined or elaborated into more concrete layers. Horizontal refinement, about division or separation, decomposes class models into fragments along *proxies*, which are the joints holding the separate fragments (smaller class models) together, enabling composition; a FRAGMENTA model is a collection of fragments with a coherent meaning as a whole.

FRAGMENTA’s multilevel modelling based on vertical refinement offers an architecture based on two strata: type (or meta) and instance. The type stratum can be further divided into layers related through a chain of vertical refinements, following principles and ideas of data refinement [35]. The instance stratum is indivisible. Type and instance strata are related through instantiation (or typing); type (or meta) layers or models are related through refinement.

Defined mathematically upon algebraic graphs and their morphisms, FRAGMENTA provides a foundation for modular and abstract class modelling. It was specified in Z [37, 60, 64] using the CZT type-checker [45, 47], verified in Isabelle [63], and implemented in Haskell [15, 36, 44]².

¹Class modelling, which evolved from database design and entity relationship modelling [19], is used for both data- and meta-modelling. The latter, FRAGMENTA’s major use so far, describes the abstract syntax of graphical languages.

²Available from <https://github.com/namalio/Fragmenta>.

1.1 Research Questions

The paper addresses the following research questions (RQs):

- *RQ1*: Can the complexity of large data models be mastered through division (or separation) to ultimately facilitate comprehension, articulation and mechanisation?³
- *RQ2*: Can class-modelling accommodate vertical abstraction and multi-level modelling?
- *RQ3*: Can graphical data modelling be improved to enhance expressiveness?

1.2 Contributions

The paper’s contributions are as follows:

- FRAGMENTA, initiated in [7] and applied in [11], is equipped here with *layering* or *vertical refinement*. To the author’s knowledge, FRAGMENTA is the first formal data- and meta- modelling framework that supports both horizontal and vertical refinement to complement separation with enhanced abstraction.
- FRAGMENTA’s multilevel modelling based on an architecture made-up of two strata, type and instance, with the former possibly further divided into layers through vertical refinement, and allowing extra-typings between models within the same layer, is, to the author’s knowledge, novel. FRAGMENTA pioneers the application of refinement, inspired by data refinement [35], in formal and graphical multilevel data- and meta-modelling, refreshing a body of work focused mostly on instantiation.
- The *proxy* primitive, a notational novelty of [7], is enhanced here with fragment composition (or resolution), based on the newly introduced notion of graph subsumption, providing a precisely defined composition mechanism.
- Several notational novelties of FRAGMENTA, namely: (i) *virtual nodes* (or *virtuals*), which provide lighter inheritance with weaker lineage (or ancestry), supporting union types; (ii) derived, value-constraint and path edges, which express model constraints graphically.
- The tool, which attests to the realisability of FRAGMENTA, enables experimentation; it checks the healthiness of FRAGMENTA models, and the correctness of typings and refinements; it deemed adequate all layered models and small examples presented in the paper.

1.3 Outline

The remainder of this paper starts with a primer on FRAGMENTA (section 2), to introduce FRAGMENTA’s main primitives. This is followed by FRAGMENTA’s mathematical definition which upgrades and re-defines [7] (section 3). FRAGMENTA is then further illustrated through three examples: (i) an e-commerce system (section 4), (ii) the abstract syntax of statecharts [33] (section 5), (iii) and a SysML profile for cyber-physical systems (section 6). The evaluation (section 7) appraises FRAGMENTA against related approaches. The remaining sections discuss the paper’s results and achievements (section 8) and related work (section 9), and draw the conclusions (section 10). Appendix A provides FRAGMENTA’s detailed mathematical definitions.

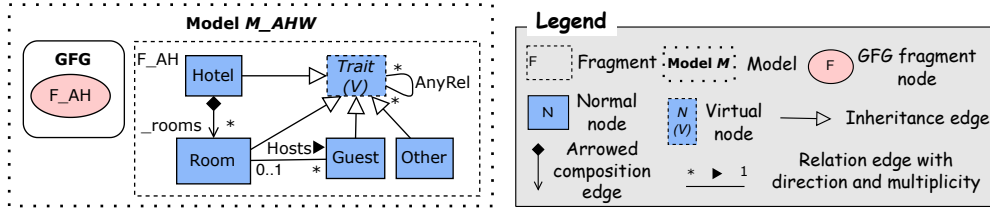


Fig. 1. Abstract hotel world model made up of one sole fragment.

2 A PRIMER ON FRAGMENTA

A two-layered model illustrates FRAGMENTA. The abstract layer (Fig. 1) describes hotels in general; the concrete layer (Fig. 2) describes a hotel for pets. Figure 2 refines Fig. 1, called *vertical refinement* herein: something more concrete is defined from something more abstract.

The model of Fig. 1 comprises one sole fragment, F_{AH} , as per the *Global Fragment Graph* (GFG). F_{AH} illustrates several modelling primitives of FRAGMENTA:

- All rectangles are nodes representing concepts from the domain of discourse. The dashed rectangle named *Trait* and labelled with “(V)” is a *virtual*, a FRAGMENTA novelty to represent inheritable features, providing a weaker notion of inheritance parenthood and enabling multiple inheritance. Virtuals are both like and unlike abstract nodes (e.g. *Pet* in Fig. 2), the equivalent of abstract classes in the classical object-oriented (OO) paradigm; like because they do not have direct instances; unlike because abstract nodes set an inheritance lineage and only allow single inheritance in FRAGMENTA⁴. The remaining nodes are self-descriptive; *Other* represents any other relevant concept, apart from *Hotel*, *Room* and *Guest*.
- The solid plain lines (without diamonds or triangles) are *relation* edges, which say that one node is meaningfully related to another. In Fig. 1, *Hosts* says that guests stay in rooms (arrow above line indicates direction), and *AnyRel* says that *Traits* may be related.
- The hollow-headed arrows establish *inheritance* or *is-a* relations between nodes — *Other*, *Guest*, *Hotel* and *Room* are *Traits*, hence *AnyRel* also applies to them.
- Compositions (lines with black diamond at the end) establish *part-of* relations with the implication that parts are not shared; *Hotel_rooms*⁵ says that *Rooms* belong to *Hotels*.
- Relation and composition edges have multiplicities at the ends — e.g. *Hosts* is many (*) to optional (0..1) —, and have a direction indicated by either the edge’s arrow, or symbols ◀ and ▶ sitting above an undirected edge. Undirected edges have multiplicities of 1, unless otherwise stated. Arrowed edges only require the target multiplicity (e.g. edge *Hotel_rooms*); the source multiplicity is assumed to be either many (relations) or 1 (compositions).

Figure 2 portrays M_{PW} , a model of an hotel for pets. Figure 3 maps the elements of M_{PW} onto M_{AHW} to say how the former complies to the latter. The GFG of Fig. 2 says how the model’s fragments transitively *reference* each other,

³Complexity tackled through division (or separation) is the basis of modularity in computer science and software engineering [54]; modularity tends to benefit comprehension and articulation [61].

⁴Virtuals lack an actual existence and embody a weaker notion of parenthood being virtual and not actual parents. A node may have: at most one strong (a normal or abstract node) and many virtual parents.

⁵Names of directed edges starting with an underscore (‘_’) make use of a convention to shorten names; the final name is obtained by prefixing the given name with the name of the source node — here, final name is *Hotel_rooms*.

- F_PW3 introduces *enumeration* PetStatus, which defines the status of pets as either privileged, middleclass or disadvantaged. Pets are further subdivided, through inheritance, into Mammals, either Dogs or Cats, or Reptiles, either Chamaeleon or Gecko; the VCE states that reptiles must not be disadvantaged.
- F_PW5 illustrates *derived edges* (dashed lines), a FRAGMENTA novelty to describe constraints through multiplicities and path expressions, to say that: dogs, reptiles and cats must be hosted in their respective zones (the path expression starts from PDog and takes the inverse of Hosts to reach PetRoom, then it takes zone to reach dogs). In F_PW7 and F_PW8 the derived edges state that: (i) ensuite rooms are served by one toilet, (ii) privileged pets stay in ensuite rooms only, (iii) there are no ensuite rooms in the reptile zone, and (iv) disadvantaged or middle-class pets cannot stay in ensuite rooms.
- F_PW6 further illustrates proxies to show how they can be used to bring over information from other fragments in order to define new model concepts.
- F_PW7 illustrates *path edges* (pointed lines connected with an extra double arrow indicating an operator, either = or $\subseteq$), another FRAGMENTA novelty to define constraints on edge paths through commuting, to say that zones of served room and toilet must be the same⁶.

Elements of M_PW (Fig. 2, concrete) are mapped onto their M_APW (Fig. 1, abstract) counter-parts in Fig. 3; this mapping defines morphism ms . M_PW refines M_APW via ms as per the formula $(M_PW, ms) \sqsubset^M M_APW$, explained in the next section.

The graph of Fig. 4, an instance of Fig. 2, depicts a pets hotel with facilities and guests. The typing (or instance-of) compliance which exists between Figs. 4 and 2 can be written concisely as $G_PW1 \ni^M M_PW$ using the definitions of the next section; this compliance is valid as confirmed by FRAGMENTA's tool. A mutation of Fig. 4, say G_PW2 , where (i) the rooms allocated to dog K and cat G are swapped, (ii) the capacity of room PR3 is changed from 20 to 0, and (iii) the month of L's birth is changed from 11 to 13, would be an invalid instance of Fig. 2, as: (i) ERND derived edge of fragment F_PW8 would be breached as disadvantaged K is staying in ensuite room PR1; (ii) derived edges S1 and S3 of fragment F_PW5 would be breached as K would be staying in a dog zone and G in a cat zone; (iii) the 0 capacity of room PR3 would breach the value-constraint edge of node Nat₁ in fragment F_PW1; and (iv) month 13 of L's birth would breach the value constraint edge associated with relation edge month in fragment F_PW1. These issues would be flagged by the FRAGMENTA tool as reasons for not establishing that $G_PW2 \ni^M M_PW$.

3 THE FRAGMENTA THEORY

FRAGMENTA is formalised using algebraic graph theory, redefining and upgrading [7]. The foundations of the FRAGMENTA theory lie in plain graphs (section 3.1). From then the theory is enriched incrementally with structural graphs (SGs) in section 3.2, built on top of graphs, to represent class-like diagrams, widely used in software engineering, fragments (section 3.3), built on top of SGs, global fragment graphs (GFGs, section 3.4), and models (section 3.5). The text refers to appendix A which contains all of FRAGMENTA's mathematical definitions that refer to theorems proved in Isabelle [63]⁷. All the mathematics was specified in Z [5] and implemented in Haskell; all FRAGMENTA examples give herein were tested in the implementation⁸.

⁶Here, each path has a different expression: from Toilet we take Serve and then zone to reach HotelZone, or we just take zone – the overall constraint states that both paths must lead to the same zone.

⁷<https://isabelle.in.tum.de/>

⁸FRAGMENTA's Z specification, Isabelle theory and Haskell implementation are all available from <https://github.com/namalio/Fragmenta>.

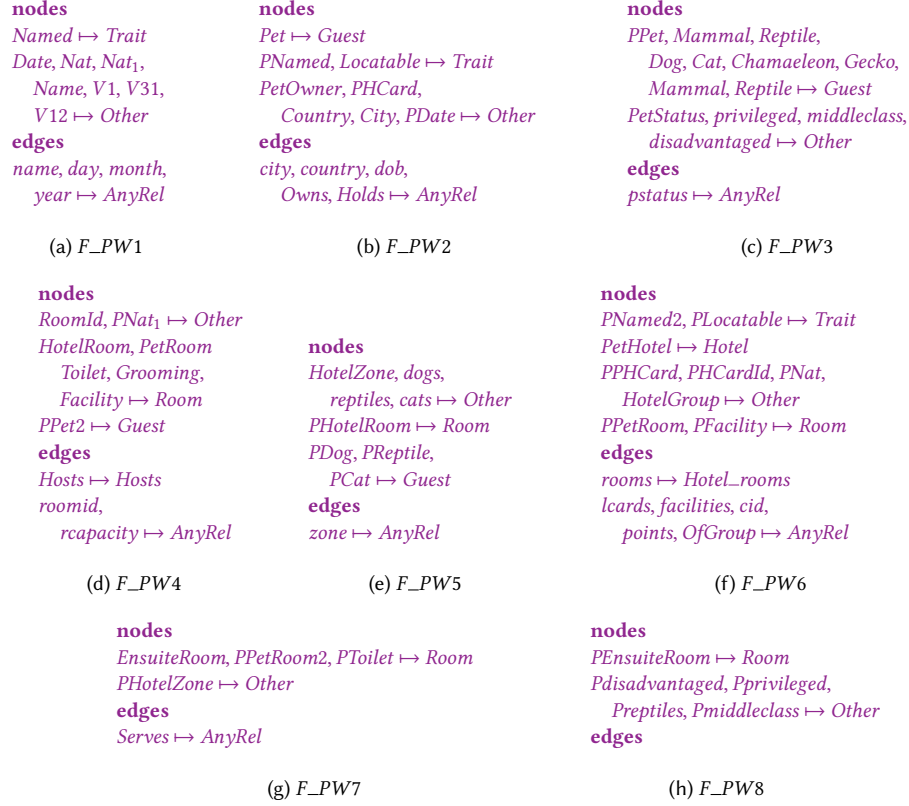


Fig. 3. Mappings for each fragment of the concrete model into the abstract model.

The sequel uses several operators related to sets (def. 1), relations (def. 2) and functions (def. 4). An abbreviated function application convention is used throughout – e.g. Ns_G means $Ns\ G$ or $Ns(G)$. Certain infix binary operators are either sub- or super-scripted with a label indicating the structure they operate upon – e.g. $\cup_G$ is graph union (G refers to graphs).

3.1 Graphs and their morphisms

Sets V and E represent all possible graph nodes and edges (def. 5). A graph G (Fig. 5a), a member of set Gr (def. 7), written $G \in Gr$ or $G : Gr$, is a quadruple $G = (N, A, s, t)$, made up of sets $N \subseteq V$ and $A \subseteq E$ of nodes and edges (or arcs), respectively, and total functions $s, t : A \rightarrow N$ which give the source and target nodes of edges, respectively. Projection functions Ns, Es, src and tgt extract the individual components of a graph, Els gives a pair formed by the graph's nodes and edges, and $\emptyset_G$ gives the empty graph (def. 7).

The following handle graphs (def. 8): (i) $adjacent(G, v_1, v_2)$ says whether node v_1 is adjacent to v_2 in graph G ; (ii) $adjacent_E(G, e_1, e_2)$ says whether edge e_1 is adjacent to e_2 ; (iii) $G \triangleright_{Es} es$ restricts G to set of edges es ; (iv) $G \circ \rightarrow_{vs}$ gives incident edges of nodes vs ; (v) $G \bullet \leftrightarrow_{vs}$ gives the edges connecting the nodes vs ; (vi) $G \leftrightarrow^*$ builds a mathematical relation between the nodes connected in G ; (vii) $G_1 \cup_G G_2$ gives union of G_1 and G_2 ; (viii) $G \odot s$ subsumes G as per replacement

be composed: $g \circ f = (f_V g \circ f_V f, f_E g \circ f_E f)$ (def. 10). Figure 5c pictures a graph morphism. Graph morphisms are partial when the mapping functions are partial rather than total (def. 9)⁹.

A graph with typing, a member of set $GrwT$ (def. 11), is a pair $GwT = (G, m)$ made up of a graph $G : Gr$ and a morphism $m : GrM$, such that $domg\ m =_p\ Els\ G$ (def. 11); such graphs have an empty element ($\emptyset_{GwT}$) and a union operator ($\cup_{GwT}$) (def. 11). Graphs with extra typing, set $GrwET$ (def. 12), are another type of graph: a pair $GwET = (GwT, m)$, where $GwT : GrwT$ and m is a partial morphism, providing extra typing, a concept elaborated in the sequel.

3.2 SGs

SGs capture graphs typical of object-oriented (OO) class modelling notations, such as UML class diagrams, which typically include: (i) relations with multiplicities, (ii) inheritance, (iii) and part-of (or composition) relations. SGs embody many of FRAGMENTA's novelties, namely: (i) proxies (a representative of another node), (ii) virtuals (an inheritable characteristic passed with virtual or soft parenthood allowing multiple inheritance), (iii) value-constraint edges (a way to restrict the values of a node or edge through an operator, such as $=$), (iv) derived edges (multiplicity constraints on edge paths), and (v) path constraints (commuting constraints on edge paths). SGs can represent templates (or generics) using a combination of virtuals and derived edges (see below).

3.2.1 Node and Edge Types. SGs support a diversity of nodes and edges. Set $SGNT$ (def. 13), of SG's node types, include: normal (nrm), abstract ($nabst$), proxy ($nprxy$), enumeration ($nenum$), value ($nval$) and virtual ($nvirt$). Set $SGET$ (def. 13), of edge types, includes: inheritance (ein), composition ($ecomp$), relation ($erel$), derived ($eder$), value constraint ($event$) and path ($epath$). Compositions and relations are either bi-directional (dbi) or one-way ($duni$) (def. 13).

Ordering relation $\prec_{NT}$ (def. 13) stipulates the inheritance restrictions of node types. Orderings $\leq_{rNT}$ and $\leq_{ET}$ (def. 13) stipulate the node and edge types which are refinement-relatable, respectively.

3.2.2 Multiplicities. Multiplicity values (set $MultVal$ of def. 14) are ordered through $\leq_{mv}$ (e.g. $1 \leq_{mv} *$, 1 less or equal than many). Ordering $\leq_{Mc}$ establishes whether one multiplicity compound (a member of set $MultC$ of def. 14) is within another (e.g. $* \leq_{Mc} 0 \dots *$, and $1 \leq_{Mc} 1 \dots *$). Relation $\propto$ (def. 14) indicates the allowed multiplicities of edge types; for instance: two-way relations can have any multiplicity, and one-way compositions may have source multiplicities of 1 or $0 \dots 1$.

3.2.3 Path Expressions (PEs). PEs (def. 15) describe edge traversals as edge-based paths. They are part of derived and path edges, and describe extra multiplicity and commuting constraints, respectively. PEs are made up of path expression atoms (PEAs), either: a particular edge or its reverse (e.g. from edge e we get PEAs e and e^{-1}). A path expression PE , defined recursively, can be either a PEA, a PEA restricted on the domain or range to a particular node through $\triangleleft_{PE}$ or $\triangleright_{PE}$, respectively, and one PE followed by another through $\circ_{PE}$. Edges e_1 and e_2 may result in the PEs: e_1 , e_1^{-1} , and $e_1 \circ_{PE} e_2$.

3.2.4 Base SGs. An SG (depicted in Fig. 6a), a member of SGr_0 , the set of base SGs (def. 17), is a tuple $(G, nt, et, sm, tm, pe, ds)$ comprising: (a) graph $G : Gr$ (see above, def. 7); (b) colouring functions $nt : Ns\ G \rightarrow SGNT$ and $et : Es\ G \rightarrow SGET$, giving kinds of nodes and edges, respectively; (c) partial functions $sm, tm : Es\ G \rightarrow Mult$, assigning multiplicities to source and target of edges, respectively; (d) partial function $p : Es\ G \rightarrow PE$, giving PE of either a derived or path edge; and (e) relation $d : Es\ G \leftrightarrow Es\ G$, giving dependencies between path edges. Figures 7a to 7g give examples of SGs. Functions gr ,

⁹A partial morphism can be built from graph of Fig. 5d into $G1$ of Fig. 5c by mapping C, D and their connecting edge onto $G1$'s A, B and their connecting edge, respectively — A and B and the edge that connects them would not be mapped.

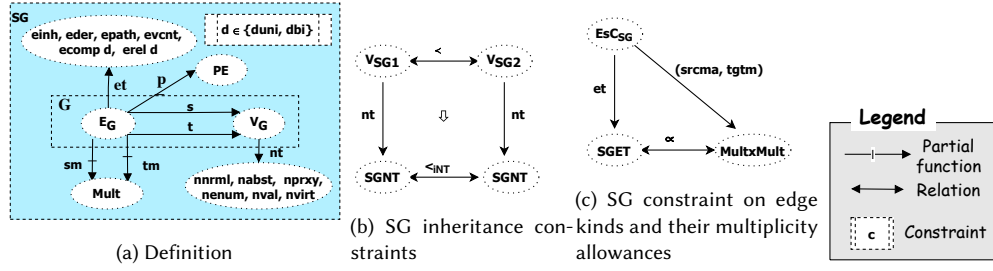


Fig. 6. Structural graph definition

nty , ety , $srcm$, $tgtm$, pe and ds extract the different SG components — for instance, $gr : SG_0 \rightarrow Gr$ yields SG's graph. Graph functions Ns , Es , src and tgt (section 3.1, def. 7) also apply to SGs (def. 17) — for instance, for any $SG : SG_0$, $Ns SG$ is same as $Ns(gr SG)$, $\emptyset_{SG}$ is the empty SG (def. 17), and hence: $gr \emptyset_{SG} = \emptyset_G$, $nty \emptyset_{SG} = \emptyset$ and $Ns \emptyset_{SG} = \emptyset$.

Functions that extract information from SGs include (def. 17): (i) $NsTy SG nks$ gets all nodes of SG of set of kinds nks ; (ii) $EsTy SG eks$ gets all edges of set of kinds eks . These are used to define relevant sets, such as $NsP = NsTy SG \{nprxy\}$ which yields proxies, similarly for $NsEther$ (kinds virtual, abstract and enumeration). Sets EsA , EsD , EsM and EsI of all association (includes composition and relation), derived, multiplicity (includes association and derived), and inheritance edges, respectively, are defined from $EsTy$ — e.g. $EsI SG = EsTy SG \{einh\}$.

Inheritance hierarchies are defined from inheritance edges. The inheritance graph is obtained through operator $\bowtie : SG_0 \rightarrow Gr$ (def. 17) — $\bowtie SG = gr SG \bowtie_{Es} EsI SG$. The inheritance relation, $< : SG_0 \rightarrow V \leftrightarrow V$ (def. 17), obtained from the inheritance graph — $< SG = (\bowtie SG)^{+*}$ —, captures parenthood. In Fig. 7a, $Person < Trait$, $Other < Trait$ and $Vehicle < Trait$.

3.2.5 Partial and Total SGs. SGs either stand alone, or are part of something larger. They are *partial* when part of a fragmented whole, *total* when monolithic or self-contained. Set SGr of partial SGs (def. 19) requires that: (i) multiplicity edges have source and target multiplicities, (ii) relation ds (dependencies) between path edges is anti-reflexive, (iii) function pe gives path edges of derived and path edges only, (iv) paths must be made of SG's association edges only, (v) edges comply to the multiplicity restrictions of their types (portrayed in Fig. 6c), (vi) the inheritance is well-formed, implying that the inheritance relation ($< SG$) complies with the required inheritance restrictions associated with the types of the related nodes (portrayed in Fig. 6b)¹⁰, and the inheritance is acyclic.

Total SGs, set $TSGr$ (def. 20), are partial SGs requiring that: (i) ethereal nodes (enumeration, abstract and virtual) are inherited; (ii) derived and path edges are well-formed (the nodes linked by the derived edges are consistent with the path expression and the encapsulated path expression is valid); and (iii) the inheritance hierarchy without virtual nodes is a tree (apart from virtual nodes, the inheritance is single, meaning that a node has at most one non-virtual or strong parent).

SGs of Fig. 7 illustrate different aspects of SGs: inheritance, virtuals and the *virtual traits* pattern (Figs. 7a and 7d); SG morphisms (Fig. 7b); enumerations, proxies and abstract nodes (Fig. 7c); compositions (Figs. 7d to 7g); derived and value constraint edges (Figs. 7d to 7g); the *templates* pattern where a pair generic is instantiated through a combination of virtual nodes and derived edges (Figs. 7f and 7g); and the *flexible edges* pattern (Fig. 7d): a unary (or self) edge on a virtual allowing multiple configurations, here constrained to preclude unary edges on *Vehicle*.

¹⁰ $\forall v_1, v_2 \bullet v_1 (< SG) v_2 \Rightarrow (nty SG) v_1 <_{NT} (nty SG) v_2$.

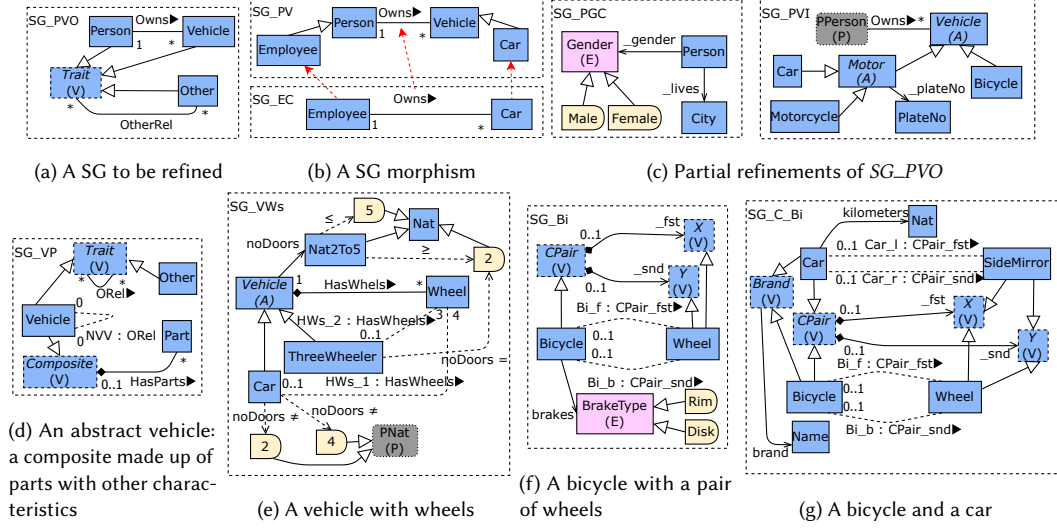


Fig. 7. Examples of structural graphs (SGs), illustrating: virtuals and the virtual traits pattern (a and d), SG morphisms (b), enumerations, proxies and abstract nodes (c), compositions (d to g), derived and value constraint edges (d to g), and the templates pattern (f and g)

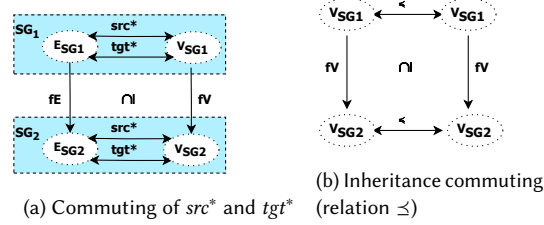


Fig. 8. SG-morphisms

Operator $\preceq$ (def. 18), the reflexive and transitive closure of the base inheritance relation $\prec$ — $SG = (\prec SG)^*$ — defines a partial order. In SG_PV of Fig. 7b: $Employee \preceq Person \preceq Person$. Functions $src^*, tgt^* : E \leftrightarrow V$ (def. 18) extend the graph functions src and tgt of def. 7 to give the source and target relations between edges and vertices — in an inheritance setting edges may possess more than one source and target nodes as descendants inherit the association edges of their ancestors. In SG_PV of Fig. 7b, $Owns$ is an edge of both $Employee$ and Car — $(Owns, Employee) \in src^*_{SG_PV}$ and $(Owns, Car) \in tgt^*_{SG_PV}$.

SGs are joined either through union ($\cup_{SG}$, def. 21), or subsumption along proxies ($\odot^{SG}$, def. 21). Figure 7e's subsumption would eliminate $PNat$ and redirect its incoming inheritance edges to Nat .

3.2.6 SG morphisms. These cater for the specificities of SGs. Because src^* and tgt^* yield relations, the equality commuting (Fig. 5b) is replaced by subset commuting (Fig. 8a). A SG morphism (def. 22, Fig. 8a) $m = (fv, fe)$ between $SG_1, SG_2 : SGr$, written $m \in SG_1 \rightarrow_{SG} SG_2$, where $fv \in Ns SG_1 \rightarrow Ns SG_2$ and $fe \in EsA SG_1 \rightarrow EsA SG_2$ (includes association and excludes inheritance edges), requires that:

$$fv \circ src^* SG_1 \subseteq src^* SG_2 \circ fe \wedge fv \circ tgt^* SG_1 \subseteq tgt^* SG_2 \circ fe \wedge fv \circ \preceq_{SG_1} \subseteq \preceq_{SG_2} \circ fv$$

Above, the first two conjuncts establish the commuting and the third inheritance-monotonicity (depicted in Fig. 8b). Partial SG morphisms, written $m \in SG_1 \rightarrow_{SG} SG_2$, are also allowed (def 22).

SGs of Figs. 7a and 7b are related through morphisms: $m_1 : SG_{PV} \rightarrow_{SG} SG_{PVO}$, $m_2 : SG_{EC} \rightarrow_{SG} SG_{PVO}$, $m_3 : SG_{EC} \rightarrow_{SG} SG_{PV}$ (depicted in Fig. 7b), $m_4 : SG_{PV} \rightarrow_{SG} SG_{EC}$:

$$\begin{aligned} m_1 &= (\{Person, Employee \mapsto Person, Vehicle, Car \mapsto Vehicle\}, \{Owns \mapsto Owns\}) \\ m_2 &= (\{Employee \mapsto Person, Car \mapsto Vehicle\}, \{Owns \mapsto Owns\}) \\ m_3 &= (\{Employee \mapsto Employee, Car \mapsto Car\}, \{Owns \mapsto Owns\}) \\ m_4 &= (\{Person, Employee \mapsto Employee, Vehicle, Car \mapsto Car\}, \{Owns \mapsto Owns\}) \end{aligned}$$

SGs of Figs. 7c and 7a are related through $m_5 : SG_{PGC} \rightarrow_{SG} SG_{PVO}$, $m_6 : SG_{PVI} \rightarrow_{SG} SG_{PVO}$, the partial $m_7 : SG_{PVI} \rightarrow_{SG} SG_{PVO}$ and $m_8 : SG_{PGC} \cup_{SG} SG_{PVI} \rightarrow_{SG} SG_{PVO}$:

$$\begin{aligned} m_5 &= (\{Person \mapsto Person, Gender, City, Male, Female \mapsto Other\}, \\ &\quad \{Person_gender, Person_lives \mapsto OtherRel\}) \\ m_6 &= (\{PPerson \mapsto Person, Vehicle, Motor, Bicycle, Motorcycle \mapsto Vehicle, PlateNo \mapsto Other\}, \\ &\quad \{Owns \mapsto Owns, Motor_plateNo \mapsto OtherRel\}) \\ m_7 &= (\{PPerson \mapsto Person\}, \{Owns \mapsto Owns\}) \\ m_8 &= m_5 \cup_{GM} m_6 \end{aligned}$$

Finally, SGs of Figs. 7d to 7g are related through $m_9 : SG_{VWs} \rightarrow_{SG} SG_{VP}$, $m_{10} : SG_{Bi} \rightarrow_{SG} SG_{VP}$, $m_{11} : SG_{C_Bi} \rightarrow_{SG} SG_{VP}$:

$$\begin{aligned} m_9 &= (\{Vehicle \mapsto Vehicle, Car \mapsto Vehicle, ThreeWheeler \mapsto Vehicle, Wheel \mapsto Part\}, \\ &\quad \{HasWheels \mapsto HasParts\}) \\ m_{10} &= (\{CPair \mapsto Composite, Wheel \mapsto Part, Bicycle \mapsto Vehicle, X \mapsto Part, Y \mapsto Part\}, \\ &\quad \{CPair_fst \mapsto HasParts, CPair_snd \mapsto HasParts\}) \\ m_{11} &= (\{CPair \mapsto Composite, Wheel \mapsto Part, Bicycle \mapsto Vehicle, Car \mapsto Vehicle, \\ &\quad SideMirror \mapsto Part, X \mapsto Part, Y \mapsto Part\}, \{CPair_fst \mapsto HasParts, CPair_snd \mapsto HasParts\}) \end{aligned}$$

The FRAGMENTA tool deemed the validity of all ten morphisms above.

3.2.7 Refinement. SG vertical refinement, FRAGMENTA's multilevel modelling underpinning, is built on top of SG morphisms, used to relate elements of refined (or concrete) and abstract SGs. FRAGMENTA's refinement principles are: (i) the abstract model sets a base model which refinements are required to comply to; (ii) refinements add detail and are allowed to restrict the abstract model. A subset relation underpins FRAGMENTA refinement; the abstract SG defines a multitude of information structures and their relations, of which refinements are subsets. This can be stated mathematically; given a function $\mathcal{M}$, which yields the meaning of a SG as the set of all possible SG instances, and concrete and abstract SGs, SG_c and SG_a , respectively, and a morphism f , then SG_c refines SG_a whenever $\mathcal{M} \circ f(SG_c) \subseteq \mathcal{M}(SG_a)$.

The two facets of FRAGMENTA models, decomposed (or fragmented) and composed, yield two refinement notions: *partial* and *total*. Partial refinement applies to fragments or partial SGs. Total refinement applies to monolithic or composed models with one sole fragment.

A concrete $SG_c : SGr$ partially refines a more abstract $SG_a : SGr$ via a morphism $m : GrM$, written $(SG_c, m) \sqsupseteq^{SG} SG_a$ (def. 23), whenever the conditions depicted in Fig. 9 (summarised in Fig. 9d) are met: (i) m is a valid morphism –

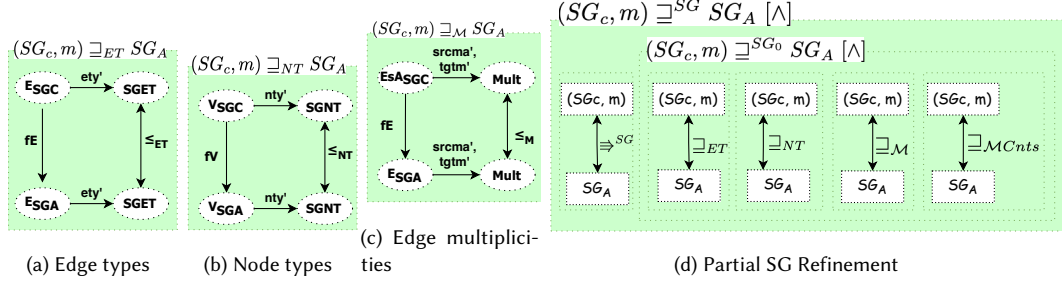


Fig. 9. Partial refinement of SGs ($\sqsupseteq_{MCnts}$ is not described graphically).

$m \in SG_c \rightarrow_{SG} SG_a$ or $(SG_c, m) \Rightarrow^{SG} SG_a^{11}$; (ii) SG_c edges are refinement-compatible with their corresponding SG_a edges as per $\leq_{ET}$ of def. 13 (Fig. 9a); (iii) SG_c nodes are refinement-compatible with their SG_a counter-parts as per $\leq_{rNT}$ of def. 13 (Fig. 9b); and (iv) multiplicities of SG_c 's association edges comply with SG_a 's to ensure that refined multiplicities (a) can only be narrowed (Fig. 9c), and (b) comply to the multiplicities of SG_a 's derived edges.

Total refinement (def. 26), written $(SG_c, m) \sqsupseteq^{SG} SG_a$, requires that: (i) m is a valid SG morphism, (ii) the conditions of partial refinement are met — $(SG_c, m) \sqsupseteq^{SG_0} SG_a^{12}$ —, (iii) SG_a 's association edges are refined adequately in SG_c — $(SG_c, m) \sqsupseteq_{Aes} SG_a$ —, and (iv) all normal nodes are refined — $m \sqsupseteq_{ANNS} SG_a$. Partial refinement is weaker than total refinement: $(SG_c, m) \sqsupseteq^{SG} SG_a \Rightarrow (SG_c, m) \sqsupseteq^{SG} SG_a$.

The following refinement results were confirmed in FRAGMENTA's tool:

- In SG_PVO (Fig. 7a), and SG_EC and SG_PV (Fig. 7b), given morphisms m_1, m_2, m_3 and m_4 defined above: $(SG_PV, m_1) \sqsupseteq^{SG} SG_PVO$ and $(SG_EC, m_2) \sqsupseteq^{SG} SG_PVO$ — both partial refinements only because normal node **Other** is not mapped to —, $(SG_EC, m_3) \sqsupseteq^{SG} SG_PVO$ — only partial because normal nodes **Person** and **Vehicle** are not mapped to (it would be total if these nodes were abstract in SG_PV) —, and $(SG_PV, m_4) \sqsupseteq^{SG} SG_EC$.
- SG_PGC and SG_PVI (Fig. 7c) partially refine SG_PVO (Fig. 7a): $(SG_PGC, m_5) \sqsupseteq^{SG} SG_PVO$ and $(SG_PVI, m_6) \sqsupseteq^{SG} SG_PVO$, but their union (Fig. 7c) is a total refinement: $(SG_PGC \cup_{SG} SG_PVI, m_7) \sqsupseteq^{SG} SG_PVO$.
- In Figs. 7d to 7g, we have that $(SG_VWs, m_8), (SG_Bi, m_9), (SG_C_Bi, m_{10}) \sqsupseteq^{SG} SG_VP$. SG_C_Bi (Fig. 7g) depicts a valid refinement of SG_VP (Fig. 7d), adding an association between **Bicycle** and **Car** would invalidate the refinement.

3.2.8 Typing. Concerned with how instances conform to their types, typing, like refinement, builds upon graph morphisms to map instances to their types. Figures 10a to 10c provide examples of graphs typed by SGs.

A morphism $m : GrM$ from a graph $G : Gr$ to a $SG : SGr$, written $m \in G \rightarrow_{G2SG} SG$, is a pair of functions $m = (fv, fe)$ such that (def. 28): (i) $fv \in Ns_G \rightarrow Ns_{SG}$, (ii) $fe \in Es_G \rightarrow Es_{SG}$ (only SG association edges are allowed as edge types), (iii) $fv \circ src_G \subseteq src^*_{SG} \circ fe$, and (iv) $fv \circ tgt_G \subseteq tgt^*_{SG} \circ fe$. The last two equations recast base graph commuting (depicted in Fig. 5b) into subset commuting to account for inheritance in the SG. All G-to-SG morphisms of Fig. 10 are valid (confirmed by the FRAGMENTA tool), except Fig. 10e, which breaches commuting; not all of them are well-typed.

A graph with typing $GwT : GrwT$ (def. 11), a pair made-up of graph $G : Gr$ and graph morphism $m : GrM$, complies with its type $SG : SGr$, written $GwT \sqsupseteq^{SG} SG$ (def. 30), provided: (i) $m \in G \rightarrow_{G2SG} SG$ (or $GwT \Rightarrow^{GwT} SG$); (ii) GwT

¹¹Relation $\Rightarrow^{SG}$ (def. 22) says that two SGs are related through a morphism: $(SG_c, m) \Rightarrow^{SG} SG_a \Leftrightarrow m \in SG_c \rightarrow_{SG} SG_a$

¹²Relation $\sqsupseteq^{SG_0}$ (def. 23) captures the conditions associated with partial refinement (see above).

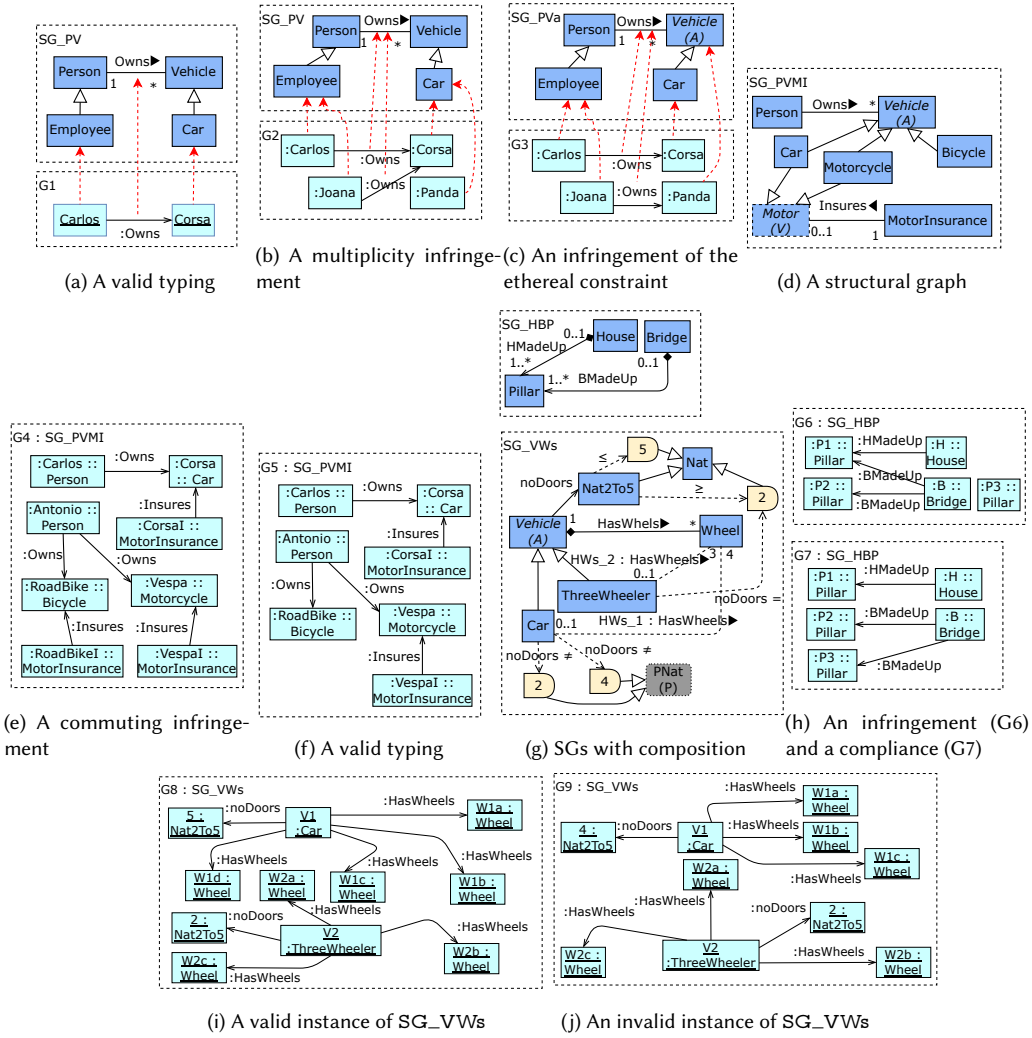


Fig. 10. Graphs typed by SGs

complies with the multiplicity constraints of its type ($GwT \models_M SG$); (iii) GwT does not contain instances of ethereal nodes (either abstract, virtual or enumeration), written $GwT \models_{FI} SG$; and (iv) GwT lacks parts shared among instances of the same compound ($GwT \models_{PNS} SG$).

Typed graphs of Fig. 10 have the following correctness results (checked by FRAGMENTA's tool):

- $G1$ in Fig. 10a is well-typed. Fig. 10b's $G2$ breaches multiplicity twice: (i) *Corsa* has two owners, (ii) *Panda* has none. $G3$ in Fig. 10c includes an instance of an abstract SG node.
- $G4$ in Fig. 10e is a mistyping of Fig. 10d — commuting is infringed, bicycles cannot have motor insurances. Figure 10f's $G5$, on the other hand, is a valid instance.

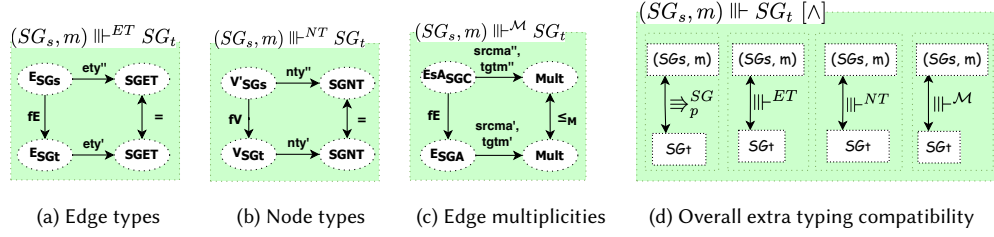


Fig. 11. Extra typing compatibility at the level of SGs.

- In Fig. 10h, G6 is a mistype of SG_HBP (Fig. 10g) – composition is infringed as node P1 is shared by compounds H and B. G7, on the other hand, is well-typed.
- Figure 10i is a valid type of SG_VWs of Fig. 10g, unlike Fig. 10j which infringes: the multiplicity constraint of the derived edge (a car must have four wheels) and the value constraint edge of Car (a car must not have 4 doors).

3.2.9 Extra Typing. Certain situations call for extra typing, where a portion of some graph is required to comply with a portion of another graph. An extra typing could be built by considering that SG_PVMI (Fig.10d) would have extra typing into SG_PV (Fig.10a) by mapping the nodes Car and Person and edge Owns into Car, Employee and Owns, respectively, effectively saying that instances of Person in SG_PVMI are instances of Employee in SG_PV.

This is handled by extra type compliance and the associated notion of extra-type compatibility. Given SGs $SG_1, SG_2 : SGr$, SG_1 is extra-type compatible with SG_2 via the morphism m , written $(SG_1, m) \dashv\vdash^{SG} SG_2$ (def 31), provided several conditions, described in Fig. 11 (summarised in Fig. 11d), are met: (i) m is a partial morphism from SG_1 to SG_2 , (ii) the multiplicities of SG_1 's mapped edges comply to the multiplicities of corresponding SG_2 's edges (source multiplicities can only be narrowed) (Fig. 11c), (iii) the types of SG_1 's mapped nodes and edges are the same as their SG_2 counterparts (Figs. 11a and 11b). The next section develops extra typing further.

3.3 Fragments

Fragments provide referencing, either intra- or inter-fragments, by stipulating the nodes proxies refer to (or represent), called referents. In addition, fragments may stipulate the extra typing of certain elements which may be allowed to have types in another graph outside the stipulated metamodel.

A fragment (Fig. 12a, def. 32) is a quintuple $F = (SG, esr, sr, tr, et)$, comprising: (i) a $SG : SGr$ (def. 17), (ii) a set of reference edges, $esr \subseteq E$, disjoint from the edges of the inner SG – $esr \cap Es SG = \emptyset$ –, (iii) functions $sr : esr \rightarrow NsP SG$ (bijective) and (iv) $tr : esr \rightarrow V$, which give source and target of reference edges, respectively, where tr gives nodes proxies refer to, and (v) extra-typing partial morphism et , where $domg et \subseteq_p (NsN SG, EsA SG)$. Figures 12b to 12f illustrate fragments, with referencing depicted as double-arrows; in Fig. 12b, proxy PFeline refers to its homonym.

Projection functions $fSG, EsR, srcR, tgtR$ and fet (def. 32) extract the inner elements of a fragment – e.g. $fSG(SG, esr, sr, tr, et) = SG$. Other fragment functions include (def. 32): (i) $fEs F$ yields all edges of fragment F (all of SG plus reference edges), (ii) $fLN F$ gives local nodes of F (those of embedded SG), (iii) $fNs F$ gives all nodes involved in F (local plus foreign nodes), and (iv) $srcF$ and $tgtF$ give the source and target functions which cater for all edges, including reference edges. In Fig. 12b, $fLN F_1$ yields all nodes included in the fragment; $fNs F_1$ also yields *Feline* of F_2 . Function $\overset{G}{\rightsquigarrow}$ (def. 32) builds

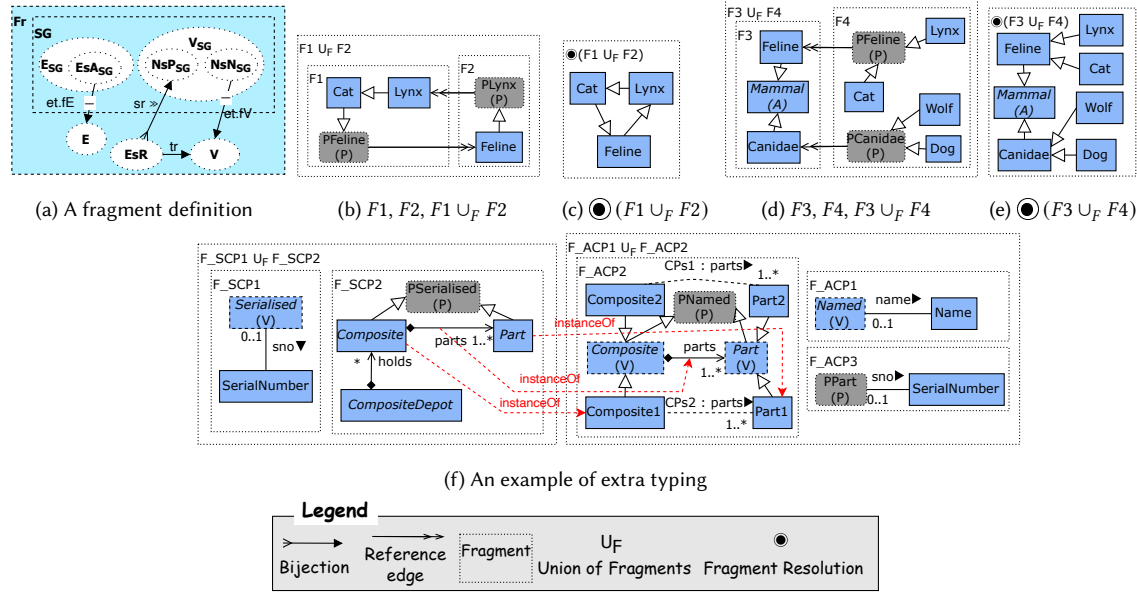


Fig. 12. Fragment-related drawings depicting the mathematical definition (a), and several illustrations, namely: a circular fragmentation (b) and its resolution (c), an healthy fragmentation (d) with its inheritance-acyclic resolution (e), two fragment collections related with an extra typing (f)

the references graph made-up of proxies connected to their referents, the basis of $\leftrightarrow$ (def. 32), a function that gives the referent of a given proxy — in Fig. 12d, $\leftrightarrow_{F_3 \cup_F F_4} PFeline = Feline$.

Fragment union $\cup_F$ (def. 33), illustrated in Figs. 12b and 12d with fragments $F_1 \cup_F F_2$ and $F_3 \cup_F F_4$, respectively, joins the contents of fragments. Fragment resolution $\odot$ (def. 34), founded on graph subsumption (defined for graphs in section 3.1 and SGs in section 3.2), replaces proxies by their referents. Figure 12c gives $\odot(F_1 \cup_F F_2)$ which resolves the fragment of Fig. 12b; Fig. 12e depicts $\odot(F_3 \cup_F F_4)$ which resolves the fragment of Fig. 12d.

Fragments are grounded on the following definitions:

- Set Fr_a (def. 35), of fragments with acyclic references. All examples of Fig. 12 are reference-acyclic.
- Set of partial fragments Fr includes all reference-acyclic fragments whose resolved encapsulated SGs are partial, which implies that inheritance graphs of resolved SGs are acyclic (def. 35). In Fig. 12b, although $F_1 \in Fr$ and $F_2 \in Fr$, we have that $F_1 \cup_F F_2 \notin Fr$ — $\odot(F_1 \cup_F F_2)$ (depicted in Fig. 12c) has an inheritance cycle.
- Set of total fragments TFr includes all acyclic fragments whose internally resolved SGs are total (def. 36). The individual component fragments F_3 and F_4 of Fig. 12d are partial; $F_3 \cup_F F_4$ is total because (i) all proxy references are local and (ii) the resolved SG (Fig. 12e) is total.

An important law proved in [7], says that the union of two partial fragments is well-formed provided: (i) the individual fragments are well-formed, (ii) mutually disjoint and (iii) the references between them only go one way (def. 35). In Fig. 12b, the two individual fragments are well-formed, but not compliant to the union law as they reference each other. The two fragments of Fig. 12d are both well-formed and compliant to the union law.

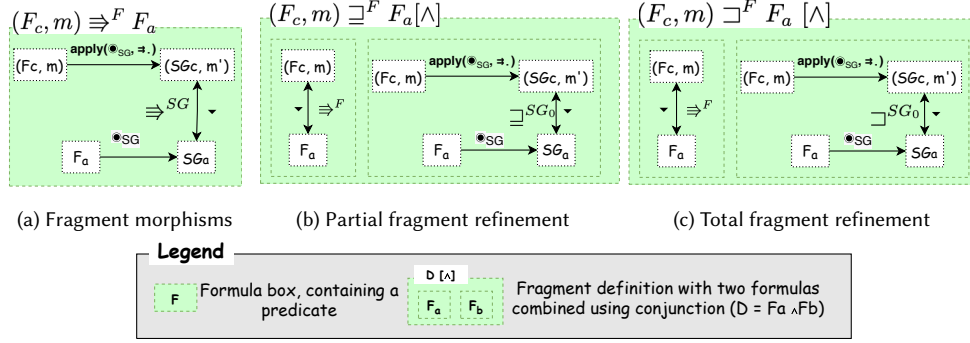


Fig. 13. Definitions of morphisms and refinements for fragments

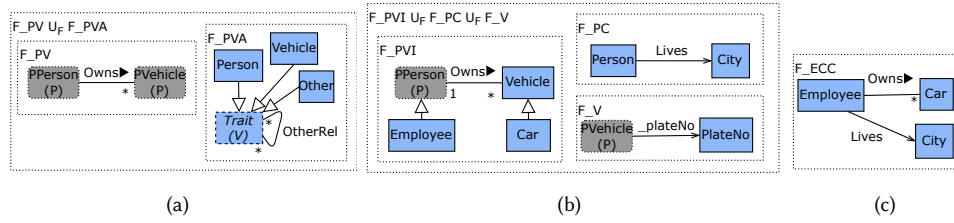


Fig. 14. Fragments and their possible refinements

3.3.1 Morphisms and Refinement. Figure 13 depicts the definitions of morphisms and refinements for fragments. A morphism $m : GrM$ between $F_c, F_a : Fr$, written $m \in F_c \rightarrow_F F_a$ or $(F_c, m) \Rightarrow^F F_a$ (Fig. 13a), is equivalent to a morphism between the resolved SGs encapsulated in the fragments. Fragment refinement is built on top of morphisms: a fragment F_c partially refines a fragment F_a through a morphism m , written $(F_c, m) \sqsubseteq^F F_a$, if the SGs resulting from resolving the fragments are in a partial refinement relation through the resolved morphism m (def. 38, depicted in formula box of Fig. 13b). Total fragment refinement (symbol $\sqsupset^F$, def. 39) requires the fragments to be total and the resolved SGs to be in a total refinement relation as depicted in Fig. 13c.

The following morphisms apply to Fig. 14: $m_1 : F_PVI \rightarrow_F F_PV$, $m_2 : F_PC \rightarrow_F F_PVA$, $m_3 : F_V \rightarrow_F F_PVA$, $m_4 : F_PVI \cup_F F_PC \cup_F F_V \rightarrow_F F_PV \cup_F F_PVA$ and $m_5 : F_ECC \rightarrow_F F_PV \cup_F F_PVA$, which are defined as:

$$\begin{aligned}
 m_1 &= (\{PPerson, Employee \mapsto PPerson, Car, Vehicle \mapsto PVehicle\}, \{Owns \mapsto Owns\}) \\
 m_2 &= (\{Person \mapsto Person, City \mapsto Other\}, \{Lives \mapsto OtherRel\}) \\
 m_3 &= (\{PVehicle \mapsto Vehicle, PlateNo \mapsto Other\}, \{Vehicle_plateNo \mapsto OtherRel\}) \\
 m_4 &= m_1 \cup_{GM} m_2 \cup_{GM} m_3 \\
 m_5 &= (\{Employee \mapsto Person, Car \mapsto Vehicle, City \mapsto Other\}, \{Owns \mapsto Owns, Lives \mapsto OtherRel\})
 \end{aligned}$$

The following was verified in the FRAGMENTA tool:

- $(F_PVI, m_1) \sqsubseteq^F F_PV$
- $(F_PC, m_2) \sqsubseteq^F F_PVA$ and $(F_V, m_3) \sqsubseteq^F F_PVA$
- $(F_PVI \cup_F F_PC \cup_F F_V, m_4) \sqsupset^F F_PV \cup_F F_PVA$
- $(F_ECC, m_5) \sqsupset^F F_PV \cup_F F_PVA$

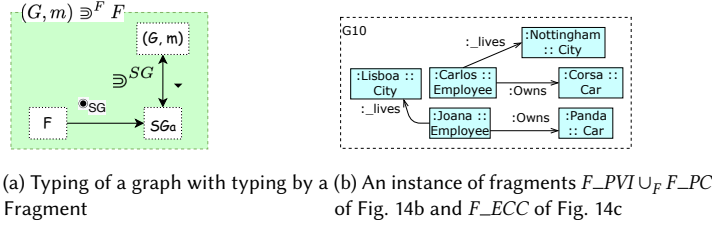


Fig. 15. Fragments as Types: definition (a) and an illustration (b).

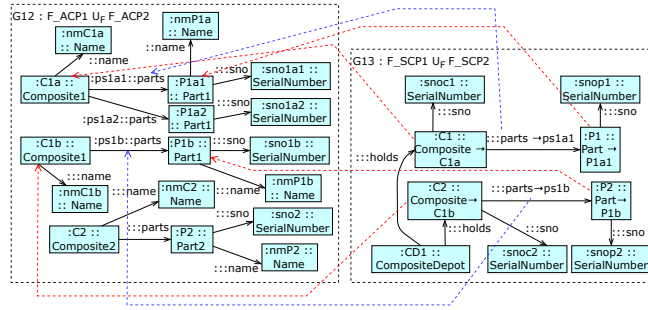


Fig. 16. Graph instances and extra typing.

3.3.2 Fragments as Types. SG typing (section 3.2.8) is extended to fragments. A graph with typing $GwT : GrwT$ (def. 11), a pair made-up of a graph $G : Gr$ and graph morphism $m : GrM$, complies with a fragment $F : Fr$, written $GwT \models^F F$, provided GwT complies with the SG resulting from resolving F as depicted in Fig. 15a (def 40). Figure 15b depicts a graph with typing $G10$ which complies with fragments $F_{PVI} \cup_F F_{PC}$ of Fig. 14b and F_{ECC} of Fig. 14c — $G10 \models^F F_{PVI} \cup_F F_{PC}$ and $G10 \models^F F_{ECC}$, respectively.

3.3.3 Extra Typing. Extra typing relies on a fragment's extra-type morphism, obtainable with function *fet*. A fragment $F_s : Fr$ is extra-type compatible with a fragment $F_t : Fr$, written $F_s \dashv^F F_t$, provided the SGs of the resolved fragments are extra-type compatible via F_s 's extra-type morphism (def. 41). This provides the basis for extra-typing compliance, which stipulates the conditions under which some graph with extra typing $Gwet : GrwET$ (def. 12), typed by a fragment $F_s : Fr$ (def. 32), is extra-typed by a graph with typing $Gwt : GrwT$ (def. 11), typed by a fragment $F_t : Fr$, written $(Gwet, F_s) \models^F (Gwt, F_t)$, as per def. 41, which is the case provided: (i) $Gwet$ is typed by $F_s - Gwet^{Gw} \models^F F_s -$, (ii) Gwt is typed by $F_t - Gwt \models^F F_t -$, (iii) the domain of $Gwet$'s extra typing morphism is consistent with F_s 's extra typing morphism, (iv) $Gwet$'s extra typing morphism is a partial morphism from $Gwet$ to Gwt , (v) F_s is extra-type compatible with $F_t - F_s \dashv^F F_t$.

Extra typing compatibility can be checked for the example of Fig. 12f, to establish that $F_{SCP2} \dashv^F F_{ACP2}$ and $F_{SCP1} \cup_F F_{SCP2} \dashv^F F_{ACP1} \cup_F F_{ACP2}$. It is also possible to check the overall extra typing compliance of Fig. 16 where: $(G13, F_{SCP1} \cup_F F_{SCP2}) \models^F (G12, F_{ACP1} \cup_F F_{ACP2})$. These checks were carried out in the FRAGMENTA tool.

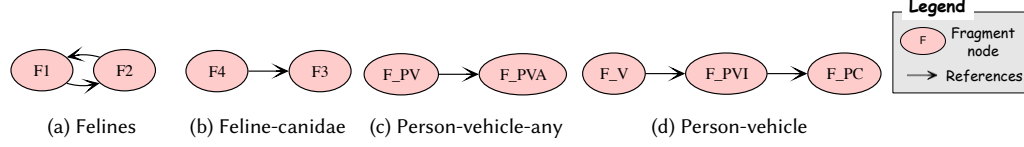


Fig. 17. Global Fragment Graphs (GFG)

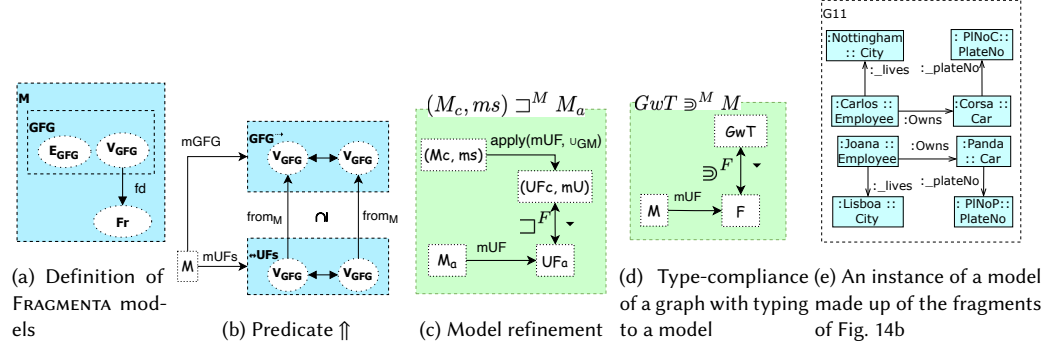


Fig. 18. FRAGMENTA Models, their refinement and typing

3.4 Global Fragment Graphs (GFGs)

GFGs say how fragments reference one another. A fragment A references fragment B when a proxy of A refers to either a node from B , or from the fragments referenced by B as per transitivity. GFGs dictate the permitted referencing flows of local fragments.

A GFG is a graph, $GFG : Gr$ (def. 42), where nodes represent fragments, and edges indicate the referencing flows. Set GFG_r (def. 42) of all well-formed GFGs includes those GFGs which, after the removal of the identity (or self) edges, are acyclic.

Relation $\rightsquigarrow$ (def. 42) gives all fragments referenced by a particular fragment; it is defined as the transitive closure of the relation obtained from the GFG: $GFG \rightsquigarrow = (GFG \leftrightarrow)^+$

Figure 17 gives examples of GFGs:

- Figure 17a captures the felines example of Fig. 12b; it depicts a malformed GFG with a disallowed cycle.
- Figure 17b, a well-formed GFG, captures the example of Fig. 12d.
- Figures 17c and 17d portray the fragment-referencing of Figs. 14a and 14b, respectively.

3.5 Models

Models hold their constituting fragments, usually inter-related to be meaningful as a whole. Depicted in Fig. 18a, a model is a pair (GFG, fd) , comprising a $GFG : GFG_r$ (def. 42) and a function $fd : Ns_{GFG} \rightarrow Fr$ which maps nodes representing fragments to their definitions (def. 43). The set of base models, Mdl_0 , comprises all models with valid GFGs and mutually disjoint fragments (def. 43). Function $mUFs$ builds the union of all the fragments of a model, and $from$ gives the fragment provenance of any model node (def. 43). Predicate $\uparrow$ (def. 43) says whether the referencing embedded in the model's fragments complies with the model's GFG by resorting to function $from$ and relation $\rightsquigarrow$, depicted as

commuting in Fig. 18b (the commuting equation is shortened to an equation with quantifiers in def. 43). Set Mdl of well-formed models (def. 43) includes all those base models (set Mdl_0) whose union of fragments is a total fragment and whose fragments' referencing complies with the model's GFG (as per $\uparrow$). Finally, operator $\odot^M$ (def. 43) gives the fragment resulting from resolving the union of the fragments of a model.

Many of the examples explored so far can now be framed as models:

- The abstract hotel world model made-up of Fig. 1 is well-formed.
- The pets world model of Fig. 2 is well-formed. Saying in the GFG that fragment F_PW1 references F_PW2 instead, would make the model malformed – the GFG would misrepresent the underlying referencing.
- A model made-up of the GFG of Fig. 17a and fragments F1 and F2 of Fig. 12b would be malformed, as the GFG contains a cycle. Removing the cycle in the GFG would not resolve this issue as the GFG would diverge from the underlying referencing.
- A model made-up of the GFG of Fig. 17b and fragments F3 and F4 of Fig. 12d would be well-formed. Making F3 reference F4 in the GFG would misrepresent the referencing flow.
- The model with GFG of Fig. 17c with fragments of Fig. 14a is well-formed. Likewise, for the model with GFG of Fig. 17d and fragments of Fig. 14b.

3.5.1 Morphisms and Refinement. Model morphisms are defined from fragment morphisms through the union of morphism. A model morphism m between models $M_s, M_t : Mdl$, written $m \in M_s \rightarrow_M M_t$, maps elements from the union of fragments of M_s onto the union of fragments of M_t (def. 44). Because model morphisms are usually a collection of morphisms defined for each fragment of the source model, we say that a model $M_s : Mdl$ and a set of morphisms $ms : \mathbf{P} GrM$, are morphism-related to another model $M_t : Mdl$, written $(M_s, ms) \Rightarrow^M M_t$, when the union of the morphisms in ms is a model morphism from M_s to M_t as per def. 44. Model refinement is defined similarly in terms of total fragment refinement (def. 45, pictured in Fig. 18c); a model $M_c : Mdl$ refines another model $M_a : Mdl$ via the morphisms $ms : \mathbf{P} GrM$, written $(M_c, ms) \sqsupset^M M_a$, if the union of fragments of M_c refines the union of fragments of M_a via the union of morphisms of $ms - (mUFs M_c, \bigcup_{GM} ms) \sqsupset^F mUFs M_a$.

The refinement examples explored so far can now be framed as models:

- The pets world concrete model of Fig. 2 is a model refinement of the abstract hotel model of Fig. 1 through the morphisms of Fig. 3.
- The model made-up of the GFG of Fig. 17d and the fragments of Fig. 14b is a refinement of the model made-up of the GFG of Fig. 17c and the fragments of Fig. 14a, through morphism m_4 of section 3.3.1.

3.5.2 Models as Types. Fragment typing is extended to model typing through the union of fragments. A graph with typing $GwT : GrwT$ (def. 11) complies with a model $M : Mdl$ – written $GwT \ni^M M$ – provided the GwT complies with the union of the model's fragments depicted in Fig. 18d (def. 46). The graph of Fig. 4 is an instance of (or is type-compliant with) the pets world concrete model of Fig. 2. The graph of Fig. 18e is an instance of the person-vehicle model made-up of the GFG of Fig. 17d and the fragments of Fig. 14b.

Extra-typing works in a similar fashion: extra-typing at the level of models reduces to extra-typing at the level of fragments by reducing models to the union of their fragments (def. 47). Two models, M_ACP and M_SCP , can be built from the fragments of Fig. 12f, where $M_SCP \dashv_M M_ACP$. For the two graphs of Fig. 12f, we have that $(G10, M_SCP) \models^M (G11, M_ACP)$.

meta) and instance. The type stratum includes the abstract model of Fig. 19a (the meta-layer) and its more concrete refinement of Fig. 19b (the type layer). The instance stratum includes Figs. 19c and 19d. The models that make the type stratum are divided in fragments which build upon each other as per their respective GFGs.

The abstract model layer (Fig. 19a) introduces three fragments: (i) *F_NF* says that *Nat* (natural numbers) is a *Feature*, which is a virtual; (ii) *F_P* defines *Percentages*; (iii) *F_AP* says that *Products* have a *price* in some currency and a value added tax (*vat*) *Percentage*, and are *Features*, which may have several attributes (*virtual traits* pattern), and introduces *OtherF* to represent a feature other than *Nat* and *Product*.

The concrete model layer (Fig. 19b), with its six fragments, is as follows:

- Fragment *F_BTs* introduces nodes *Nat*, *Nat_1*, defined from *Nat* to represent the strictly positive natural numbers, *Name* and *Country*, and the virtuals *Named* and *National*. In terms of the mapping to Fig. 19a, all *Nat*-related nodes are mapped to *Nat*, *Named* and *National* to *Feature* and all others to *OtherF*.
- Fragment *F_P* refers to the homonymous of Fig. 19a (same fragment is used in both layers). In the mapping, *Percentage* is mapped to itself, and the remaining nodes to *Nat*.
- Fragment *F_E* defines the Euro currency. In the mapping, *Euro* is mapped to *Currency*, and the remaining nodes to *Nat*.
- Fragment *F_PP* defines the abstract *Product*, made-up of a *vat Percentage*, a Euro *price*, and a *unit*, either kilograms, grams, pieces, millilitres and litres, and the *Volume* virtual a disjoint union of millilitres and litres. In the mapping, *Product* is mapped to its homonymous, *Unit* and its values to *OtherF*, *Volume* to *Feature*, and the proxies are mapped as their referents.
- Fragment *F_PB* introduces *Books* (a product), which have a *year*, *authors*, *publisher*, a 10%*vat* and sold as pieces. In the mapping, *Book* is mapped to *Product*, and *Publisher* and *Author* to *OtherF*.
- Fragment *F_PF* introduces *Food*, categorised according to the *FoodGroup* enumeration as either fruit or vegetable, starchy food (such as potatoes and cereals), dairy, fat (such as olive oil) and protein (such as meat, fish and beans), and with a *vat* of 4% and sold as pieces. In the mapping, *Food* is mapped to *Product*, and *FoodGroup* and its values to *OtherF*.
- Fragment *F_Be* introduces the abstract *Beverage*, a product sold in volume units, sub-divided into *Alcoholic* with a *vat* of 20/% and *NonAlcoholic* with a *vat* of 7%. In the mapping, *Beverage*, *Alcoholic* and *NonAlcoholic* are mapped to *Product*.
- Fragment *F_PS* introduces *Shoe*, a product with a *brand*, a *vat* of 20/%, a shoe *size*, a targeted age group and gender. In the mapping, *Shoe* is mapped to *Product*, and *AgeGroup* and its values, and *Gender* and its values to *OtherF*.
- The refinement to the abstract layer has been checked in the FRAGMENTA tool.

Figures 19c and 19d, both instances of Fig. 19b, illustrate the instance layer. They both define the book *bBD*, the food item *fB*, the non-alcoholic beverage *bGW*, and the shoe *sNB*. Figure 19c is a valid instance. Figure 19d breaches several metamodel constraints: (i) *bBD*'s unit is litres, (ii) author *aFP* is countryless, (iii) *fB*'s *vat* is negative, (iv) *fB* and *bGW* have both kilogram units, (v) *sNB*'s size 18 is below the minimum allowed, and (vi) the price of *bGW* is 0 euros and 118 cents, which breaches the euro cents constraint.

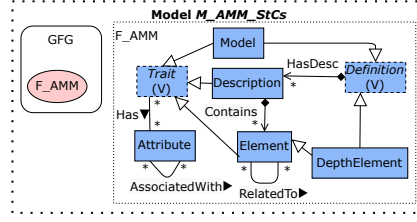


Fig. 20. Abstract layer of the FRAGMENTA metamodel of statecharts.

5 A LAYERED DEFINITION OF STATECHARTS

The metamodel of statecharts (StCs) [33] is modelled in FRAGMENTA. The sequel presents abstract and concrete layers of StCs' metamodel, illustrated and exercised through instances.

5.1 The Abstract Layer

The abstract metamodel (Fig. 20) is made up of a single fragment:

- Definitions (virtuals) are defined in terms of Descriptions, which contain Elements. Models and DepthElements are Definitions.
- Elements are related to other elements (edge RelatedTo) to capture horizontality. DepthElements (Elements with depth), captures verticality or depth.
- Models, Elements and Descriptions are Traits (a virtual node) which may have Attributes that may be inter-related.

5.2 The Concrete Layer

The concrete metamodel (Fig. 21) is made-up of the following fragments inter-related as per GFG:

- F_MM1: Statechart definitions (virtual StCDef) contain descriptions (StCDesc), made-up of Elements (abstract). A StCModel is a StCDef. StC models and descriptions are Named, a virtual. In the mapping into Fig. 20, StCModel is mapped to Model, StCDesc to Description, StCDef to Definition, Element to Element, Named to Trait, Name to Attribute, HasDesc to HasDesc, Contains to Contains and Named_name to Has.
- F_MM2: Abstract States are Elements, sub-divided into StartStates, EndStates, HistoryStates, and MutableStates, which are named and inherit StCDef to allow depth. In terms of Fig. 20, all states are mapped to Element, except MutableState which is mapped to DepthElement; proxies are mapped like their referents.
- F_MM3 constrains StC descriptions through derived edges to say that descriptions contain one StartState, and may contain one EndState and one HistoryState.
- F_MM4: Transitions are elements made up of one source and one target States. They may have an Event, a Guard and an Action. Virtual WExp represents something made up of an expression, such as Events, Guards and Actions. With respect to the mapping into Fig. 20, Transition maps to Element, and all other non-proxies to Attribute.
- F_MM5 constrains the way transitions are related to start, end and history states. Transitions must not have init nodes as targets, and end nodes as sources; start states must be the source state of at least one transition;

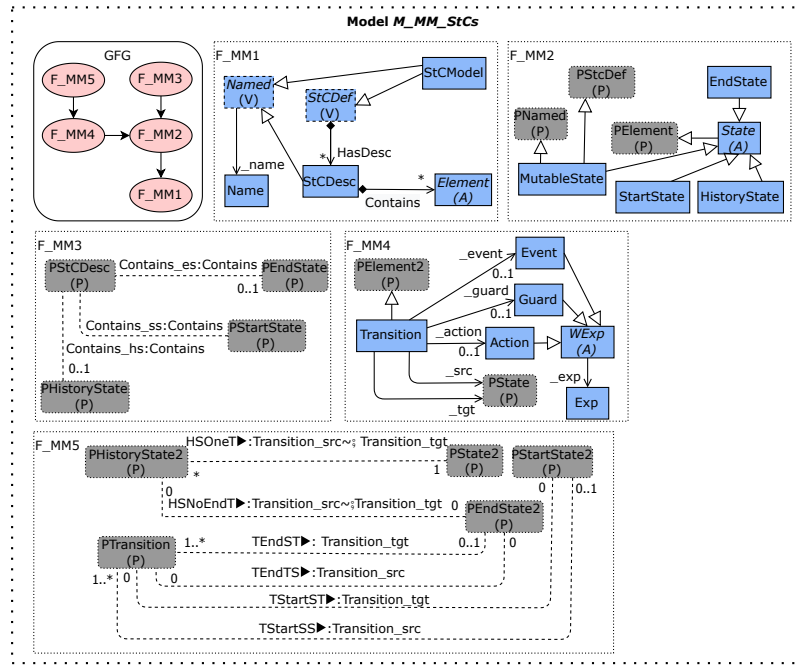


Fig. 21. FRAGMENTA model capturing the concrete layer of StCs' metamodel.

end states must be targets of at least one transition; history states must have one transition into one other state, which must not be an end state.

5.3 Illustrations

The StCs of Fig. 22 were compliance-checked against the metamodel (Fig. 21) by FRAGMENTA's tool:

- Figure 22a complies with the metamodel. Glands, initially idle, secrete hormones when triggered by the environment, and die upon receiving the apoptosis (or cell-death) signal.
- Figure 22b describes a resuscitating gland, an invalid metamodel instance that breaches a constraint of F_MM5 which rules out end states with outgoing transitions.
- Figure 22c, a valid StC with one definition and two descriptions, describes a buzzer with two different tones. The top description says that an initially muted buzzer goes from Muted to Buzzing upon event buzz, and back after 3 seconds triggering mute. In the bottom description: (i) the buzzer emits a happy tone (state Happy), changeable to an angry one (state Angry) and back upon chSound, contingent on the buzzer being Muted; (ii) the history state H marks the most recently visited state (Happy by default).
- Figure 22d, a variant of Fig. 22c, breaches several constraints: (i) the top description lacks an initial state (see F_MM3); (ii) the bottom description violates two F_MM5 rules: history states must have incoming transitions, and initial states must not have incoming transitions. In Fig. 22c, removing the transition from the history state, would breach the constraint of derived edge HSONeT, saying that history states must have one outgoing transition.

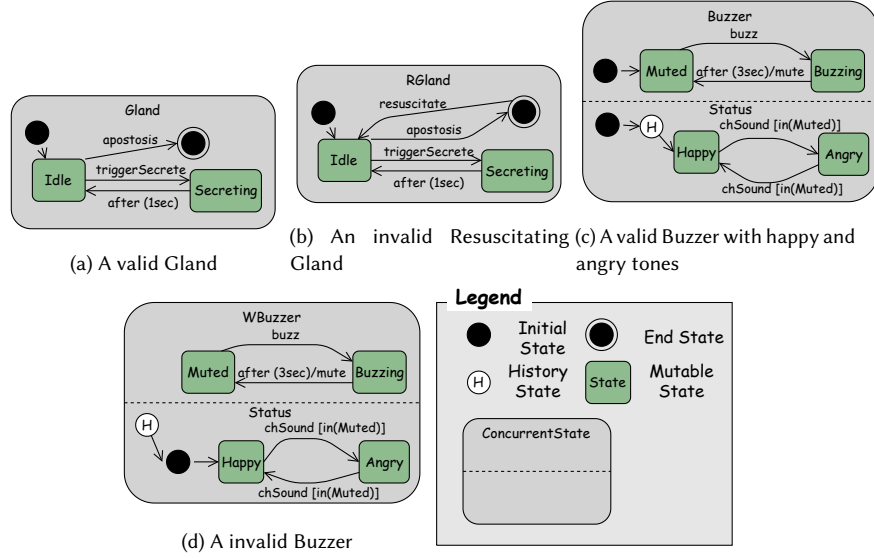


Fig. 22. Example Statecharts

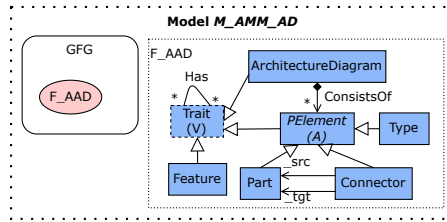


Fig. 23. FRAGMENTA metamodel of the abstract architecture diagrams of the Into-SysML profile.

6 INTO-SYSML: A SYSML PROFILE FOR CYBER-PHYSICAL SYSTEMS

FRAGMENTA is applied to *INTO-SysML*, a SysML [23, 52] profile for cyber-physical systems [10, 11]. The metamodel, previously described using an early version of FRAGMENTA, is described herein as a FRAGMENTA layered model. The abstract layer (section 6.1) captures general architectural models; it is refined by two concrete layers: architecture structure diagrams (section 6.2) and connection diagrams (section 6.3). Section 6.4 illustrates INTO-SysML with a water tanks system.

6.1 The Abstract Layer

The abstract metamodel (Fig. 23) comprises a single fragment, *F_AAD*; it is as follows:

- An *ArchitectureDiagram* consists of primitive elements — abstract node *PElement*.
- A *PElement* can either be *Part*, a *Connector* or a *Type*. Connectors join *Parts* through edges *Connector_src* and *Connector_tgt*.

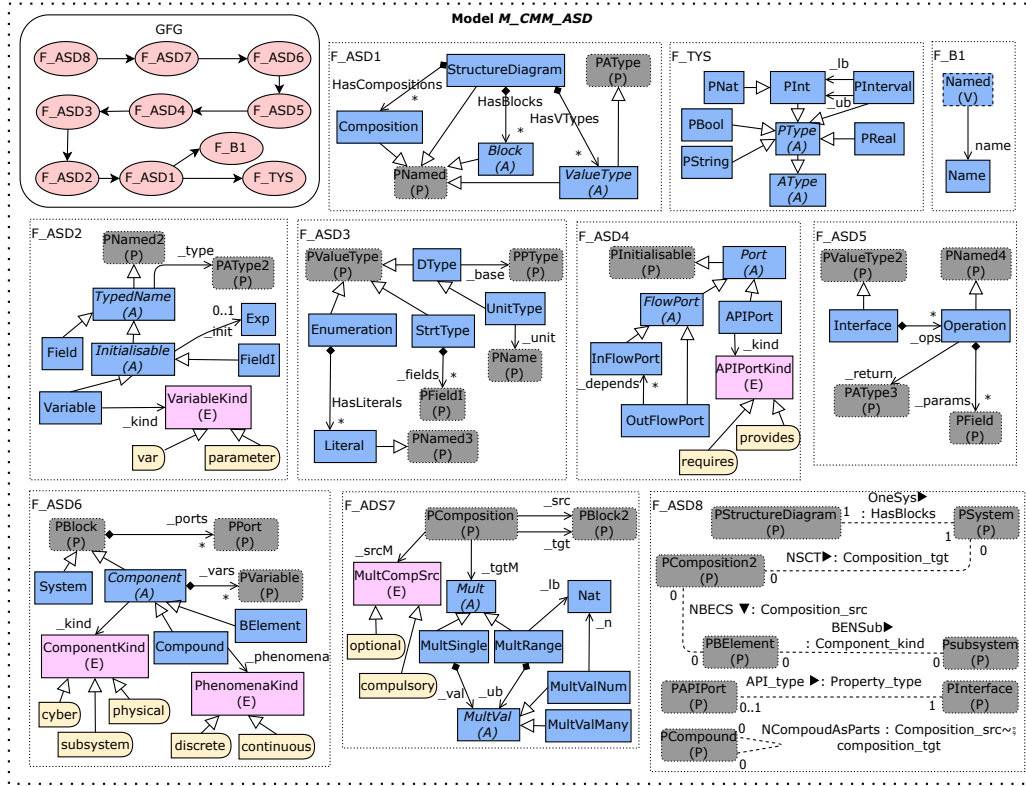


Fig. 24. FRAGMENTA metamodel of architecture structure diagrams (ASDs) of the Into-SysML profile.

- Virtual Trait represents any model element. A feature represent an extra aspect of the model. Traits are inter-relatable through edge Has (virtual traits pattern).

6.2 The Concrete Metamodel of Architecture Structure Diagrams (ASDs)

Figure 24 presents INTO-SysML’s concrete metamodel of architecture structure diagrams (ASDs), a specialisation of SysML’s block-definition diagrams. The GFG says how the model’s 10 fragments are inter-related. The fragments are as follows:

- **F_B1**: **Named**, a virtual, represents something with a **Name**. In the refinement mapping to the abstract model of Fig. 23, **Named** is mapped to **Trait**, and **Name** to **Feature**.
- **F_TYS**: Primitive types (**PTypes**) include integers (**PInt**), of which natural numbers (**PNat**) are a subset, intervals (**PInterval**) made-up of integer lower- and upper-bounds, reals, booleans and strings. A **PType** is a **AType**, which includes primitive and value-types. In the refinement mapping, all nodes are mapped to **Type**.
- **F_ASD1**: a **StructureDiagram** comprises **Block** and **ValueType** (both abstract), and **Composition**. **ValueTypes** are types – proxy **PAType** refers to **AType** of **F_TYS**. In the mapping: **StructureDiagram** is mapped to **ArchitectureDiagram**, **Block** to **Part**, and **ValueType** to **Type** – proxies are mapped like their referents.

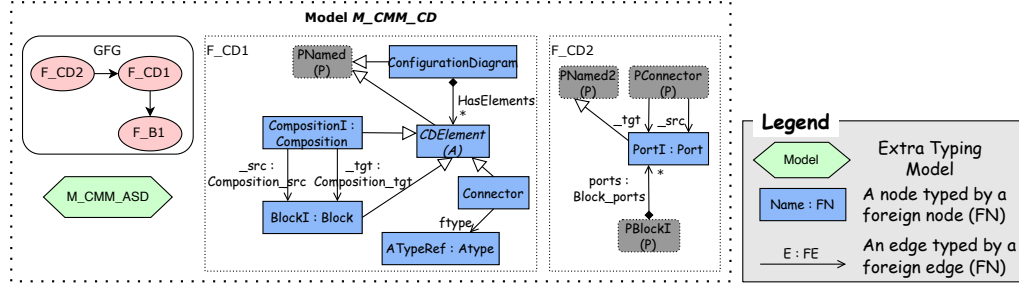


Fig. 25. FRAGMENTA metamodel of connection diagrams (CDs) of the Into-SysML profile.

- **F_ASD2:** A Field is a **TypedName** (abstract), which has a type. **Initialisable** (abstract), a **TypedName**, may have an initialisation expression. **FieldIs** and **Variables** are **Initialisables**; **Variables** may either be normal or parameters. In the mapping, **Exp**, **VariableKind**, **var** and **parameter** are mapped to **Feature**, **TypedName** and **Initialisable** to **Trait** and the two field nodes to **Part**.
- **F_ASD3:** Enumerations are value types made up of named **Literals**. Structural types (**StrtType**), also value types, are made up of initialisable fields. Derived types (**DType**), also value types, have a base, a primitive type. **UnitTypes** (such as °C or centigrades), which are **DTypes**, have a name of a unit. In the mapping, **StrtType**, **DType**, **UnitType**, **Enumeration** are mapped to **Type**, **literals** to **Feature**.
- **F_ASD4:** Ports (abstract) are initialisable and divided into **FlowPorts** and **APIPorts**. **APIPorts**' two kinds of abstract programming interfaces (APIs) are **requires** and **provides**. **FlowPorts** are further divided into in- and out-flow ports, where the latter have dependencies with the former. In the mapping, ports are mapped to **Part**, **APIPortKind**, **requires** and **provides** to **Feature**.
- **F_ASD5:** Interfaces are value types made up of **Operations**, which have a return type and parameters. In the mapping, **Interface** is mapped to **Type**, **Operation** to **Feature**.
- **F_ASD6:** A block is either a **System** or a **Component** (abstract), either of kind **cyber**, **subsystem** or **physical**, and sub-divided into **Compounds** or base elements (**BElement**). **Compounds** may handle either discrete or continuous phenomena. In the mapping, all **Block** nodes are mapped to **Part**, **ComponentKind** and **PhenomenaKind** and their children to **Feature**.
- **F_ASD7:** Compositions have a source and a target block with an optional source multiplicity, either optional or compulsory, and a target multiplicity. Multiplicities (**Mult**) can either be single (**MultSingle**) or range (**MultRange**). A **MultSingle** holds a multiplicity value, **MultVal**, either a single natural number (**MultValNum**) or just many (**MultValMany**, written *). A **MultRange** has a natural number lower bound (edge to **Nat**) and a **MultVal** upper bound. In the mapping, all multiplicity-related nodes are mapped to **Feature**.
- **F_ASD8:** The following constraints are described as derived edges: (i) a ASD must have one system block; (ii) systems may not be parts in compositions; (iii) **BElements** may neither be compounds nor subsystems; (iv) an **APIPort**'s type must be interface; and (vi) compounds may not have other compounds as parts.

6.3 The Concrete Metamodel of CDs

Figure 25 presents the concrete metamodel of CDs, which specialise SysML's internal block diagrams. CDs' metamodel imports ASDs' metamodel of Fig. 24, presented above, to provide the extra ASD types that certain CD elements require.

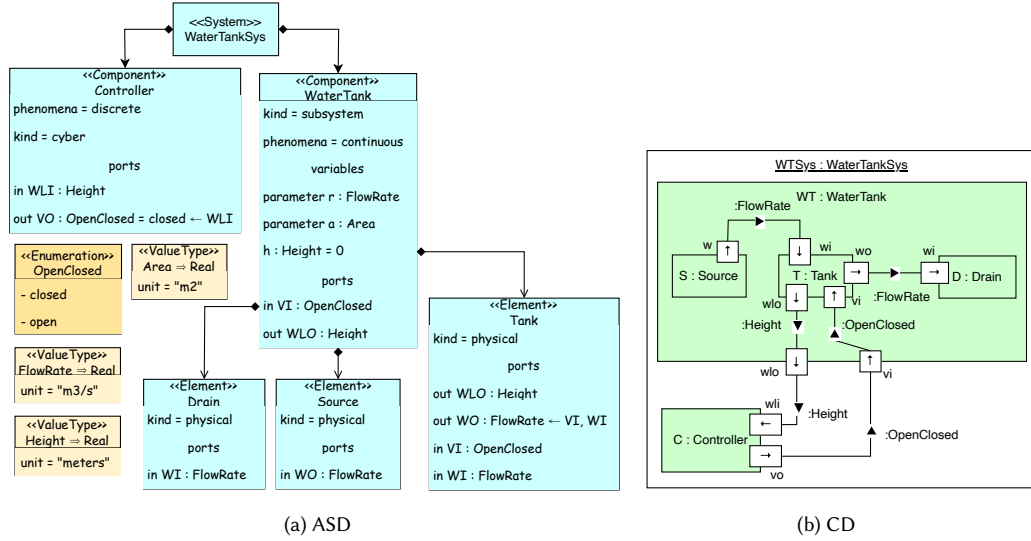


Fig. 27. Into-SysML model of the water tanks system from [11].

CDs' metamodel is made-up of three fragments (see GFG), one of which is F_B1, shared with ASDs; the other two fragments are as follows:

- **F_CD1:** ConfigurationDiagrams comprise a collection of CDElements, an instance of either composition (CompositionI) or block (BlockI), or a Connector. Extra type constraints state that BlockIs and CompositionIs are instances of ASDs' Block and Composition (Fig. 24), respectively. A CompositionI has a source and a target BlockIs (extra-typed as edges CompositionI_src and CompositionI_tgt). A Connector has a flowing type, represented by ATypeRef, extra-typed as AType. In the refinement mapping to Fig. 23, ConfigurationDiagram is mapped to ArchitectureDiagram, CDElement to PElement, CompositionI and Connector to Connector, BlockI to Part and ATypeRef to Type.
- **F_CD2:** Port instances (PortI) (port instances) are extra-typed as Port. Block instances are made up of PortIs; edge ports is extra-typed as Block_Ports — PortIs of a CD block correspond to ports of a ASD block. A Connector has a source and a target PortI. In the refinement mapping, PortI is mapped to Part.

6.4 Illustration

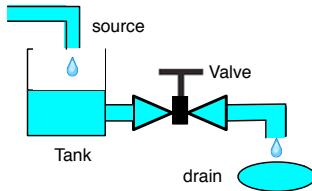


Fig. 26. Water Tanks system.

In the system of Fig. 26, a source of water fills a tank. A valve controls the outflow of water, which flows into the drain when the valve is open. A software controller opens or closes the valve depending on the tank's water level. The Into-SysML model of this simple cyber-physical system (Fig. 27) comprises one ASD (Fig. 27a) and one CD (Fig. 27b).

In the ASD (Fig. 27a), the system block comprises: Controller, a cyber component, and WaterTank, a subsystem. Controller includes: (i) input port WLI of type Height (in meters) to get a water level input from WaterTank; and (ii) valve output VO of type OpenClosed (an enumeration) to instruct the WaterTank to either

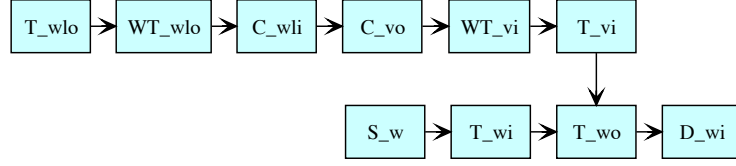


Fig. 28. Port dependency graph extracted from the Into-SysML model of water tanks (Fig. 27)

open or close the valve. `WaterTank`'s three variables are: (i) `FlowRate` parameter r measures the inner flow of water in cubic meters per second, (ii) parameter a gives the tank's Area in square meters, and (iii) variable h holds the height (or level) of water in the tank. `WaterTank` has two ports: (i) input port VI takes the valve's instruction, and (ii) port WLO outputs the water's height. `WaterTank` comprises three components: (i) `Drain` with its input port WI (incoming water flow); (ii) `Source` with its output port WO (outgoing water flow); and (iii) `Tank` with its input ports VI (valve's state) and WI (incoming water flow), and output ports WO (outgoing water flow) and WLO (water level).

The CD (Fig. 27b) connects the ASD block instances through port instances as per Fig. 26. System `WTSys` (instance of `WaterTankSys`) is composed of WT and C, instances of `WaterTank` and `Controller` respectively. WT is sub-divided into S, T and D. Connectors link port instances — for example, C's output port vo (instance of `Controller` port VO) is linked to WT input port vi (instance of `WaterTank` input port VI).

The algebraic loop check subjacent to such models, done in CSP in [11], can be performed within the FRAGMENTA tool. Figure 28 presents the port dependency graph extracted from Fig. 27; within the FRAGMENTA tool it can be established that the graph is acyclic — hence, algebraic loops are absent in the model. In the ASD (Fig. 27a), making port `Tank.WLO` dependent on port `Tank.VI` would introduce an algebraic loop — an edge from `T_vi` to `T_wlo` would be added to Fig. 28.

7 EVALUATION

The sequel introduces evaluation questions, dissected from perspectives (section 7.1). FRAGMENTA is compared against a selection of competitors using a sample of models (section 7.2). Finally, criteria and results are presented for the two perspectives, horizontal (section 7.3) and vertical (section 7.4) separation of concerns, before presenting the overall results (section 7.5).

7.1 Evaluation Question (EQ)

The following question drives the evaluation:

EQ1. Is FRAGMENTA's modelling approach supported by its novelties better than competing approaches with respect to horizontal and vertical decomposition, formality and graphical expressiveness?

This question is dissected through the prism of two perspectives: *horizontal* and *vertical separation of concerns*. The former deals with articulation and covers graphical expressiveness, horizontal decomposition and horizontality's formality; the latter with layering which concerns abstraction, refinement and typing (or instantiation).

7.2 Competitors and Evaluation Sample

Table 1 presents FRAGMENTA's evaluation competitors. Because UML is a benchmark, three different flavours are considered: (i) monolith UML (MUML), a traditional usage without partitioning, (ii) partitioned UML (PUML), an

Approach	Description
Monolith UML (MUML)	A traditional, non-partitioned UML usage.
Partitioned UML (PUML)	Informal partitioning for UML class models (from [25, 43]).
Package UML (PkgUML)	An approach based on UML with package merge [24, 53].
MergeUML	Sabetzadeh et al [58, 59]’s UML model merging approach.
METADEPTH	The multi-level modelling approach based on potencies of [20, 21].

Table 1. Approaches compared against FRAGMENTA in the evaluation.

Model	Problem	Description
Abstract Hotel	Hotel – Pet hotel	Abstract hotel layered model (Fig. 1, section. 2).
Pet Hotel	Hotel – Pet hotel	Concrete pet hotel layered model (Fig. 2, section. 2).
Pet hotel instance	Hotel – Pet hotel	Pet hotel instances of layered model (Fig. 4, section. 2).
Abstract commerce	Commerce	Abstract e-commerce layered model (Fig. 19a, section 4).
Concrete commerce	Commerce	Concrete e-commerce layered model (Fig. 19b, section 4).
Commerce instances	Commerce	Instances of the e-commerce model (Figs. 19c and 19d, section 4).
Abstract statecharts	Statecharts	Abstract statecharts layered model (Fig. 20, section 5.1).
Concrete statecharts	Statecharts	Concrete statecharts layered model (Fig. 21, section 5.2).
Statechart instances	Statecharts	Instances of the statecharts metamodel (Fig. 22, section 5.3).
Abstract Into-SysML	Into-SysML	Abstract Into-SysML’s architecture diagrams (Fig. 23, section 6.1).
Architecture structure diagrams (ASDs)	Into-SysML	ASDs (Fig. 24), part of the Into-SysML metamodel (section 6.2).
Connection diagrams (CDs)	Into-SysML	CDs (Fig. 25), part of the Into-SysML metamodel (section 6.3).
Into-SysML instances	Into-SysML	ASD and CD instances (Fig. 27), illustrating Into-SysML (section 6.4).

Table 2. Sample of models used in the evaluation.

informal approach from the literature (e.g. [25, 43]), and (iii) UML with packaging (PkgUML), investigated in [24, 53]. Two approaches were selected because they are novel with respect to horizontal and vertical separation of concerns: UML with model merge (MergeUML) of Sabetzadeh et al [58, 59], and METADEPTH [20, 21], respectively.

The sample of models that sets the basis of the comparison includes the four layered models presented herein (table 2).

7.3 Horizontal separation of concerns (HSoC): criteria and results

The sequel presents HSoC’s orthogonal factors (sections 7.3.1 to 7.3.4), the HSoC overall score formula (section 7.3.5), and the overall results (section 7.3.5).

7.3.1 Transmission Effectiveness (TE). Founded on the limits of human information processing [46], TE gauges how information is conveyed. A good TE means effective decomposition and good usability. A bad TE entails information overload, unsatisfactory decomposition and impoverished usability.

Information load (IL), TE’s base measure, accounts for amount of information; it is based on summing the weights assigned to model elements as per Table 3a, which gives element types and their IL weights. Individual elements weigh 1; additional representations weigh 5 due to the cognitive overhead involved in handling them (e.g. separate diagram); ILs of textual descriptions are estimated as follows: 6 for simple constraints and 9 for complex constraints¹³. This

¹³These are estimated as they are not precisely specified herein. Typically, they correspond to VCL’s value edge constraints (simple constraints) and derived and path edges (complex constraints).

Node contour	1				
Edge and direction	1				
Name	1				
Multiplicity	1	Excellent	5	Excellent (5)	0 . . 55
Supplemental information	1	Good	4	Good (4)	56 . . 80
Extra representation	5	Satisfactory	3	Satisfactory (3)	81 . . 105
Simple textual constraint	6	Unsatisfactory	2	Unsatisfactory (2)	106 . . 130
Complex textual constraint	9	Poor	1	Poor (1)	> 130
(a) Element types and their information load weights		(b) Evaluation's five-point scale		(c) Transmission effectiveness scores and corresponding information load intervals	

Table 3. Information load weights, the five-point scale, and transmission effectiveness scores

Excellent (5)	Almost everything described graphically, despite possible minor limitations ($GER \geq .95$). The model's TE is at least good ($TE \geq 4$).
Good (4)	Most description needs addressed graphically ($.8 \leq GER < .95$). The model's TE is at least good ($TE \geq 4$).
Satisfactory (3)	Despite linguistic limitations, majority of what is needed is described graphically ($.65 \leq GER < .80$) and the model's TE is at least satisfactory ($TE \geq 3$), or most description needs addressed graphically ($GER > .80$), but model's TE is below satisfactory ($TE < 3$).
Unsatisfactory (2)	Linguistic limitations prevent the graphical expression of many pertinent properties ($.5 \leq GER \leq .65$).
Poor (1)	The graphical linguistic power is too limited ($GER < .5$).

Table 4. Criteria of expressiveness (E).

provides the basis for: *maximum* ($IL^\bullet$) and *mean* ($\overline{IL}$) diagram IL, *total* model IL (IL^Σ) and IL per fragment (IL/F). $IL^\bullet$ gives a fragmented model's maximum IL, $\overline{IL}$ is the mean, IL^Σ is the overall model's IL (sum of individual ILs), including other diagrams describing how fragments are interrelated, and IL/F gives the overall model's IL score per fragment (IL^Σ divided by number of fragments of the model).

Table 3c says how TE rankings, on the evaluation's five-point scale (table 3b), are derived from IL intervals. A model's TE can either be *excellent* ($IL \leq 55$), *good* ($56 \leq IL \leq 80$), *satisfactory* ($81 \leq IL \leq 105$), *unsatisfactory* ($106 \leq IL \leq 130$), or *poor* ($IL \geq 130$). Measures maximum TE ($TE^\bullet$), average TE ($\overline{TE}$) and TE per fragment (TE/F) are derived from $IL^\bullet$, $\overline{IL}$, and IL/F , respectively, by applying the function described by table 3c.

The TE score is the mean of the three individual TEs:

$$TE = \frac{TE^\bullet + \overline{TE} + TE/F}{3}$$

A model's size is characterised with respect to IL^Σ as either *small* ($IL^\Sigma < 90$), *medium* ($90 \leq IL^\Sigma < 200$) or *large* ($IL^\Sigma \geq 200$).

7.3.2 Expressiveness (E). About graphical descriptive capability, E is related to articulation, a tenet of HSoC¹⁴. A good E indicates capacity to express what is needed succinctly. A bad E is a sign of verbosity, awkwardness or inability to express graphically certain required things.

¹⁴The graphical focus is due to FRAGMENTA's graphical nature.

Excellent (5)	The decomposition of the model is effective and mechanically composable. DC is formal and tool-supported.
Good (4)	The decomposition of the model is effective and mechanically composable. DC is formally defined, but lacks tool-support.
Satisfactory (3)	DC mechanisms are either flawed or unconvincing. The model is small ($IL^\Sigma < 90$), which diminishes need for DC.
Unsatisfactory (2)	DC mechanisms are either flawed or unconvincing. Either they are not properly defined or unconvincing and the model is at least medium-sized ($IL^\Sigma \geq 90$), or a satisfactory definition is missing altogether and the model is medium-sized ($90 \leq IL^\Sigma < 200$).
Poor (1)	Not possible to make a much needed mechanical decomposition due to the lack of means and the model is large ($IL^\Sigma \geq 200$).

Table 5. Criteria of decomposition and composition (DC)

Excellent (5)	HWF, formally defined and tool-supported, ensures excellent healthiness. All healthiness checks, pertinent to the evaluation presented here, are covered.
Good (4)	HWF, formally defined and tool-supported, ensures good healthiness. The few unsupported pertinent checks are negligible as model is small ($IL^\Sigma < 90$).
Satisfactory (3)	Healthiness guarantees are only satisfactory. Existing HWF is not proper (unrigorous and unconvincing), without tooling and resulting model is small ($IL^\Sigma < 90$). Or HWF is proper but the unsupported pertinent checks are important as model is not small ($IL^\Sigma \geq 90$).
Unsatisfactory (2)	Healthiness guarantees are dubious. HWF is either not proper (unrigorous, unconvincing, and without tooling) and model is medium-sized ($90 \leq IL^\Sigma < 200$), or it is unacceptable and model is small ($IL^\Sigma < 90$).
Poor (1)	Healthiness guarantees are unreliable. Acceptable HWF is missing altogether and model is not small ($IL^\Sigma \geq 90$), or existing HWF is not proper (unrigorous and unconvincing) and model is large ($IL^\Sigma \geq 200$).

Table 6. Criteria of horizontal well-formedness (HWF)

Measure *graphical expressiveness ratio* (GER), which supports appraisals of E, is calculated as:

$$GER = \frac{IL^\Sigma - TIL}{IL^\Sigma}$$

where *TIL* (textual IL) is the total IL of the estimated textual descriptions.

Table 4 sets out E's criteria on table 3b's five-point scale, using objective measures *GER* and *TE*.

7.3.3 Decomposition and Composition (DC). Decomposition breaks things apart, composition puts the parts together. A good DC indicates capacity to break down soundly and compose mechanically. A bad DC entails inadequate DC means. Table 5 sets out DC's criteria, which uses the measure IL^Σ .

7.3.4 Horizontal well-formedness (HWF). A well defined and, ideally, formal notion of well-formedness paves the way for rigorous consistency and adequacy checking. A good HWF entails soundness, formality and effective consistency-checking. A bad HWF signals an inadequate healthiness notion that may be imprecise, sketchy or limited. Table 6 sets out the criteria for HWF using IL^Σ .

7.3.5 *Score.* *HSoC*'s score is a weighted sum calculated from the factors:

$$HSoC = TE \times .34 + (E + DC + HWF) \times .22$$

TE gets a weight of 34%; *E*, *DC* and *HWF* get 22% each. The higher TE weight is due to TE's superior objectivity, based on a measure of diagram element counts, which captures the goodness of a decomposition, a tenet of *HSoC*.

7.3.6 *Results.* Table 7 gives the results for *HSoC*; it includes columns for: number of fragments (# *Fs*), ILs for maximum ($IL^\bullet$), average ($\overline{IL}$) and overall (IL^Σ), IL per fragment (IL/F), maximum ($TE^\bullet$) and mean ($\overline{TE}$) TE, TE per fragment (TE/F), overall TE (*TE*), *E*, *DC*, *HWF* and overall *HSoC*.

The rationale for the *HSoC* evaluation of the hotel world model (Fig. 1) is as follows:

- In *FRAGMENTA* (Fig. 1), ILs of nodes *Hotel*, *Room*, *Guest* and *Other* cost 2 (one box, plus one name), *Trait* costs 3 (2 plus supplemental kind), inheritance arrows cost 1 (line with arrow), all remaining edges cost 4. In *F_AH*, $IL = 27$, also the model's $IL^\bullet$ and $\overline{IL}$ as there is only one fragment. $IL^\Sigma = 34 - 27$ plus cost of GFG (5) and its node (2). $IL/F = 34$. *TE* is excellent — $TE^\bullet = \overline{TE} = TE/F = 5$. *E*, *DC* and *HWF* are all excellent: everything is expressed neatly, the only fragment is formally composable, and well-formedness is tool-checked, respectively. Overall *HSoC* is excellent.
- A trivial *MUML* translation of Fig. 1 would make *Trait* abstract. Virtuals differ from abstract classes, which imply a stronger *is-a* semantics and single inheritance, but this is negligible in this case — expressing *AnyRel* of Fig. 1 with individual associations would be a more onerous alternative. Therefore, *MUML*'s $IL^\bullet$ and $\overline{IL}$ is 27, as *FRAGMENTA*, but with a lower IL^Σ of 27 (no extra package diagram), giving a IL/F of 27. *TE* is excellent. *E* is excellent as everything is expressed graphically and the *TE* is good. *DC* is satisfactory — only one fragment without a composable underpinning. *HWF* is unsatisfactory (2) as its definition is mostly informal, not overly significant in this small model. Overall *HSoC* is good ($3.9 \approx 4$).
- The other approaches vary only slightly from *FRAGMENTA* or *MUML*. *MergeUML* trails closely behind *FRAGMENTA* with an *HSoC* of $4.78 \approx 5$, ranked 4 in *HWF* due to limitations at the level of decomposition healthiness¹⁵ and tool-supported formalisation¹⁶, not significant in this model. *METADEPTH*'s *HSoC* is good ($4.12 \approx 4$), ranked satisfactory in *HWF* — its formalisation is too focused on layering, neglecting relevant aspects, such as multiplicities.

The rationale for table 7's evaluation of pet hotel (section 2), expressed in *FRAGMENTA* in Fig. 2, and monolith and partitioned UML in Fig. 29, is as follows:

- ILs of *FRAGMENTA* fragments F_PW_i of Fig. 2, where $i \in 1..8$, are, respectively, 40, 37, 42, 35, 51, 55, 24 and 46. Hence: $IL^\bullet = 55$ ($TE^\bullet = 5$), $\overline{IL} \approx 41$ ($\overline{TE} = 5$), $IL^\Sigma = 365$ (sum of all fragment ILs, plus extra diagram, plus IL of GFG), $IL/F = 365/8 \approx 46$ ($TE/F = 5$); overall *TE* is excellent. *E*, *DC* and *HWF* are excellent (5) as: (i) everything is expressed including constraints, (ii) mechanical composition and decomposition is effective, and (iii) the model's healthiness is checked thoroughly with a tool. Overall, *HSoC* is excellent (= 5).
- *MUML*'s sole fragment (Fig. 29a) has a $IL^\bullet = \overline{IL} = 237$, but $IL^\Sigma = 342$ to account for the constraints expressed textually. Hence, *TE* is poor — $TE^\bullet = \overline{TE} = TE/F = 1$. *E* is unsatisfactory — $GER = .7$ and $TE = 1$, reflecting

¹⁵Unlike *FRAGMENTA*, *Merge UML* lacks a notion of a well-formed fragment to ensure horizontal healthiness and correct compositions.

¹⁶*Merge UML*'s tool is unable to check whether the source multiplicity of Fig. 1's composition is either 1 or 0..1 only, and whether multiplicities are well-formed as multiplicities are separate and external from the core graph-based representation.

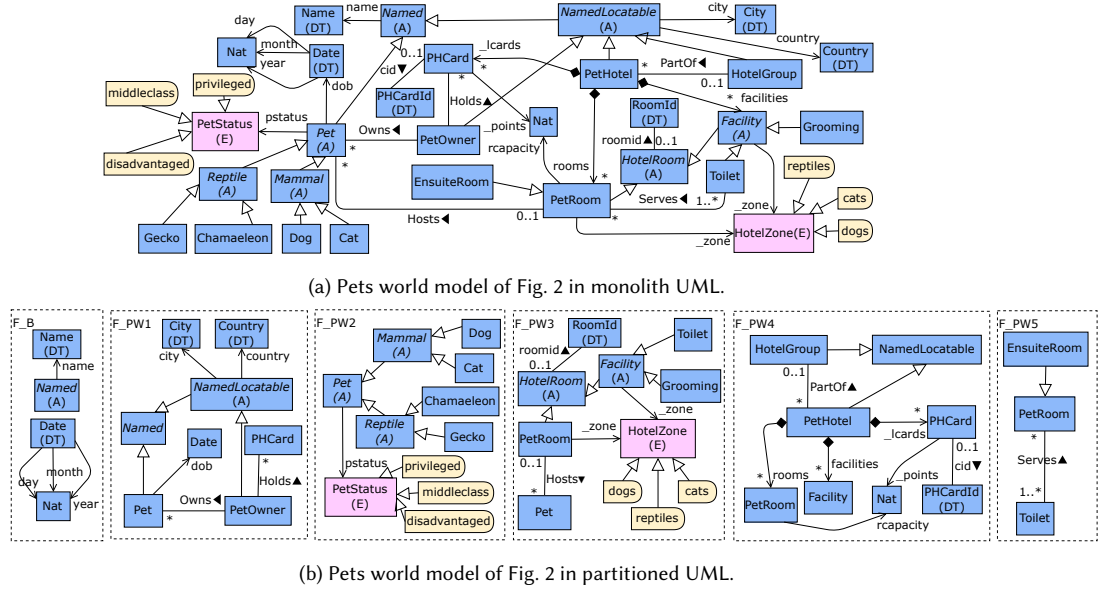


Fig. 29. Pets-world model of Fig. 2 expressed in monolith and partitioned UML.

UML's inability to express constraints graphically. DC is poor due to lack of decomposition means much needed in this fairly large model. *HWF* is poor as model is large. Overall, *HSoC* is poor ($1.22 \approx 1$).

- In PUML (Fig. 29b), ILs of F_PW_i , where $i \in 1..6$, are, respectively, 19, 39, 48, 52, 45 and 12. Hence: $IL^\bullet = 52$ ($TE^\bullet = 5$), $\overline{IL} \approx 36$ ($\overline{TE} = 5$), $IL^\Sigma = 320$, and $IL/F = 320/6 \approx 53$ ($TE/F = 5$); overall TE is excellent. *E* is satisfactory – $GER = .57$ and $TE = 5$. DC is poor (1) as a much needed mechanical underpinning is absent in a model of this size. *HWF* is poor as the model is fairly large and without a formal underpinning. Overall, *HSoC* is satisfactory ($2.8 \approx 3$).
- A PkgUML model would include a package diagram in addition to Fig. 29b. Hence: $IL^\bullet = 52$ ($TE^\bullet = 5$), $\overline{IL} \approx 36$ ($\overline{TE} = 5$), $IL^\Sigma = 342$, and $IL/F = 342/7 \approx 49$ ($TE/F = 4$); overall TE is excellent. Like PUML, *E* is satisfactory (3). DC is unsatisfactory as PkgUML's DC theory is deficient (see section 9) and the model is large. Like PUML, *HWF* is poor. Overall, *HSoC* is satisfactory ($3.02 \approx 3$).
- A MergeUML model would include an *interconnection diagram* relating manifestations of the same element across fragments in addition to Fig. 29b. Hence: $IL^\bullet = 52$ ($TE^\bullet = 5$), $\overline{IL} \approx 36$ ($\overline{TE} = 5$), $IL^\Sigma = 350$, and $IL/F = 350/7 \approx 58$ ($TE/F = 4$); overall TE is excellent. *E* is satisfactory (3), as PUML and PkgUML. DC is excellent (5) due to the underlying formal mechanics. *HWF* is satisfactory (3) due to the limitations of the formal underpinning, relevant for a model of this size. Overall, *HSoC* is good ($4.12 \approx 4$).
- A METADEPTH model would be similar to MUML (Fig. 29a). Because horizontal decomposition is not supported, the IL-based TE scores are low: $IL^\bullet = 237$ ($TE^\bullet = 1$), $\overline{IL} = 237$ ($\overline{TE} = 1$), $IL^\Sigma = 342$, and $IL/F = 342$ ($TE/F = 1$); overall TE is poor. Like MUML, *E* is unsatisfactory, and DC and *HWF* are poor (the formalisation is excessively focused on vertical layering, leaving crucial aspects out and the model is large). Overall, *HSoC* is poor ($1.22 \approx 1$).

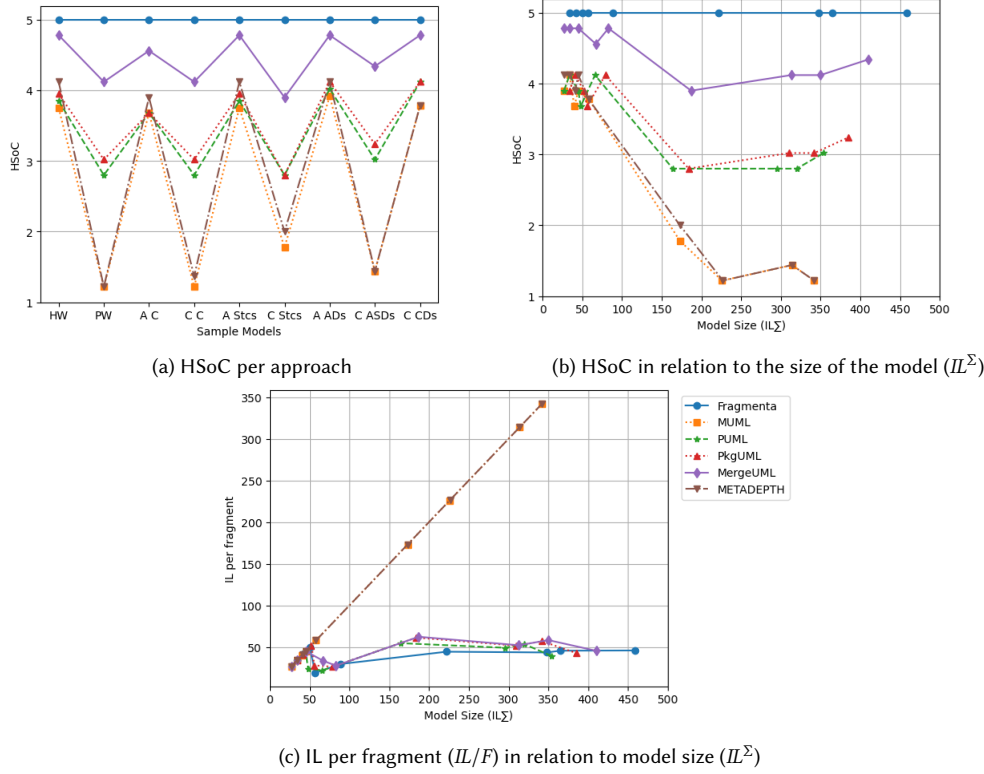


Fig. 30. Plots of the evaluation of Horizontal Separation of Concerns (HSoC). Abbreviations: HW = Hotel World (Fig. 1), PW = Pets World (Fig. 2), A StCs = Abstract Statecharts (Fig. 20), C StCs = concrete statecharts (Fig. 21), A ADs = abstract SysML-based architecture diagrams (Fig. 20), C ASDs = concrete SysML-based architecture structure diagrams (Fig. 24), C CDs = concrete SysML-based connection diagrams (Fig. 25).

The three plots of Fig. 30 provide different perspectives over table 7's data, namely: HSoC scores for each model of the sample (Fig. 30a), HSoCs with respect to a model's size or IL^Σ (Fig. 30b), and relation between IL per fragment and IL^Σ (Fig. 30c). The results ($N = 9$) are as follows:

- FRAGMENTA is consistently excellent (mean 5, standard deviation = 0); MergeUML ($m = 4.56 \approx 5$, $sd = .25$) is also excellent.
- METADEPTH ($m = 2.88 \approx 3$, $sd = 1.36$) and MUML ($m = 2.73 \approx 3$, $sd = 1.27$) are highly dependant on the model's size (Fig 30b) – *TE* degrades considerably when the size increases.
- Pkg-UML ($m = 3.48$, $sd = .46$) is only slightly better than PUML ($m = 3.41$, $sd = .54$), and both better than METADEPTH and MUML because of their superior *TE*; however, performances still degrade with larger models due to lower *E*, *DC* and *HWF* which become more pertinent as models increase in size (Fig 30b).
- Figure 30c shows that all approaches, except MUML and METADEPTH, are able to control *TE* as the size of the model increases, as IL/F , a good *TE* indicator, remains nearly constant. Hence, the clear differences in overall *HSoC* are mainly due to mechanics and quality of what is conveyed, as per factors *E*, *DC*, and *HWF*, as discernable from Figs. 30a and 30b.

Excellent (5)	Layering concerns articulated adequately, covering vertical abstraction (VA) and instantiation (or typing). Extra typing supported if needed.
Good (4)	Most layering concerns articulated adequately, covering both VA and instantiation (or typing). Extra typing needed but unsupported.
Satisfactory (3)	Layering concerns articulated partially. Either only instantiation supported and model is small ($IL^\Sigma < 90$), or VA supported but unconvincingly and model is at most medium-sized ($IL^\Sigma < 200$).
Unsatisfactory (2)	Layering concerns articulated partially. Either only instantiation supported and the model is medium-sized ($90 \leq IL^\Sigma < 200$), or VA supported unconvincingly and model is large ($IL^\Sigma \geq 200$).
Poor (1)	Layering concerns only partially articulated. Only instantiation supported. VA unsupported but important as model is large ($IL^\Sigma \geq 200$).

Table 8. Criteria for layering description (LD)

7.4 Vertical Separation of Concerns (VSoC): criteria and results

Concerned with vertical organisation, VSoC provides layering: models constitute layers, kept separate and independent but related through element mappings to other layers, analogous to the paper’s graph theory: layers are graphs related through morphisms.

The evaluation assesses how the examined approaches fare against FRAGMENTA, designed to facilitate layering through abstraction (or refinement), typing and extra typing. The sequel presents evaluation factors and criteria, the overall score formula, and VSoC’s evaluation results.

7.4.1 Factors. VSoC is evaluated on the sample models by appraising each approach on table 3b’s 5-point scale with respect to the following factors:

- **Layering description (LD).** This ascertains the adequacy of the linguistic and conceptual support for abstraction (construction of abstract layers above), refinement (concrete layers below) and instantiation (or typing). LD’s criteria, set out in table 8, uses the measure IL^Σ .
- **Vertical formality and checking (VFC).** This assesses the formal underpinning of the vertical machinery and its capacity to check both the healthiness of layered models, and the validity of model instances with respect to type models according to table 9’s criteria.

7.4.2 Overall Score. VSoC’s overall score is a weighted sum with 40% for LD and 60% for VFC :

$$VSoC = LD \times .4 + VFC \times .6$$

VFC’s 60% is higher than LD’s 40% to reflect the higher importance attributed to formality and mechanical verification.

7.4.3 Results. Figure 31 summarises the results. Table of Fig. 31a provides the average scores for the four layered models (pet world, e-commerce, statecharts and Into-SysML as per table 2), plotted in Fig. 31b. A summary of VSoC’s evaluation is as follows:

- FRAGMENTA’s LD and VFC are excellent across the four models. Layering is fully and adequately articulated, including the extra typing. Refinements, extra typing and instantiations are checked using FRAGMENTA’s tool. The overall score is excellent (**VSoC** = 5).

Excellent (5)	Layering's formal underpinning, supporting instantiation and vertical abstraction (I & VA), is sound and tool-supported enabling thorough checking of the: (i) healthiness of a model's vertical layering, and (ii) validity of object (or instance) models with respect to any type of model higher up in the vertical hierarchy. A few pertinent properties (≤ 5) may be left unchecked provided the main model is small ($IL^\Sigma < 90$).
Good (4)	Layering's formal I & VA underpinning is tool-supported, checking both vertical healthiness and instance validity. A few pertinent properties (≤ 5) are left unchecked and the main model is at least medium-sized ($IL^\Sigma \geq 90$).
Satisfactory (3)	Layering's formal underpinning is tool-supported, but checks instantiation only. Only two vertical layers supported: instance and model. Several pertinent properties or aspects are unchecked.
Unsatisfactory (2)	Layering's semi-formal linguistics for I & VA enable manual instance validity checking only, manageable as main model is small ($IL^\Sigma < 90$).
Poor (1)	Layering is semi-formal, if supported at all. Manual instance validity checks are difficult to manage as main model is at least medium-sized ($IL^\Sigma \geq 90$).

Table 9. Criteria of VSoC Formality and Checking (FC)

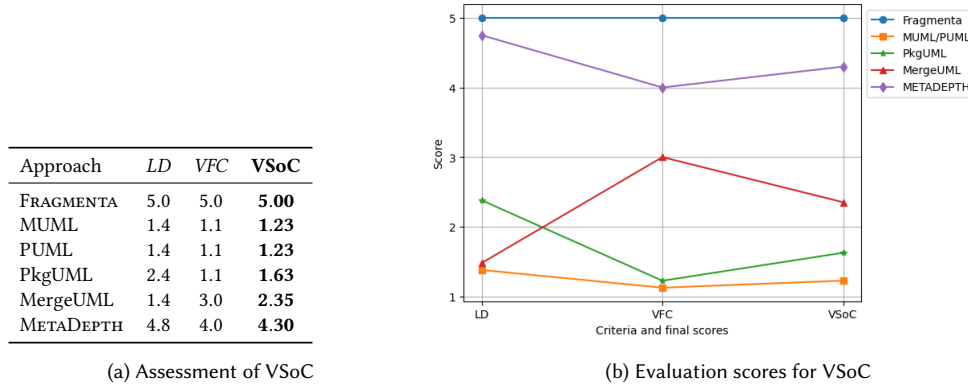


Fig. 31. Evaluation results of vertical separation of concerns (VSoC). Variables: *LD* = layering description, *VFC* = vertical formality and checking, *VSoC* = overall VSoC. Criteria assessed on a 5-point scale: 1 = poor, 2 = unsatisfactory, 3 = satisfactory, 4 = good and 5 = excellent.

- MUML and PUML's LD scores oscillate between poor and unsatisfactory with an average of 1.4 (≈ 1) as vertical abstraction is unsupported and the linguistics of instantiation is semi-formal. *VFC* is also deemed poor on average ($= 1.1 \approx 1$) as layering checks are manual. Overall, score is poor (**VSoC** = 1.23 ≈ 1).
- PkgUML gets an average score of unsatisfactory ($2.8 \approx 3$) in *LD*, better than PUML and MUML due to its support for package refinement. Like MUML and PUML, its *VFC* average score is poor ($= 1.1 \approx 1$). Overall score is unsatisfactory (**VSoC** = 1.93 ≈ 2).
- MergeUML is deemed unsatisfactory in *LD*, as PUML and MUML for the same reasons. *VFC*'s average score of satisfactory ($= 3$) is due to the formal and tool-supported instantiation checks. Overall score is unsatisfactory (**VSoC** = 2.35 ≈ 2).
- METADEPTH's *LD*, excellent in all layering examples except Into-SysML connection diagrams as extra-typing is unsupported, yields an average score of excellent ($= 4.8 \approx 5$); the vertical abstraction scheme based on typing tends to be more succinct than FRAGMENTA's refinement. *VFC* is good ($4.3 \approx 4$) as: (i) there is a formal

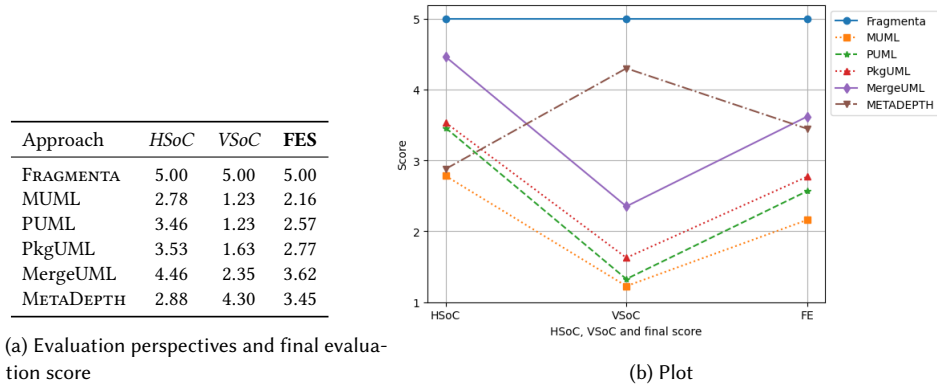


Fig. 32. Overall evaluation highlighting the two perspectives, *HSoC* and *VSoC*, and final evaluation score (FES). All evaluations assessed on a 5-point scale with values 1 (poor), 2 (unsatisfactory), 3 (satisfactory), 4 (good) and 5 (excellent). Abbreviations: *HSoC* = Horizontal separation of concerns; *VSoC* = Vertical separation of concerns; FE = final evaluation.

underpinning based on graph morphisms with a (ii) notion of well-formedness which is tool-supported, but (iii) instantiation checking, excessively focussed on vertical abstraction and potencies, is limited as many relevant aspects are left out. Overall score is good (***VSoC*** = $4.3 \approx 4$).

7.5 Overall Evaluation

FE, the overall evaluation score, is a weighted sum obtained from *HSoC* and *VSoC*:

$$FE = HSoC \times .6 + VSoC \times .4$$

HSoC's 60%, higher than *VSoC*'s 40%, is due to *HSoC*'s higher prevalence, as it concerns what the models express and the fragmentations involved in controlling complexity, which are major modelling concerns in the current practice; *VSoC* is about relations between models at different levels of abstraction, important to control complexity, and for abstraction and comprehensibility, but perhaps less important in the current practice.

Figure 32 presents the overall evaluation accounting for *HSoC* and *VSoC*, and *FE*. Table of Fig. 32a gives the evaluation results, plotted in Fig. 32b, which are as follows:

- FRAGMENTA, the top-scorer, is appraised consistently as excellent ($FE = 5$).
- MergeUML [58, 59], the runner-up, was good overall ($FE = 3.78 \approx 4$). Excellent in *HSoC*, but only satisfactory in *VSoC*.
- METADEPTH [21, 21] was also good overall ($FE = 3.57 \approx 4$). It was excellent in *VSoC*, but only satisfactory in *HSoC*.
- PUML ($FE = 2.69 \approx 3$) and PkgUML ($FE = 2.86 \approx 3$) were both satisfactory overall, whereas MUML was unsatisfactory ($FE = 2.28 \approx 2$).

7.6 Evaluation Questions Revisited

An analysis of the evaluation questions under the light of the results highlights that FRAGMENTA answers EQ1 (Is FRAGMENTA's modelling approach supported by its novelties better than competing approaches with respect to horizontal

and vertical decomposition, formality and graphical expressiveness?) positively as it was consistently and clearly better than its competitors overall.

An in-depth analysis of the comparative benefits of FRAGMENTA's novelties highlights that:

- Proxies, a key HSoC ingredient, underpin the key decomposition theorem from [7], a pillar upon which FRAGMENTA's well-formedness notion for fragmented models is built. FRAGMENTA's main HSoC competitor, MergeUML, lacks this primitive, hence, it does not guarantee the well-formedness of compositions of fragmented models. This is one of the reasons why FRAGMENTA's results in HWF — $mean = 5, sd = 0$ — were better than MergeUML's — $mean = 3.56 \approx 4, sd = .53$ —, especially for large models.
- Virtuals, the light inheritance packs, proved to be an interesting feature which provided only a negligible advantage in the evaluation as the other approaches could circumvent the lack of virtuals in most cases with either abstract classes or more definitions, with only a negligible increase in the underlying linguistics.
- FRAGMENTA's graphical constraints, provided by derived, value constraint and path edges, provided an advantage. FRAGMENTA's HSoC's expressiveness results — $mean = 5, sd = 0$ — were better than those of the runner-up MergeUML — $mean = 4, sd = 1.12$.
- Fragmenta's VSoC novelties also provided an advantage. In LD, FRAGMENTA — $mean = 5, sd = 0$ — was slightly better than the runner-up METADEPTH — $mean = 4.75, sd = 0.5$ — mainly due to FRAGMENTA's extra typing. In formality and checking, FRAGMENTA — $mean = 5, sd = 0$ — was better than METADEPTH — $mean = 4, sd = 0$.

7.7 Threats to Validity

The sequel discusses limitations and biases that may affect the reliability, integrity and generalisability of the evaluation results given herein.

7.7.1 Internal Validity. Considerations on whether extraneous factors could have interfered with the evaluation results, raise the question of the adequacy of the sample of approaches FRAGMENTA was compared against, which could be biased somehow. The selection rationale considered the need for: (i) a representation for the current practice which would set the benchmark, and (ii) approaches that innovate and compete with FRAGMENTA. The current practice is represented by three UML flavours: (i) traditional monolith UML, the way UML is mostly taught and practiced, (ii) partitioned UML, a dialect used in the advanced UML literature, based on ad hoc fragmentation, and (iii) a more modern UML with linguistic support for fragmentation through packages. The innovative approaches included Sabetzadeh et al [58, 59] and METADEPTH [20, 21], both appraised by the author as the most advanced competing approaches in HSoC and VSoC, respectively.

7.7.2 Construct Validity. Because the evaluation was designed and undertaken by the author who himself appraises the merits of FRAGMENTA, his work, the measurements could be prone to bias, especially if the evaluation criteria is overly subjective. This issue was addressed by objectifying the evaluation criteria, which provides only a little margin of subjectivity, in some cases none at all; this diminishes the possibility of evaluator disagreements considerably but not entirely. Another source of bias could lie in the weights that underpin the scores of HSoC, VSoC and overall. Criteria and weights underpinning evaluation scores are all based on the judgments of the author, hence, they have a certain inherent subjectivity; they have been made explicit, for the sake of rigour and transparency, to facilitate posterior scientific scrutiny.

It is important to acknowledge the limitations and assumptions of the evaluation’s measurements. In HSoC, a prominent factor is TE, based on notions of information load and limits of human information processing [46], and notions of modularity and separation of concerns and how decomposition favours comprehensibility [61]. TE is HSoC’s highest-weighted factor, 34%, because it is the most objective and the one reflecting closely what HSoC is about. The results suggest that the TE measurements make sense — good decompositions leading to high TE scores and bad ones leading to low ones. However, this is perhaps not as accurate as a user controlled experiment in which users say what is and what is not working for them.

Another criteria whose assumptions need acknowledging is HSoC’s expressiveness (E) and its graphical expressiveness focus. It is in graphical expressiveness that notable novelties of FRAGMENTA lie; this graphical emphasis is grounded on the cognitive benefits of pictorial representations [42]. However, it is not always the case that the graphics are better [42]. Hence, the results of the evaluation, with its graphical expressiveness focus aimed at appraising FRAGMENTA’s graphical novelties, should not be interpreted as better expressiveness in general nor better usability; a proper appraisal of these qualities would require another study.

7.7.3 External Validity. The inadequacy of the models used in the evaluation could put the generalisability of the results into question. Apart from the model of section 2, developed for the purpose of this paper, all other models originate from elsewhere and have a certain inherent degree of external validity; the model of section 4 is derived from a benchmark example of multi-level modelling with added complexity, the model of section 5 is simply a model of statecharts [33], a popular graphical language, and the model of section 6 was initiated in the context of an European Union research project. The evaluation results are based on these four models.

8 DISCUSSION

8.1 FRAGMENTA’s Graph-based Underpinning

FRAGMENTA captures the richness of data modelling as structural graphs (SGs), which build upon simple graphs. SGs support multiplicities and inheritance; graph colouring accounts for diversity. SGs’ revised morphisms — between SGs (vertical refinement) and from graphs to SGs (typing) — cater for inheritance by allowing edges to have more than one source and target nodes — an edge can be the source of a particular node and all its descendants. Fragments builds up on SGs by adding referencing; they are composed and reduced to SGs through subsumption.

8.2 Fragments, GFGs and Models

Fragments, defined from SGs, provide confinement but allow intra- and inter-node connections through proxies. Fragments deal with matter at the local level; proxies are local referencing artifices to connect to nodes from the overall model; the referencing aids the model’s logic by providing the provenance of a proxy and is crucial for mechanical composition. GFGs (Global Fragment Graphs) take a more global stance, saying how the different fragments of a model reference each other; GFG nodes represent fragments, edges indicate that one fragment references another. A model is a GFG together with an indexed set of fragments. Instances are represented in FRAGMENTA as graphs with typing; the paper provided examples where instances take the form of statecharts (section 5), Into-SysML models (section 6), and products of an e-commerce system (section 4).

8.3 Virtuals

Virtuals embody a novel lighter inheritance scheme. Like *abstract* nodes, they lack a direct existence as they have no direct instances and represent something inheritable; unlike their abstract counter-parts, virtuals put aside strong lineage or ancestry, in favour of weaker parenthood to overcome the limitations of the prevalent single inheritance — in FRAGMENTA, a node may inherit from at most one abstract node, but may inherit from many virtuals. Virtuals embody the idea that a node may only have one strong parent, but may have traits in common with weaker parents. Metaphorically, virtuals are like cultural traits possessed and shared by members of a culture. Virtuals can also represent ad-hoc groupings of unrelated nodes as disjoint unions. Virtuals were key in the paper’s main FRAGMENTA illustrations (sections 2 and sections 4 to 6) to represent union types and anything inheritable, allowing a range of classes to inherit from a pool of inheritable things. In Fig. 2, *Named*, widely inherited, represents something with a name; in Fig. 19b *Volume* is a disjoint union.

8.4 Graphical Constraints

Together, derived, constraint and path edges, make up FRAGMENTA’s support for graphical constraints, a noteworthy novelty. Derived edges express extra multiplicities; in Fig. 2, derived edge of fragment *F_PW5* specialises edge *Serves* — pet rooms have at least one toilet, but ensuite rooms have exactly one. Constraint-value edges constrain the values of either nodes or association edges; in Fig. 2, fragment *F_PW1* says that: the values of *Nat₁* are greater or equal than 1, and edge *day* of node *Date* takes natural number values less or equal than 31. Path edges describe diagram commutings; in Fig. 2, fragment *F_PW7* says that a toilet’s zone must be the same as the zone of the rooms it services (the two paths must commute).

8.5 Patterns

Virtuals and derived edges give rise to interesting patterns. The paper identified three FRAGMENTA patterns: (i) *virtual traits*, (ii) *flexible relations* and (iii) *templates*. *Virtual traits* makes relations inheritable by a number of classes through a virtual; the relation may be a manifestation of *flexible relations* — a unary association on a virtual allowing for a variety of configurations —, as is the case in Fig. 1 and the other three major illustrations (sections 4 to 6). These two patterns usually concern abstract layered modelling to prescribe a structure for refinements, but *flexible relations* is applicable in other settings as well.

Templates represent generic things, instantiable in a model. This relies on virtuals to represent the generic parts, inheritance for instantiation, and derived edges for refinement of inherited relations, as illustrated in Figs. 7f and 7g, where the virtual *CPair* represents a pair made up of two generic components, which are instantiated differently.

8.6 Horizontal and Vertical Refinement

Horizontal refinement gives rise to partitionings (decompositions, or fragmentations). It was introduced in [7], but enhanced here with *fragment resolution* (or composition) to stitch fragments mechanically along proxies through subsumption. It inherits from [7] the restrictions of proxies, namely: (a) proxies may not inherit, and (b) fragment references must be one-way only.

Vertical refinement, introduced here, complements horizontal refinement. It provides a novel vertical *layering* inspired by data refinement [35] based on graph notions of morphisms and commuting. A model refines another if: (i) there is a valid morphism from the concrete model to its abstract counter-part, and (ii) the concrete model satisfies certain

compliance conditions related to multiplicities, and node and edge types. Vertical refinement follows principles and ideas of data refinement, rather than being directly derived from it. *Narrowing* is such an example; refinements narrow down the denoted set of states of their abstract counter-parts, which is reflected in the rules: (i) total refinements should not exclude things from the abstract model (only partial refinements may do so); and (ii) refinement multiplicities are either narrowed or remain the same. FRAGMENTA's vertical refinement affects state spaces, differing from general data refinement which has a behavioural dimension.

8.7 Multilevel modelling

Through refinement, distinguished from typing in FRAGMENTA's upgrade presented here, FRAGMENTA puts forward a multilevel modelling architecture based on two strata: *type* and *instance*. The type (or meta) stratum may be further divided into layers; the instance stratum is indivisible. Type layers represent models at different levels of abstraction, from abstract to concrete related through the transitive refinement relation, a morphism with special characteristics focused on elaboration. Type and instance strata are related through typing, also defined as a morphism. FRAGMENTA's multi-level modelling novelty relies on refinement's ability to relate models vertically, underpinned by the transitive refinement relation, an alternative to the overused instantiation relation as a means to relate models [1, 2]. In addition, FRAGMENTA allows partial extra typings: models of the type stratum may have some of its elements typed by another model.

The pets world example of section 2, together with e-commerce, statecharts and Into-SysML of sections 4 to 6 illustrate multilevel modelling. The abstract metamodel conveys an essential structure that must be complied with by concrete metamodels, providing vertical separation of concerns. FRAGMENTA's typing allows graphs typed by fragmented metamodels, as shown with the statechart examples of section 5, whose correctness can be checked with FRAGMENTA's tool. FRAGMENTA's extra typing allows type elements to be instances of elements in another model, as illustrated in Into-SysML model of section 6, where elements of CDs have extra types in the model of ASDs.

Multilevel modelling serves several useful purposes: (i) *stepwise development*, where the abstract model acts as the precursor to the concrete model; (ii) *separation of concerns*, as abstract and concrete models may be carefully articulated to focus on different things; (iii) *abstraction*, as the abstract model provides an abstraction which may be useful for reasoning, verification and explanation.

To ease the description of morphism mappings which underpin typing and refinement, the morphism definitions inherited from [7] were improved to abstain from mapping inheritance edges.

8.8 Separation and Composition

Separation (or decomposition) constitutes the means through which complexity is managed horizontally. Composition is grounded on two major mechanisms: (i) *fragment union*, which joins fragments without altering their contents, and (ii) *fragment resolution*, which replaces proxies by their referents. Both are used to produce the overall model composition, a monolith: (i) the model's fragments are joined using union, and then (ii) the proxies of the union fragment are resolved.

The composition theorem, proved in [7], says that the composition of a model's fragments is well-formed provided fragments are individually well-formed — or, if a fragmented model is well-formed then its composed monolith is well-formed also. This is relevant to FRAGMENTA, which relies on fragment composition or resolution to reduce fragments to SGs. The theorem imposes two restrictions: (i) the fragment's referencing is one-way only, and (ii) proxies must not inherit. In practice, these restrictions are not severely limiting,

8.9 Method, Formalisation and Proofs

FRAGMENTA's mathematics was developed using a combination of notations and tools. The theory was specified in Z [37, 60, 64] with the support of the CZT type-checker [45, 47], to ensure consistency with respect to names and types. Z, a high-level mathematical language based on the Zermelo-Fraenkel set theory, supports sets, functions, relations and predicate logic. The mathematics presented here was derived from, and is very close to, the Z specification [5]. The Isabelle proof assistant [63]¹⁷ was used to prove the theory's theorems or laws (see appendix A). Z provided high-level mathematical expressivity, with support for consistency and well-formedness checking; Isabelle was mainly used to prove theorems. Formal specification in Z and proof of theorems in Isabelle contributed to the quality of the work presented here.

8.10 Graphical Expressiveness

FRAGMENTA emphasises graphical modelling, maximising graphical expressivity to avoid extra textual constraints. The evaluation (section 7) confirmed FRAGMENTA's cutting-edge graphical expressivity. This is positive and follows from studies that endorsed the benefits of pictorial representations [42], which have been influential in computer science [33, 34]. However, graphical is not necessarily better, hence, FRAGMENTA's superior graphical expressivity does not necessarily entail neither superior expressivity in general, nor improved usability. However, [6] highlighted benefits of graphical software modelling, namely in reading and comprehensibility.

The different FRAGMENTA constraints express things differently. Derived edges enhance classical association-multiplicity constraints. Value-constraint edges express graphically what is known as relational or boolean expressions involving operators (e.g. $2 \leq 3$). Path constraints express the commuting constraints used in graph and category theories.

FRAGMENTA makes some expressivity gains through virtuals, which go beyond classical inheritance to factor more commonality than what is usually done, and proxies as means to express decomposition joints. Most gains, however, come from constraint edges (derived, value-constraint and path) which extend the reach of data modelling's graphical expressivity.

8.11 FRAGMENTA Tool

The FRAGMENTA tool is an Haskell [15, 36, 44] implementation of the FRAGMENTA theory presented herein¹⁸. It enlivened FRAGMENTA and increased the reliability of the paper's results. The tool can: (i) check the well-formedness of graphs, SGs, fragments, GFGs and models; (ii) resolve fragments and models using subsumption; (iii) check the correctness of typings and refinements, including partial extra typings; and (iv) produce graphs processable by the Graphviz tools [27, 31, 32]¹⁹. The tool enabled experimentation and contributed significantly to FRAGMENTA's quality; it checked all FRAGMENTA models and examples presented herein.

9 RELATED WORK

FRAGMENTA, initiated in [7], upgraded and redefined here, is a mathematical theory of a graphical data- and meta-modelling framework that tackles scalability and graphical expressivity. Metamodelling, regarded as important for model-driven development [2], is based on graph typing, founded on the graph morphism notion. Scalability, underpinned by

¹⁷<https://isabelle.in.tum.de/>

¹⁸The Haskell code is available at <https://github.com/namalio/Fragmenta/>.

¹⁹<https://graphviz.org/>

ideas related to separation of concerns [54, 61], is tackled through horizontal and vertical refinement, both mechanisms of modularity and abstraction, respectively. FRAGMENTA’s application to a SysML profile for cyber-physical systems in [10, 11] is revisited in section 6; FRAGMENTA’s new features generate a metamodel redesign where: (i) an abstract model captures the commonalities of two different diagram types, (ii) constraints are expressed graphically (they were expressed textually in [10, 11]) and (iii) deals with the profile’s extra typing needs, whereby elements of a connection diagram are instances of elements of an architecture structure diagram, not dealt with in [10, 11].

The work presented here extends and improves [7] in the following ways:

- FRAGMENTA is augmented with vertical refinement inspired by data refinement [35] to enable the construction of layered data models in a sound manner.
- Abstract expressiveness is enhanced with virtual nodes to represent things with an inherent degree of variability (e.g. virtual traits patterns discussed in section 8.5).
- Refinement is distinguished from instantiation (or typing), both based on graph morphisms. Refinement, concerned with elaboration, checks whether a concrete model is an acceptable elaboration of its abstract counter-part. Typing concerns model instantiation; it checks whether instances comply with the restrictions imposed by their types.
- To enhance both vertical and horizontal refinement, models may have extra typing relations with other models within the same layer.
- Proxies, introduced in [7] and inspired by VCL’s *references* [6, 8, 9], are enhanced with *fragment resolution*, a composition mechanism which replaces proxies by their referents that is theoretically underpinned by pushouts of category theory [26, 41], and is here defined as graph subsumption — simpler than classical solutions which refine pushouts as quotients. This entailed a redefinition of FRAGMENTA’s higher-level constructions [7] — refinement and typings at the level of models and fragments are reduced to SGs via resolution.
- Horizontal refinement is considerably improved: (i) global fragments graphs (GFGs) are simplified to support *references* edges only, allowing both top-down and bottom-up design; (ii) revised morphisms preclude inheritance from the mappings ([7] required self-inheritance dummy edges); (iii) the cluster layer of [7] was removed in favour of a simpler two-layered architecture based on fragments and GFGs.
- Virtuals, inspired by disjoint unions and *soft parents* [4], enhance inheritance to express disjoint unions and ancestry-free inheritable properties.
- The emphasis on graphical expressiveness is inspired by [42] and the inspiration that it induced in computer science [33, 34], and VCL’s positive empirical results [6].
- Derived edges specialise edge multiplicity constraints. General properties may be stated as relation edges and specialised with derived edges, involving edge paths, a composition of one or more edges. The pets example of section 2 says that, in general, toilets are shared by several pet rooms (expressed as relation edge), except ensuite rooms which have one single toilet which is not shared (expressed as derived edge). As discussed in section 8.5, virtuals together with derived edges give rise to interesting patterns enabling the expression of templates.
- As illustrated in the paper, value-constraint and path edges provide further means to express constraints graphically. Value-constraint edges are inspired by VCL’s *derived edges* [6, 8, 9], and path edges, which, like derived edges, also affect whole edge paths, by the commuting notion, used widely in graph and category theories.

- The Haskell tool, which implements and supports the theory presented here, verifies the well-formedness of models, the correctness of typings and refinements, and produces model compositions. It verified all the paper's examples.

The sequel analyses related work in graph-based horizontal refinement, complexity management of graphical data modelling, multilevel modelling, and UML modularity and composition.

9.1 Graph-based theories of Horizontal Refinement

The underpinning of Jurack and Taentzer [39, 40] is, like FRAGMENTA, graph-based. Its two-layer structure resembles FRAGMENTA; their local level based on graphs with inheritance and containment (IC-graphs) is similar to FRAGMENTA's SGs, but uses import and export interfaces to enable composition; their global level is akin to FRAGMENTA's GFGs; their typing foundation is graph morphisms as FRAGMENTA. As acknowledged by [40], inheritance cycles (a malformation) may arise when parts are composed, avoided in FRAGMENTA through the proved union composition law [7], which ensures preservation of inheritance well formedness provided some constraints are met. Despite the similarities and common foundation, FRAGMENTA goes further than [39, 40] with respect to: (i) support for both fragmentation and layering (or horizontal and vertical refinement, respectively), (ii) fragment composition through fragment union and resolution (pushout-based composition of [39, 40] is not actually specialised and defined), (iii) edge multiplicities, (iv) novel concepts, such as proxies, virtual nodes, graphical constraint edges edges, and (v) an implementation.

9.2 Complexity Management of Graphical Data Modelling

Graphical data modelling, rooted in seminal works of database design such as entity relationship modelling [19], was taken-up by class modelling within the object-oriented paradigm [14] and subsequently applied to metamodeling to describe the abstract syntax of graphical languages. Metamodeling, FRAGMENTA's main application so far, is exemplified here with the metamodels of statecharts (section 5) and the Into-SysML profile (section 6).

Complexity management of data models, researched for over four decades [28, 34, 48–50], tackles the scalability issues arising in large data models [28, 49] caused by the limits in the human processing of information [46]. The proposed solutions to this problem reduce the amount of information, typically through abstraction or separation, which correspond to vertical or horizontal refinement, respectively.

Feldman and Miller [28]'s predominately vertical approach for entity-relationship diagrams (ERD) can be used in either a bottom-up or top-down fashion, making use of both abstraction and decomposition. Teory et al [62] elaborates [28] through a bottom-up method to identify abstractions. Moody [48, 49] changes the direction pursued until then towards horizontal refinement; a context data model indicates the main subject areas or fragments; each subject area has its own data model; proxies (*foreign entities* in [48, 49]) establish cross-subject relations.

These works are essentially methods with limited semi-formal linguistic support, stipulating how things are broken apart (decomposition), but eluding composition. FRAGMENTA, on the other hand, is mathematically defined with an underpinning theory of vertical refinement, decomposition through proxies, and composition through fragment union and resolution. Moody [48, 49]'s linguistic construct, a possible precursor of FRAGMENTA's proxy, is not accompanied by a mathematical study or implementation which delves into the construct's properties and intricacies, like is done in [7] and continued here; FRAGMENTA supports layering as [28], left out of [48, 49]. Moody's context data model, absent in [28], is akin to FRAGMENTA's GFG.

9.3 Multilevel Modelling

Metamodelling values multilevel modelling [1, 2, 12, 20, 22], seen as underpinning the relation between models and metamodels. FRAGMENTA opens up a new path in this area. Layering based on typing, which emphasises inheritance of explicitly stated properties — concrete layers inherit class properties of their abstract counter-parts —, gives way to refinement, which emphasises abstract modelling and the establishment of a structure or organisation which concrete layers must comply to. It is not explicitly-stated properties that are inherited — in the e-commerce example of section 4, such properties were inherited (or shared) through fragment reuse —, but some fundamental architecture capturing some essence of the modelled problem.

Stratification, the layered organisation of models, is a characteristic of multilevel modelling approaches. Two distinct models can be discerned, *stratified* and *meshed*, corresponding, respectively, to the *strict* and *loose* approaches to metamodelling of [12]. FRAGMENTA and MetaDepth [20, 21] are stratified — layers are separate descriptions related through morphisms. DeepTelos [38] and ML2 [29] are meshed — layering is embedded in a single description as relations within the same model, which implies absence of actual separation. The stratified model is more true to layering and separation of concerns. The meshed model can be criticised for being essentially uni-level modelling, as it relies on intra-model relations; the meshed model’s alleged superior flexibility comes at the cost of added complexity and reduced conceptual clarity.

Multilevel modelling approaches relate layers differently. MetaDepth, DeepTelos and ML2 rely on instantiation. FRAGMENTA resorts to refinement in addition to instantiation, used to relate type and instance strata and for extra-typing. The sole reliance on instantiation entails a dual interpretation of meta-classes; all approaches except FRAGMENTA follow the *clabject* model [1, 3, 12] — certain elements have a dual facet: classes for levels below, and objects or instances for levels above.

Instantiation depth control is a notable concern. Potency-based modelling [1, 3] relies on a *potency* or *level* attribute, a natural number prescribing instantiation depth — 0 means that a clabject is an instance, hence, not instantiatable. Potency-based MetaDepth [20, 21] relates levels through graph morphisms, which indicate the distance between the related levels (adjacent levels have a distance of 1). FRAGMENTA does not control instantiation depth; like MetaDepth, it relates layers through graph morphisms, but allows adjacent layers only; classes retain their class semantics irrespective of their level and may be instantiated provided they are not *ethereal* (neither abstract nor virtual); objects can only inhabit the instance stratum which cannot be further instantiated. DeepTelos and ML2 are rather unclear about the meta-levels involved. DeepTelos uses the concept of most general instances to define hierarchies of what are essentially types (or classes); ML2 also relies on type hierarchies; both DeepTelos and ML2, like FRAGMENTA, rely on chains of related elements; in DeepTelos and ML2, chains are grounded on the instantiation relation, whereas FRAGMENTA uses refinement. Instantiation depth control is, therefore, either based on *potencies* or *chained*.

Depth may be achieved in either a *transitive* or *mixed* fashion. FRAGMENTA is transitive as it relies on the transitivity of both refinement and morphism composition — elements from non-adjacent layers may only be indirectly and transitively related. MetaDepth, ML2 and DeepTelo are mixed as they provide direct, and indirect and transitive means.

All analysed approaches have a mathematical underpinning. FRAGMENTA and MetaDepth are based on algebraic graph theory, ML2 and DeepTelos on predicate logic.

Table 10 contrasts the analysed approaches with respect to stratification, the supported layering types (either refinement or instantiation), instantiation control, depth and formalism. With respect to separation as a means to

Research Work	Stratification	Inter-level relations	Instantiation control	Depth	Formalism
FRAGMENTA	stratified	instantiation and refinement	chained	transitive	graphs
MetaDepth [20, 21]	stratified	instantiation	potencies	mixed	graphs
DeepTelos [38]	meshed	instantiation	chained	mixed	predicate logic
ML2 [29]	meshed	instantiation	chained	mixed	predicate logic

Table 10. Classification of multilevel modelling approaches, according to stratification (*stratified* or *meshed*), layering (*instantiation*, or *instantiation and refinement*), instantiation depth control (*potencies* or *chained*), depth (*transitive* or *mixed*) and formalism (*graphs* or *predicate-logic*).

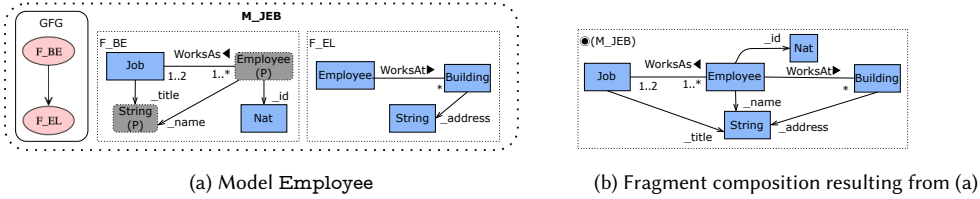


Fig. 33. The Employee example from [24] in FRAGMENTA.

control complexity, a tenet principle of this paper, both graph-based approaches, FRAGMENTA and MetaDepth, are better — their stratification ensures layer separation.

9.4 UML Modularity and Composition

Catalysis [25] divides a UML class model into subject areas, effectively fragments; it shares FRAGMENTA’s philosophy: different things can be said about something in different contexts. Catalysis relies on informal mechanisms of decomposition and composition, unlike FRAGMENTA.

UML groups model elements in *packages* [30, 53], akin to FRAGMENTA’s fragments but may contain both classes and collaborations. Larman [43] uses packages to separate subject areas. Two UML packaging mechanisms are relevant: *imports* and *merges*. Importing provides access to elements of imported packages [53]; merging builds bigger packages from smaller ones [24, 53]. Figure 33 renders in FRAGMENTA the UML package example of [24, p. 446].

UML package importing resembles FRAGMENTA’s referencing. When a fragment *A* references another, say *B*, it means that *A* may contain proxies referring to elements of either *B*, or of other fragment that *B* references, as per transitivity. In FRAGMENTA, elements are imported through proxies; in UML, importing brings elements into some context (or namespace). In Fig. 33a, proxies *String* and *Employee* in fragment *F_BE* materialise imports from *F_EL*. FRAGMENTA allows both a top-down and a bottom-up style of referencing and importing; models of sections 2 and 5 follow a traditional bottom-up style — elements are defined before the proxies that reference them —, whereas Fig. 33a follows a more top-down style — proxies are introduced first.

UML package merging resembles FRAGMENTA’s fragment resolution (or composition), which, unlike package merging, is mathematically defined, grounded on graph subsumption defined herein. Figure 33b shows the composition of Fig. 33a’s two fragments. Dingel et al [24] reports issues with package merging, proposing formal solutions which lack an accompanying implementation.

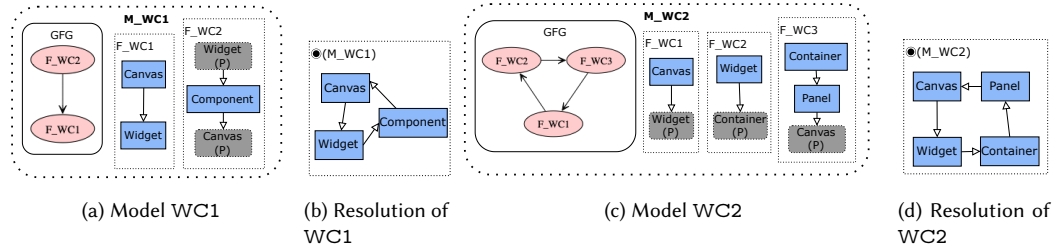


Fig. 34. Example models from [59] in FRAGMENTA, both invalid, and their malformed fragment resolutions

UML templates [53], another UML modularity and composition mechanism, provide flexible parametrisation means akin to FRAGMENTA’s template patterns obtained through virtuals, inheritance and derived edges as shown in Figs. 7f and 7g and discussed in section 8.5. Unlike FRAGMENTA, UML templates lack a formal underpinning.

9.5 Model Merging

Category theory’s colimit, proposed as a foundation for model merging [18], is at the heart of [57], which relies on *interconnection diagrams* to relate separate models²⁰. FRAGMENTA follows the same underpinning, but integrates proxies within the modelling, avoiding the separate representation.

Sabetzadeh et al [58, 59] builds up on [57] to detect inconsistencies when fragments are composed, such as the ones from section 3.3 (Figs. 12b and 12c). Figure 34 renders in FRAGMENTA models from [58, 59]. While [58, 59] spots the inheritance cycles of Fig. 34 from the merged model, FRAGMENTA does so locally without building the overall composition; fragment F_WC2 of Fig. 34a violates the constraint which prevents proxies from inheriting; the inheritance cycle resulting from model of Fig. 34c (see Fig. 34d) is caught through the GFG which includes a disallowed cycle. To avoid the manual *interconnection diagrams*, the separate representation relating fragments of [57–59], Nejati et al [51] resorts to an heuristic matcher to automate the interconnections. FRAGMENTA, illustrated in Fig. 34, constructs fragmented models through proxies, which precludes both manually built *interconnection diagrams* and complicated matching algorithms — only the proxy’s referent needs to be provided. Like [51, 57–59], FRAGMENTA supports a single mode of inheritance, but provides *virtuals* to overcome its restrictions. Model composition mechanics of [51, 57–59] is pair-wise; the overall composition is built incrementally with big models requiring many smaller compositions. FRAGMENTA builds the overall composition in two steps: the different fragments are composed using union composition, and the overall composition is obtained from the union fragment through resolution. The optimisations of Rubin and Chechik [55] to tackle the inefficiencies of pair-wise composition are unable to improve the NP complexity of the matching algorithms.

10 CONCLUSIONS

Graphical data (or conceptual) modelling, software engineering’s most widely used form of modelling, is here given an uplift. The field’s roots can be traced back to Chen’s work on entity-relationship modelling in the 1970s [19], extended to embrace the ideas of object-oriented (OO) modelling in the 1980s [14, 16, 17, 56] and subsequently applied to metamodeling, widely used to define the abstract syntax of graphical languages, in the 1990s [12]. The paper proposes a substantiated solution to the problem of complexity management, researched for four decades. Mainstream OO modelling’s core concepts were established in the early 1990s without any substantial primitives added ever since. This

²⁰The models from [18, 57], not far from Fig. 33, require an extra representation to relate elements from different fragments.

paper uplifts OO modelling through an upgrade to the novel FRAGMENTA class modelling framework, initially proposed in [7], following the vein of innovative OO and graphical modelling research discussed in section 9.

Section 2 presents and motivates FRAGMENTA with a layered model, involving an abstract representation of hotels in general and a concrete realisation (a refinement) as a more complex hotel for pets. This illustrates FRAGMENTA's major novelties, namely, vertical refinement as the basis of the layering, horizontal refinement to manage the complexity of the pets world model with proxies acting as modelling entities and composition joints, virtuals to express intricate inheritance relations, and graphical constraints to state graphically what is usually stated textually.

Section 3 defines FRAGMENTA mathematically by uplifting [7]. The theory is built incrementally, starting from graphs, and then on to structural graphs, the different kinds of morphisms, fragments, GFGs and models. This includes the major horizontal refinement improvement of *fragment resolution* (or composition), the new vertical refinement inspired by data refinement [35], which enables multilevel modelling, and the partial extra typings, another multilevel modelling ingredient.

Sections 4 to 6 illustrate FRAGMENTA with: (i) a layered model of an e-commerce application, similar to a benchmark model of multilevel modelling (section 4), (ii) a statecharts metamodel (section 5), and (iii) a metamodel of a SysML profile for cyber-physical systems (section 6). These illustrations use a two-layered metamodel, highlighting vertical refinement's capacity to articulate essence and detail. The several fragmented models, with its panoply of detailed properties expressed visually, showcase FRAGMENTA's graphical expressiveness and horizontal refinement.

Section 7 evaluates FRAGMENTA to appraise its adequacy and effectiveness. It concludes that FRAGMENTA, supported by its novelties, is overall better than the compared approaches, a prominent FRAGMENTA advantage being graphical expressiveness.

Section 8 discusses the results of the paper, highlighting characteristics of FRAGMENTA and its novelties, and the way it was developed. Section 9 discusses related work from different related areas of research.

FRAGMENTA is exercised here with four major case studies, which although not excessively large, are sufficiently large and interesting to highlight its capabilities, which proved advantageous in a comparison to related approaches in section 7's evaluation. This supports FRAGMENTA's suitability for large-scale modelling. The paper's main contributions are as follows:

- FRAGMENTA is the first graphical and formal data modelling framework supporting both vertical (layering) and horizontal (decomposition or fragmentation) refinement.
- FRAGMENTA's novel layered architecture based on two strata, type and instance, where the type stratum may be further divided into layers through vertical refinement. In addition, models may have extra typings within the same layer. Vertical refinement is a novel application of ideas linked to formal data refinement, hitherto scarcely explored in the areas of data- (or conceptual-) and meta-modelling.
- Fragment composition (or resolution) formally defined using graph subsumption enhances and substantiates the novel proxy. To the author's knowledge, no other work gave this much depth to the proxy concept, key to horizontal refinement and fragmented modelling.
- The notational novelties of (i) virtuals, which enhance inheritance, and (ii) derived, value-constraint and path edges, which enhance graphical constraint modelling.
- FRAGMENTA's Haskell implementation²¹ attests to FRAGMENTA's realisability, enables experimentation, and contributed considerably to the quality of the work presented here.

²¹ available from <https://github.com/namalio/Fragmenta>

RQ	Contributions
RQ1	FRAGMENTA is the first formal data-modelling framework supporting both vertical and horizontal refinement, which are mechanisms of abstraction and modularity, respectively.
RQ2	FRAGMENTA proposes a layered architecture based on two strata, type and instance; the type stratum may be further divided into layers through vertical refinement; extra typings say that elements from one model are typed by elements of another.
RQ3	The paper introduces several novelties: (i) fragment composition along proxies, defined as graph subsumption, improves horizontal refinement, (ii) virtuals make inheritance more agile, and (iii) derived, value-constraint and path edges enhance graphical constraint expressivity.
RQ1, RQ2, RQ3	FRAGMENTA's adequacy with respect to large scale modelling is exercised with four case studies, which although not excessively large, are sufficiently large and interesting to highlight FRAGMENTA's capabilities which proved advantageous in an evaluation against related approaches (section 7). One case study is a benchmark problem of multilevel modelling; two case studies involve industrial languages, namely, statecharts, a UML notation, and the Into-SysML profile, which involves two SysML notations.
RQ1, RQ2, RQ3	FRAGMENTA's Haskell implementation is a minor contribution which attests to FRAGMENTA's realisability; it enables experimentation with the framework and is a contributor to the quality of the work presented here. All layered models and examples presented in the paper were checked using the tool.

Table 11. Summary of the paper's contributions per research question (RQ).

Table 11 summarises the paper's contributions for each research question raised in section 1.1.

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A AUXILIARY DEFINITIONS

DEFINITION 1 (SETS). Set membership $\in$, set containment $\subseteq$, powersets $\mathbf{P}$ and the empty set $\emptyset$ are defined as:

$$x \in S \Leftrightarrow \exists y : S \bullet x = y \quad S \subseteq T \Leftrightarrow \forall x : S \bullet x \in T \quad \mathbf{P} X = \{S \mid S \subseteq X\} \quad \emptyset X = \{x \mid \neg x \in X\}$$

Set operations union $\cup$, intersection $\cap$ and subtraction $\setminus$ are defined as:

$$A \cup B = \{x \mid x \in A \vee x \in B\} \quad A \cap B = \{x \mid x \in A \wedge x \in B\} \quad A \setminus B = \{x \mid x \in A \wedge x \notin B\}$$

Non-empty powersets $\mathbf{P}_1$, and optionality (either a singleton or the empty set) are defined as:

$$\mathbf{P}_1 X = \{S \mid S \in \mathbf{P} X \wedge S \neq \emptyset\} \quad \mathbf{opt} X = \{s : \mathbf{P} X \mid (\exists x : X \bullet s = \{x\}) \vee s = \emptyset\}$$

□

DEFINITION 2 (RELATIONS). Operator $\leftrightarrow$ denotes a relation (a set of pairs) between two given sets; id builds the identity relation over a given set; and operator $\sim$ inverts a given relation:

$$X \leftrightarrow Y = \{(x, y) \mid x \in X \wedge y \in Y\} \quad \text{id } X = \{(x, x) \mid x \in X\} \quad r \sim = \{(y, x) \mid (x, y) \in r\}$$

Domain and range of a relation may be obtained using functions dom and ran , respectively:

$$\text{dom } r = \{x \mid \exists y : \text{ran } r \bullet (x, y) \in r\} \quad \text{ran } r = \{y \mid \exists x : \text{dom } r \bullet (x, y) \in r\}$$

Operators for domain ($\triangleleft$) and range ($\triangleright$) restriction, domain ($\trianglelefteq$) and range ($\trianglerighteq$) subtraction, and relational image ($\llbracket \rrbracket$) are defined as:

$$S \triangleleft r = \{r' \mid r' \subseteq r \wedge \text{dom } r' \subseteq S\} \quad r \triangleright S = \{r' \mid r' \subseteq r \wedge \text{ran } r' \subseteq S\}$$

$$S \trianglelefteq r = (\text{dom } r \setminus S) \triangleleft r \quad r \trianglerighteq S = r \triangleright (\text{ran } r \setminus S) \quad r \llbracket S \rrbracket = \text{ran}(S \triangleleft r)$$

Operator $\circ$ composes two relations; $\circ$ does the backward composition of relations; $^+$ and * give, respectively, the transitive and the reflexive-transitive closure of a relation $X \leftrightarrow X$, and operator $\oplus$ denotes the relational overriding of a relation within

another::

$$r \circ s = \{(x, z) \mid \exists y : \text{ran } r \bullet (x, y) \in r \wedge (y, z) \in s\} \quad g \circ f = f \circ g$$

$$r^+ = \begin{cases} r & \text{if } r \circ r \subseteq r \\ r \circ r & \text{otherwise} \end{cases} \quad r^* = r^+ \cup \text{id}(\text{dom } r) \quad r \oplus s = (\text{dom } s) \triangleleft r \cup s$$

Relations acyclic, injective and antireflexive are built from generic sets X and Y :

$$\text{acyclic } X = \{r \mid r \in X \leftrightarrow X \wedge r^+ \cap \text{id } X = \emptyset\} \quad \text{injrel } X Y = \{r \mid r \in X \leftrightarrow Y \wedge r^\sim \in Y \leftrightarrow X\}$$

$$\text{antireflexive } X = \{r \mid r \in X \leftrightarrow X \wedge r \cap \text{id } X = \emptyset\}$$

Above, $\cap$ is set intersection and $\emptyset$ is the empty set (def. 1). $\square$

DEFINITION 3 (FUNCTIONS). *Partial ($\rightarrow$), total ($\twoheadrightarrow$), injective ($\rightarrow$), surjective ($\twoheadrightarrow$) and bijective ($\leftrightarrow$) functions are defined from relations (def. 2):*

$$X \rightarrow Y = \{f \mid f \in X \leftrightarrow Y \wedge \forall x : X ; y_1, y_2 : Y \mid (x, y_1) \in f \wedge (x, y_2) \in f \bullet y_1 = y_2\}$$

$$X \twoheadrightarrow Y = \{f \mid f \in X \twoheadrightarrow Y \wedge \text{dom } f = X\} \quad X \mapsto Y = \{f \mid f \in X \mapsto Y \wedge f^\sim \in Y \twoheadrightarrow X\}$$

$$X \mapsto Y = \{f \mid f \in X \mapsto Y \wedge f^\sim \in Y \twoheadrightarrow X\} \quad X \twoheadrightarrow Y = \{f \mid f \in X \twoheadrightarrow Y \wedge \text{ran } f = Y\}$$

$$X \mapsto Y = \{f \mid f \in X \mapsto Y \wedge f \in X \twoheadrightarrow Y\}$$

Trees are those acyclic relations (see def. 2) over some set X which are partial functions:

$$\text{tree } X = \{r \mid r \in X \leftrightarrow X \wedge r \in \text{acyclic} \wedge r \in X \twoheadrightarrow X\}$$

$\square$

DEFINITION 4 (GENERIC FUNCTIONS AND PREDICATES). *The generic functions defined below are as follows: (i) apply does a pairwise function application, (ii) the takes the value of an optional set, (iii) $\boxtimes$ totalises a partial function within a set, and (iv) $^\oplus$ is the closure of relation composition with respect to relation override, which stretches a relation by getting only the end points of a transitive closure:*

$$\text{apply}[X, Y, Z, W] : ((X \rightarrow Z) \times (Y \rightarrow W)) \rightarrow (X \times Y) \rightarrow (Z \times W) \quad \text{the} : \text{opt}[X] \twoheadrightarrow X$$

$$\text{apply}(f, g)(x, y) = (f \ x, g \ y) \quad \text{the } \{x\} = x$$

$$_ \boxtimes _ : (X \rightarrow X) \times \mathbf{P} X \rightarrow (X \twoheadrightarrow X) \quad _^\oplus : (X \leftrightarrow X) \rightarrow (X \leftrightarrow X)$$

$$f \boxtimes A = (\text{id } A) \oplus f$$

$$r^\oplus = \begin{cases} r & \text{if } (r \circ r) = r \\ r \oplus (r \circ r)^\oplus & \text{otherwise} \end{cases}$$

Above, $\oplus$ is relation override and $\circ$ is relational composition (def. 2).

Predicates $=_p$ and $\subseteq_p$ are pairwise equality and set containment:

$$(xs, ys) =_p (zs, ws) \Leftrightarrow xs = zs \wedge ys = ws \quad (xs, ys) \subseteq_p (zs, ws) \Leftrightarrow xs \subseteq zs \wedge ys \subseteq ws$$

Laws. *The following laws were proved in Isabelle:*

$$\vdash f \boxtimes \emptyset = f \quad \vdash \emptyset \boxtimes s = (\text{id } s) \quad \vdash f \boxtimes (A \cup B) = f \boxtimes A \cup f \boxtimes B$$

$$r \in X \twoheadrightarrow Y \vdash r^\oplus \in X \twoheadrightarrow Y \quad \vdash \text{ran}(f \boxtimes s) = s \setminus \text{dom } f \cup \text{ran } f$$

□

DEFINITION 5 (VERTICES AND EDGES). Disjoint sets V and E represent all possible nodes and edges of graphs, respectively.

□

DEFINITION 6 (NUMERIC NODES). Special nodes designate the numeric sets, namely:

$$nNatS : V \quad nIntS : V \quad nRealS : V$$

These denote (from left to right) the natural numbers, the integers and the reals, respectively.

There are also functions which extract either the integer or real number embedded in a node:

$$to\mathbb{Z} : V \rightarrow \text{opt}[\mathbb{Z}] \quad to\mathbb{R} : V \rightarrow \text{opt}[\mathbb{R}]$$

$to\mathbb{Z}$ and $to\mathbb{R}$ above yield an optional (opt, def. 1), which yields a singleton with the extracted number if there is a number embedded in the node, or the empty set otherwise. □

DEFINITION 7 (GRAPHS). A graph $G = (N, A, s, t)$ consists of sets $N \subseteq V$ and $A \subseteq E$ of nodes and edges respectively, and source and target functions $s, t : A \rightarrow N$.

The set of graphs Gr , such that $G : Gr$, is defined as:

$$Gr = \{(N, A, s, t) \mid N \in \mathbf{P} V \wedge A \in \mathbf{P} E \wedge s \in A \rightarrow N \wedge t \in A \rightarrow N\}$$

Functions Ns , Es , src and tgt extract the different components of a graph:

$$Ns(N, A, s, t) = N \quad Es(N, A, s, t) = A \quad src(N, A, s, t) = s \quad tgt(N, A, s, t) = t$$

Function Els yields a pair with the given graph's nodes and edges; $\emptyset_G$ yields the empty graph:

$$Els G = (Ns G, Es G) \quad \emptyset_G = (\emptyset, \emptyset, \emptyset, \emptyset)$$

□

DEFINITION 8 (GRAPH FUNCTIONS). Several functions (below) operate upon a given graph G : (i) $EsId$ yields G 's identity edges, (ii) $rNs G es$ gives G 's nodes connected by set of edges es , (iii) $G \bowtie_{Es} es$ restricts G to set of edges es , (iv) $G \bowtie_{Ns} vs$ restricts G to set of nodes vs , and (v) $G \ominus_{Ns} vs$ removes set of nodes vs from G .

$$EsId : Gr \rightarrow \mathbf{P} E \quad rNs : Gr \rightarrow \mathbf{P} E \quad \bowtie_{Es} : (Gr \times \mathbf{P} E) \rightarrow Gr \quad \bowtie_{Ns}, \ominus_{Ns} : (Gr \times \mathbf{P} V) \rightarrow Gr$$

$$EsId_G = \{e : Es_G \mid src_G e = tgt_G e\} \quad rNs G es = ran(es \triangleleft src_G) \cup ran(es \triangleleft tgt_G)$$

$$G \bowtie_{Es} es = (rNs_G es, Es_G \cap es, es \triangleleft src_G, es \triangleleft tgt_G)$$

$$G \bowtie_{Ns} vs = (Ns_G \cap vs, G \bullet \bullet vs, (G \bullet \bullet vs) \triangleleft src_G, (G \bullet \bullet vs) \triangleleft tgt_G)$$

$$G \ominus_{Ns} vs = (Ns_G \setminus vs, Es_G \setminus (G \circ \circ vs), (G \circ \circ vs) \triangleleft src_G, (G \circ \circ vs) \triangleleft tgt_G)$$

Above, $\triangleleft$ and $\trianglelefteq$ are relational domain restriction and subtraction, respectively (def. 2).

Notion of adjacency is captured by two functions: (i) $adjacent(G, v_1, v_2)$ says whether nodes v_1, v_2 are adjacent in G , (ii) $adjacent_E(G, e_1, e_2)$ says whether edges e_1, e_2 are adjacent in G .

$$adjacent_- : \mathbf{P}(Gr \times V \times V) \quad adjacent_E_- : \mathbf{P}(Gr \times E \times E)$$

$$adjacent(G, v_1, v_2) \Leftrightarrow \exists e : Es_G \bullet src_G e = v_1 \wedge tgt_G e = v_2 \quad adjacent_E(G, e_1, e_2) \Leftrightarrow src_G e_1 = tgt_G e_2$$

Other functions explore notions of connectedness and incidence: (i) $G \circ \rightarrow \circ vs$ yields G 's edges incident to nodes vs (edges with the nodes as either source or target), and (ii) $G \bullet \leftrightarrow \bullet ns$ yields G 's edges connecting set of nodes vs (edges with the nodes as both source and target).

$$\begin{aligned} & _ \circ \rightarrow \circ _ , _ \bullet \leftrightarrow \bullet _ : Gr \times \mathbf{P} V \rightarrow \mathbf{P} \\ & G \circ \rightarrow \circ vs = src_G \sim \langle \langle vs \rangle \rangle \cup tgt_G \sim \langle \langle vs \rangle \rangle \quad G \bullet \leftrightarrow \bullet ns = src_G \sim \langle \langle vs \rangle \rangle \cap tgt_G \sim \langle \langle vs \rangle \rangle \end{aligned}$$

Several functions build new structures from graphs: (i) $G^{\rightleftharpoons}$ gives the graph that takes G and inverts its edges: (ii) $G^{\leftrightarrow}$ builds G 's node adjacency relation, (iii) $G^{\leftrightarrow E}$, builds G 's edge adjacency relation, and (iv) $G_1 \cup_G G_2$ constructs the union of graphs G_1 and G_2 .

$$\begin{aligned} & _ \rightleftharpoons : Gr \rightarrow Gr \quad _ \leftrightarrow : Gr \rightarrow V \leftrightarrow V \quad _ \leftrightarrow E : Gr \rightarrow E \leftrightarrow E \quad _ \cup_G _ : Gr \times Gr \rightarrow Gr \\ & G^{\rightleftharpoons} = (Ns_G, Es_G, tgt_G, src_G) \\ & G^{\leftrightarrow} = \{(v_1, v_2) \mid adjacent(G, v_1, v_2)\} \quad G^{\leftrightarrow E} = \{(e_1, e_2) \mid adjacent_E(G, e_1, e_2)\} \\ & G_1 \cup_G G_2 = (Ns_{G_1} \cup Ns_{G_2}, Es_{G_1} \cup Es_{G_2}, src_{G_1} \cup src_{G_2}, tgt_{G_1} \cup tgt_{G_2}) \end{aligned}$$

Above, graph union is defined as the set union (symbol $\cup$, def. 1) of the graph's components.

Graph subsumption (symbol $\odot$) replaces nodes according to a replacement mapping:

$$\begin{aligned} & _ \odot _ : Gr \times (V \leftrightarrow V) \rightarrow Gr \\ & G \odot s = \begin{cases} (Ns_G \setminus \text{dom } s \cup \text{ran } s, Es_G, (s \boxtimes Ns_G) \circ src_G, (s \boxtimes Ns_G) \circ tgt_G) & \text{if } s \in Ns_G \leftrightarrow Ns_G \\ G & \text{otherwise} \end{cases} \end{aligned}$$

Above, the substitution mapping s is a partial function covering the nodes of given graph G . The subsumed graph includes the graph's nodes minus subsumed nodes, the edges remain the same, and the source and target functions are totalised within node identity through function $\boxtimes$ (def. 4) — subsumed nodes are substituted, and the rest remains the same.

The following predicates capture useful conditions. $\odot$ says whether a graph is acyclic, $\boxtimes$ says whether two graphs are disjoint (no nodes or edges in common), and $\boxplus$ generalises $\boxtimes$ for any number of graphs:

$$\begin{aligned} & \odot _ : \mathbf{P} Gr \quad \boxtimes_{Es}, \boxtimes _ : \mathbf{P}(Gr \times Gr) \quad \boxplus _ : \mathbf{P}(I \leftrightarrow Gr) \\ & \odot G \Leftrightarrow G^{\leftrightarrow E} \in \text{acyclic} \quad \boxtimes_{Es}(G_1, G_2) \Leftrightarrow Es G_1 \cap Es G_2 = \emptyset \\ & \boxplus(G_1, G_2) \Leftrightarrow Ns G_1 \cap Ns G_2 = \emptyset \wedge \boxtimes_{Es}(G_1, G_2) \quad \boxplus Gs[I] \Leftrightarrow \forall i, j : \text{dom } Gs \mid i \neq j \bullet \boxplus(Gs i, Gs j) \end{aligned}$$

Above, set I is any indexing set. $\odot$ checks whether the graph's edge relation is acyclic (def. 2).

Laws. The following laws were proved in Isabelle:

$$\begin{aligned}
& \exists(G_1, G_2) \vdash \exists_{Es}(G_1, G_2) \quad G_1, G_2 \in Gr \vdash G_1 \cup_G G_2 \in Gr \quad G \in Gr \vdash G \cup_G \emptyset_G = G \\
& G_1, G_2 \in Gr; \exists_{Es}(G_1, G_2) \vdash G_1 \cup_G G_2 = G_2 \cup_G G_1 \quad G_1, G_2 \in Gr \vdash \exists(G_1, G_2) = \exists(G_2, G_1) \\
& G_1, G_2 \in Gr \vdash \exists_{Es}(G_1, G_2) = \exists_{Es}(G_2, G_1) \\
& G_1, G_2 \in Gr; \exists_{Es}(G_1, G_2) \vdash \text{adjacent}(G_1 \cup_G G_2, x, y) \Leftrightarrow \text{adjacent}(G_1, x, y) \vee \text{adjacent}(G_2, x, y) \\
& G_1, G_2 \in Gr; \exists_{Es}(G_1, G_2) \vdash (G_1 \cup_G G_2)^{\leftrightarrow} = G_1^{\leftrightarrow} \cup_G G_2^{\leftrightarrow} \\
& G_1, G_2 \in Gr; \exists_{Es}(G_1, G_2) \vdash rNs(G_1 \cup_G G_2) es = rNs G_1 es \cup rNs G_2 es \quad G \in Gr \vdash rNs G es \subseteq Ns G \\
& G_1, G_2 \in Gr; \exists(G_1, G_2) \vdash rNs G_1 es_1 \cap rNs G_2 es_2 = \emptyset \\
& G \in Gr \vdash G \bowtie_{Es} es \in Gr \quad G_1, G_2 \in Gr; \exists(G_1, G_2) \vdash \exists(G_1 \bowtie_{Es} es, G_2 \bowtie_{Es} es) \\
& \vdash \emptyset_G \bowtie_{Es} es = \emptyset_G \quad G \in Gr \vdash G \bowtie_{Es} \emptyset = \emptyset_G \quad G \in Gr \vdash (G \bowtie_{Es} es) \in Gr \\
& G_1, G_2 \in Gr; \exists_{Es}(G_1, G_2) \vdash (G_1 \cup_G G_2) \bowtie_{Es} es = G_1 \bowtie_{Es} es \cup_G G_2 \bowtie_{Es} es \\
& G \in Gr; es_b \cap Es_G = \emptyset \vdash G \bowtie_{Es} (es_a \cup es_b) = G \bowtie_{Es} es_a \\
& G \in Gr; s \in rNs G es \leftrightarrow rNs G es \vdash (G \odot s) \bowtie_{Es} es = (G \bowtie_{Es} es) \odot s \quad \vdash \emptyset_G \multimap ns = \emptyset \\
& G \in Gr \vdash G \multimap Ns_G = Es_G \quad G \in Gr \vdash G \multimap \emptyset = \emptyset \quad G \in Gr \vdash (G \multimap ns) \subseteq Es_G \\
& G_1, G_2 \in Gr; \exists_{Es}(G_1, G_2) \vdash (G_1 \cup_G G_2) \multimap vs = G_1 \multimap vs \cup_G G_2 \multimap vs \\
& G \in Gr; vs \cap Ns_G = \emptyset \vdash G \multimap vs = \emptyset \quad \vdash \emptyset_G \bullet \bullet ns = \emptyset \\
& G \in Gr \vdash G \bullet \bullet Ns_G = Es_G \quad G \in Gr \vdash G \bullet \bullet \emptyset = \emptyset \quad G \in Gr \vdash (G \bullet \bullet ns) \subseteq Es_G \\
& G_1, G_2 \in Gr; \exists_{Es}(G_1, G_2) \vdash (G_1 \cup_G G_2) \bullet \bullet vs = G_1 \bullet \bullet vs \cup_G G_2 \bullet \bullet vs \quad \vdash \emptyset_G \overset{\rightharpoonup}{=} \emptyset_G \\
& G \in Gr \vdash (G \overset{\rightharpoonup}{=}) \overset{\rightharpoonup}{=} G \quad G \in Gr \vdash (G \overset{\rightharpoonup}{=})^{\leftrightarrow} = (G^{\leftrightarrow})^{\sim} \quad G_1, G_2 \in Gr \vdash (G_1 \cup_G G_2) \overset{\rightharpoonup}{=} G_1 \overset{\rightharpoonup}{=} \cup_G G_2 \overset{\rightharpoonup}{=} \\
& G \in Gr \vdash G \odot \emptyset = G \quad G \in Gr \vdash G \odot \text{id}(Ns_G) = G \quad \vdash \emptyset_G \odot s = \emptyset_G \quad G \in Gr \vdash (G \odot s) \in Gr \\
& G \in Gr \vdash G \bowtie_{Ns} \emptyset = \emptyset_G \quad \vdash \emptyset_G \bowtie_{Ns} ns = \emptyset_G \quad G \in Gr \vdash (G \bowtie_{Ns} ns) \in Gr \quad G \in Gr \vdash G \ominus_{Ns} \emptyset = G \\
& \vdash \emptyset_G \ominus_{Ns} ns = \emptyset_G \quad G \in Gr \vdash (G \ominus_{Ns} ns) \in Gr \quad G \in Gr \vdash G \ominus_{Ns} ns_a \cup ns_b = G \ominus_{Ns} ns_a \ominus_{Ns} ns_b \\
& G_1, G_2 \in Gr; \exists_{Es}(G_1, G_2) \vdash G_1 \cup_G G_2 \ominus_{Ns} ns = G_1 \ominus_{Ns} ns \cup_G G_2 \ominus_{Ns} ns \\
& \exists_{Es}(G_1, G_2) \vdash \exists_{Es}(G_1 \ominus_{Ns} ns_1, G_2 \ominus_{Ns} ns_2) \quad G_1, G_2 \in Gr; \exists(G_1, G_2) \vdash \odot(G_1 \cup_G G_2) \Leftrightarrow \odot G_1 \wedge \odot G_2
\end{aligned}$$

□

DEFINITION 9 (GRAPH MORPHISMS). Graph morphisms map elements of one graph onto another. A total graph morphism f between graphs $G_1, G_2 : Gr$ (see def. 7), written $f : G_1 \rightarrow_G G_2$, is a pair of total functions (see def. 4) $f = (f_V, f_E)$, $f_V : Ns_{G_1} \rightarrow Ns_{G_2}$ and $f_E : Es_{G_1} \rightarrow Es_{G_2}$, which map nodes and edges, respectively, and must preserve the source and target functions of edges: $f_V \circ \text{src}_{G_1} = \text{src}_{G_2} \circ f_E$ and $f_V \circ \text{tgt}_{G_1} = \text{tgt}_{G_2} \circ f_E$.

In partial graph morphisms between graphs $G_1, G_2 : Gr$, written $f : G_1 \rightarrow_G G_2$, the morphism functions may be partial (see def. 4): $f_V : Ns_{G_1} \rightarrow Ns_{G_2}$ and $f_E : Es_{G_1} \rightarrow Es_{G_2}$. The commuting equations change to: $f_V \circ ((\text{dom } f_E) \triangleleft \text{src}_{G_1}) = \text{src}_{G_2} \circ f_E$ and $f_V \circ ((\text{dom } f_E) \triangleleft \text{tgt}_{G_1}) = \text{tgt}_{G_2} \circ f_E$; here, functions source and target are restricted to the edges mapped by morphism f only.

Set GrM defines all possible graph morphisms:

$$GrM = \{(f_V, f_E) \mid f_V \in V \rightarrow V \wedge f_E \in E \rightarrow E\}$$

Sets of total, $G_1 \rightarrow_G G_2$ and partial $G_1 \rightarrowtail_G G_2$ morphisms, such that $G_1 \rightarrow_G G_2 \subseteq GrM$ and $G_1 \rightarrowtail_G G_2 \subseteq GrM$, are defined as:

$$\begin{aligned} G_1 \rightarrow_G G_2 &= \{(fv, fe) \mid fv \in Ns_{G_1} \rightarrow Ns_{G_2} \wedge fe \in Es_{G_1} \rightarrow Es_{G_2} \\ &\quad \wedge fv \circ src_{G_1} = src_{G_2} \circ fe \wedge fv \circ tgt_{G_1} = tgt_{G_2} \circ fe\} \\ G_1 \rightarrowtail_G G_2 &= \{(fv, fe) \mid fv \in Ns_{G_1} \rightarrowtail Ns_{G_2} \wedge fe \in Es_{G_1} \rightarrowtail Es_{G_2} \\ &\quad \wedge fv \circ ((\text{dom } fe) \triangleleft src_{G_1}) = src_{G_2} \circ fe \wedge fv \circ ((\text{dom } fe) \triangleleft tgt_{G_1}) = tgt_{G_2} \circ fe\} \end{aligned}$$

Above, the equations involving function composition (symbol $\circ$) ensure diagram commutativity.

Several relevant functions operating on graph morphisms are defined below. Projection functions f_V and f_E extract the two components of a graph morphism. Functions gid and $\emptyset_{GM}$ yield a graph's identity and empty morphisms, respectively. Functions $domg$, and $codg$ yield the domain and co-domain of a morphism, respectively.

$$\begin{aligned} f_V : GrM &\rightarrow V \rightarrowtail V & f_E : GrM &\rightarrow E \rightarrowtail E & gid : Gr &\rightarrow GrM & \emptyset_{GM} : GrM \\ f_V(fv, fe) &= fv & f_E(fv, fe) &= fe & gid &= (id \ Ns \ G, id \ Es \ G) & \emptyset_{GM} &= (\{\}, \{\}) \\ domg \ m &= (dom(f_V \ m), dom(f_E \ m)) & codg \ m &= (ran(f_V \ m), ran(f_E \ m)) \end{aligned}$$

Laws. The following laws were proved in Isabelle:

$$\begin{aligned} \vdash gid \ \emptyset_G &= \emptyset_{GM} \quad G \in Gr \vdash gid \ G \in G \rightarrow_G G \quad \vdash domg \ \emptyset_{GM} =_p \text{Els} \ \emptyset_G \quad \vdash codg \ \emptyset_{GM} =_p \text{Els} \ \emptyset_G \\ f \in G_1 \rightarrow_G G_2 \vdash domg \ f &=_p \text{Els} \ G1 \quad f \in G_1 \rightarrow_G G_2 \vdash codg \ f \subseteq_p \text{Els} \ G2 \\ f \in G_1 \rightarrowtail_G G_2 \vdash domg \ f &\subseteq_p \text{Els} \ G1 \quad f \in G_1 \rightarrowtail_G G_2 \vdash codg \ f \subseteq_p \text{Els} \ G2 \\ f \in G_1 \rightarrow_G G_2 \vdash f \in G_1 \rightarrowtail_G G_2 \end{aligned}$$

□

DEFINITION 10 (COMPOSITION OF GRAPH MORPHISMS). The functional composition of graph morphisms $f : G_1 \rightarrow_G G_2$ and $g : G_2 \rightarrow_G G_3$, where $G_i \in \{1,3\} : Gr$, is defined as:

$$g \circ_G f = ((f_V \ g) \circ (f_V \ f), (f_E \ g) \circ (f_E \ f))$$

Operators union composition $\cup_{GM}$ and generalised union composition $\bigcup_{GM}$ are defined as:

$$\begin{aligned} _ \cup_{GM} _ : GrM \times GrM &\rightarrow GrM & \bigcup_{GM} _ : \mathbf{P} \ GrM &\rightarrow GrM \\ f \cup_{GM} g &= (f_V \ f \cup f_V \ g, f_E \ f \cup f_E \ g) \\ \bigcup_{GM} \emptyset &= \emptyset_{GM} \\ \bigcup_{GM} (\{f\} \cup fs) &= f \cup_{GM} (\bigcup_{GM} fs) \end{aligned}$$

Laws. The following laws were proved in Isabelle:

$$\begin{aligned} f \in G_1 \rightarrow_G G_2 ; g \in G_2 \rightarrow_G G_3 \vdash g \circ_G f \in G1 \rightarrow_G G3 &\quad \vdash (h \circ_G g) \circ_G f = h \circ_G (g \circ_G f) \\ f \in G_1 \rightarrow_G G_2 ; g \in G_2 \rightarrow_G G_3 ; \boxplus \langle G_1, G_2, G_3 \rangle \vdash f \cup_{GM} g \in (G_1 \cup_{GM} G_2) \rightarrow_G (G_3 \cup_{GM} G_4) \\ f \in G_1 \rightarrow_G G_2 \vdash f \circ_G gid_{G1} = f &\quad f \in G_1 \rightarrow_G G_2 \vdash gid_{G2} \circ_G f = f \end{aligned}$$

□

DEFINITION 11 (GRAPHS WITH TYPING). A graph with typing is a pair $GwT = (G, t)$, made-up of a graph $G : Gr$ and a morphism $t : GrM$, such that $domg\ t =_p\ Els\ G$ (the morphism's domain is G 's nodes and edges). The set of such graphs $GrwT$, such that $GwT : GrwT$, is defined as:

$$GrwT = \{(G, t) \mid G \in Gr \wedge t \in GrM \wedge domg\ t =_p\ Els\ G\}$$

The following projection functions extract the elements of such graphs:

$$(G, t)^G = G \quad (G, t)^T = t$$

The empty element $(\emptyset_{GwT})$ and union composition $(\cup_{GwT})$ are defined as follows:

$$\emptyset_{GwT} = (\emptyset_G, \emptyset_{GM}) \quad (G_1, t_1) \cup_{GwT} (G_2, t_2) = (G_1 \cup_G G_2, t_1 \cup_{GM} t_2)$$

□

DEFINITION 12 (GRAPHS WITH EXTRA TYPING). A graph with extra typing is a pair $GwET = (G, et)$, made-up of a graph with typing $G : GrwT$ (def. 11) and a partial morphism $et : GrM$, such that $domg\ et \subseteq_p\ Els\ G$ (the morphism's domain is a subset of G 's nodes and edges). The set of such graphs $GrwET$, such that $GwET : GrwET$, is defined as:

$$GrwET = \{(Gwt, et) \mid Gwt \in GrwT \wedge et \in GrM \wedge domg\ et \subseteq_p\ Els\ Gwt\}$$

The following projection functions extract the elements of such graphs:

$$(Gwt, et)^{Gw} = G \quad (Gwt, et)^{ET} = et \quad (Gwt, et)^G = Gwt^G \quad (Gwt, et)^T = Gwt^T$$

The empty element $(\emptyset_{GwET})$ and union composition $(\cup_{GwET})$ are defined as:

$$\emptyset_{GwET} = (\emptyset_{Gwt}, \emptyset_{GM}) \quad (G_1, et_1) \cup_{GwET} (G_2, et_2) = (G_1 \cup_{GwT} G_2, et_1 \cup_{GM} et_2)$$

□

DEFINITION 13 (SG NODE AND EDGE TYPES). SG 's node types (set $SGNT$) are: normal, abstract, proxy, enumeration, value, and virtual. SG 's edge types (set $SGET$) are: inheritance, composition (or containment), relation, derived, path and value constraint. Composition and relation edges can be either bi-directional or uni-directional.

$$\begin{aligned} SGNT &= \{nnrml, nabst, nprxy, nenum, nval, nvirt\} \\ SGET &= \{et \mid et \in \{einh, eder, epath, evcnt\} \\ &\quad \vee et \in \{ae\ d \mid ae \in \{ecomp, erel\} \wedge d \in \{dbi, duni\}\}\} \end{aligned}$$

$\prec_{NT}$, an ordering relation on $SGNT$, indicates the node types that are inheritance-relatable:

$$\begin{aligned} nt_1 \prec_{NT} nt_2 &\Leftrightarrow nt_1 \neq nprxy \wedge nt_2 \neq nval \\ \wedge nt_1 &= nabst \Rightarrow nt_2 \in \{nabst, nvirt, nprxy\} \wedge (nt_1 = nenum \Rightarrow nt_2 \in \{nvirt, nprxy\}) \end{aligned}$$

Above, $\prec_{NT}$ stipulates that (i) proxies must not inherit, (ii) values must not be inherited, (iii) abstract nodes may inherit from abstract, virtual and proxy nodes only, (iv) enumerations may only inherit virtuals or proxies.

$\leq_{rNT}$ and $\leq_{ET}$ are ordering relations on sets $SGNT$ and $SGET$, respectively, indicating node and edge types that can be refinement-related, respectively:

$$\begin{aligned}
 nt_1 \leq_{rNT} nt_2 &\Leftrightarrow nt_1 = nt_2 \vee nt_1 = nprxy \vee nt_1 = nnrml \wedge nt_2 = nprxy \\
 &\vee nt_2 \in \{nabst, nvirt\} \wedge nt_1 \in \{nnrml, nvirt, nabst\} \vee nt_2 = nnrml \\
 et_1 \leq_{ET} et_2 &\Leftrightarrow et_1 = et_2 \\
 &\vee (\forall d_1, d_2 : SGED \bullet et_1 = erel d_1 \wedge et_2 = erel d_2 \vee et_1 = ecomp d_1 \wedge et_2 = ecomp d_2) \\
 et_1 \leq_{ET} et_2 &\Leftrightarrow \neg\{einh, eder, epath, evcnt\} \subseteq \{et_1, et_2\} \wedge (et_1 \leq_{ET} et_2 \\
 &\vee et_2 = erel dbi \wedge (et_1 = ecomp dbi \vee et_1 = ecomp duni) \vee et_2 = erel duni \wedge et_1 = ecomp duni)
 \end{aligned}$$

□

DEFINITION 14. (Multiplicities) The multiplicity sets include: (i) *MultiVal* (multiplicity values), the disjoint union (symbol $\uplus$) of natural numbers with symbol $*$ (many); (ii) *MultiR* (multiplicity ranges), pairs of lower and upper bound multiplicities; (iii) *MultiC* (multiplicity compounds), either a single multiplicity value or a range; and (iv) *Multi*, a non-empty set of multiplicity compounds (a singleton when there is just one multiplicity, a larger set otherwise):

$$\begin{aligned}
 MultiVal &= \mathbb{N} \uplus \{*\} \quad MultiR = \{(lb, ub) \mid lb \in \mathbb{N} \wedge ub \in MultiVal \wedge (ub = * \vee (ub \in \mathbb{N} \wedge lb \leq ub))\} \\
 MultiC &= MultiVal \uplus MultiR \quad MultiCMany = \{*, (0, *)\} \\
 Multi &= \{ms : \mathbf{P}_1 MultiC \mid \# ms > 1 \Rightarrow \forall m : ms \bullet m \notin MultiCMany\}
 \end{aligned}$$

Function *mlb* and *mub* give lower and upper bounds of a $m \in MultiC$, respectively, where $k \in \mathbb{N}$:

$$\begin{aligned}
 mlb, mub &: Multi \rightarrow MultiVal \\
 mlb * &= 0 \quad mlb k = k \quad mlb (k, m) = k \quad mub m = m \quad mub (k, m) = m
 \end{aligned}$$

Relation $\leq_{mv}$ stipulates an ordering on set *MultiVal*:

$$m_1 \leq_{mv} m_2 \Leftrightarrow m_2 = * \vee \{m_1, m_2\} \subseteq \mathbb{N} \wedge m_1 \leq m_2$$

Relation $\emptyset$ says whether a natural number complies to a multiplicity:

$$k \emptyset m \Leftrightarrow mlb m \leq_{mv} k \wedge k \leq_{mv} mub m$$

Predicate $\cdots$ says whether some natural number complies with any of the given multiplicities:

$$k \cdots \{m\} \Leftrightarrow k \emptyset m \quad k \cdots \{m\} \cup ms \Leftrightarrow k \emptyset m \vee k \cdots \{m\} \cup ms$$

Relation $\leq_{Mc}$ stipulates an ordering on *MultiC* to say whether one multiplicity is within another:

$$mc_1 \leq_{Mc} mc_2 \Leftrightarrow mlb mc_2 \leq_{mv} mlb mc_1 \wedge mub mc_1 \leq_{mv} mub mc_2$$

Relation $\leq_{\mathcal{M}}$ stipulates an ordering on *Multi* to say whether one multiplicity set is within another:

$$m_1 \leq_{\mathcal{M}} m_2 \Leftrightarrow \forall mc_1 : m_1 \bullet \exists mc_2 : m_2 \bullet mc_1 \leq_{Mc} mc_2$$

The multiplicity sets for many, range and alternative multiplicities, respectively, are:

$$\begin{aligned} \text{MultMany} &= \{ms : \text{Mult} \mid \exists m_c : \text{MultC} \bullet ms = \{m_c\} \wedge m_c \in \text{MultCMany}\} \\ \text{MultRange} &= \{ms : \text{Mult} \mid \exists m : \text{MultC} \bullet ms = \{m\} \wedge (m \in \mathbb{N} \wedge m > 1) \\ &\quad \vee \exists lb : \mathbb{N} ; um : \text{MultVal} \mid 2 \leq_{mv} um \bullet m = (lb, um) \} \\ \text{MultEither} &= \{ms : \text{Mult} \mid \# ms > 1\} \end{aligned}$$

Predicate $\propto$ describes the multiplicities permitted by the different edge types:

$$\begin{aligned} et \propto (m_1, m_2) &\Leftrightarrow et = \text{erel dbi} \vee et = \text{eder} \vee et = \text{ecomp duni} \wedge m_1 = \{1\} \\ &\vee et = \text{erel duni} \wedge m_1 \in \text{MultMany} \vee et = \text{ecomp dbi} \wedge m_1 \in \{\{1\}, \{(0, 1)\}\} \end{aligned}$$

The above says: (i) bi-directional relations and derived edges can have any multiplicity, (ii) source multiplicities of uni-directional containments and relations are 1 and *, respectively, and (iii) source multiplicities of bi-directional containments are either 1 or 0 . . 1. $\square$

DEFINITION 15 (PATH EXPRESSIONS). Path expressions capture edge paths used in path-based constraint edges (either derived or path). Recursive set of path expressions, PE, is defined from the recursive sets of path expressions atoms and composites, PEA and PEC, respectively:

$$\text{PEA} ::= E \mid E^{-1} \quad \text{PEC} ::= \text{PEA} \mid V \triangleleft_{PE} \text{PEA} \mid \text{PEA} \triangleright_{PE} V \quad \text{PE} ::= \text{PEC} \mid \text{PEC} \circ_{PE} \text{PE}$$

A PEA is either a single edge or the reverse of an edge. A PEC is either a PEA, a PEA whose domain (or source) is restricted to a particular node, or a PEA whose range is restricted to a node. A PE is either a single path expression composite, or path expression composite followed by a path expression.

Function $e\text{PEA} : \text{PEA} \rightarrow E$, which gives the edge of a PEA, is defined inductively:

$$e\text{PEA } e = e \quad e\text{PEA } e^{-1} = e$$

Functions $\text{srcPEA} : Gr \rightarrow \text{PEA} \rightarrow V$, $\text{srcPEC} : Gr \rightarrow \text{PEC} \rightarrow V$ and $\text{srcPE} : Gr \rightarrow \text{PE} \rightarrow V$, defined inductively, take a graph G and either a PEA, PEC, or PE, respectively, to give the path's source with respect to G . Given $G : Gr$, $e : E$, $pea : \text{PEA}$, $v : V$, $pec : \text{PEC}$, and $pe : \text{PE}$, the definitions are as follows:

$$\begin{aligned} \text{srcPEA } G e &= \text{src } G e \quad \text{srcPEA } G e^{-1} = \text{tgt } G e \quad \text{srcPEC } G pea = \text{srcPEA } G pea \\ \text{srcPEC } G (v \triangleleft_{PE} pea) &= \text{srcPEA } pea \quad \text{srcPEC } G (pea \triangleright_{PE} v) = \text{srcPEA } pea \\ \text{srcPE } G pec &= \text{srcPEC } G pec \quad \text{srcPE } G (pec \circ_{PE} pe) = \text{srcPEC } G pe_1 \end{aligned}$$

Functions $\text{tgtPEA} : \text{PEA} \rightarrow E$, $\text{tgtPEC} : \text{PEC} \rightarrow E$, and $\text{tgtPE} : \text{PE} \rightarrow E$ give the target node of a PEA, PEC or PE with respect to a given graph G :

$$\begin{aligned} \text{tgtPEA } G e &= \text{tgt } G e \quad \text{tgtPEA } G e^{-1} = \text{src } G e \quad \text{tgtPEC } G pea = \text{tgtPEA } G pea \\ \text{tgtPEC } G (v \triangleleft_{PE} pea) &= \text{tgtPEA } pea \quad \text{tgtPEC } G (pea \triangleright_{PE} v) = \text{tgtPEA } pea \\ \text{tgtPE } G pec &= \text{tgtPEC } G pec \quad \text{tgtPE } G (pec \circ_{PE} pe) = \text{tgtPE } G pe \end{aligned}$$

Functions $startEA_C : PEC \rightarrow PEA$, $startEA : PE \rightarrow PEA$, $endEA_C : PEC \rightarrow PEA$ and $endEA : PE \rightarrow PEA$, defined inductively on sets PEC and PE , give either start (or source) or end (or target) PEAs, respectively:

$$\begin{aligned} startEA_C\ pea &= pea & startEA_C (v \triangleleft_{PE} pea) &= pea & startEA_C (pea \triangleright_{PE} v) &= pea \\ startEA\ pec &= startEA_C\ pec & startEA (pec \circ_{PE} pe) &= startEA_C\ pec \\ endEA_C\ pea &= pea & endEA_C (v \triangleleft_{PE} pea) &= pea & endEA_C (pea \triangleright_{PE} v) &= pea \\ endEA\ pec &= endEA_C\ pec & endEA (pec \circ_{PE} pe) &= endEA\ pe \end{aligned}$$

Functions $rsrcPE, rtgtPE : PE \rightarrow E$ reduce a PE to either the source or target edges, respectively; they are defined from $startEA$ and $endEA$, respectively:

$$rsrcPE = ePEA \circ startEA \quad rtgtPE = ePEA \circ endEA$$

□

DEFINITION 16 (INFORMATION OF VALUE CONSTRAINT EDGES). Set $SGVCEOP$ defines the allowed operators of a value-constraint edge: equality (eq), inequality (neq), less or equal than (leq), greater or equal than (geq), less than (lt), and greater than (gt).

$$SGVCEOP = \{eq, neq, leq, geq, lt, gt\}$$

VCI holds the information associated with a value-constraint edge: an operator, $SGVCEOP$ above, and an optional edge, which indicates the constrained edge or self (constraint refers to source node):

$$VCI = SGVCEOP \times opt[E]$$

□

DEFINITION 17 (STRUCTURAL GRAPHS). A structural graph $SG = (G, nty, ety, sm, tm, p, d, vci)$ comprises: (i) a graph $G : Gr$ (def. 7), (ii) two colouring functions for nodes and edges, $nty : Ns_G \rightarrow SGNT$ and $ety : Es_G \rightarrow SGET$ (def. 13), (iii) source and target multiplicity functions $sm, tm : Es_G \rightarrow Mult$ (def. 14), (iv) a partial function $p : Es_G \rightarrow PE$ giving the path expression of either derived or path edges (def. 15), (v) a relation $d : Es_G \leftrightarrow Es_G$ giving the dependencies between path edges, and (vi) a partial function $vci : Es_G \rightarrow VCI$ (def. 16) giving the information associated with value-constraint edges.

Base set SGr_0 , such that $SG : SGr_0$, is defined as:

$$\begin{aligned} SGr_0 &= \{(G, nt, et, sm, tm, p, d, vci) \mid G \in Gr \wedge nt \in Ns_G \rightarrow SGNT \wedge et \in Es_G \rightarrow SGET \\ &\quad \wedge sm \in Es_G \rightarrow Mult \wedge tm \in Es_G \rightarrow Mult \wedge p \in Es_G \rightarrow PE \wedge d \in Es_G \leftrightarrow Es_G \wedge vci \in Es_G \rightarrow VCI\} \end{aligned}$$

Several projection functions extract the eight elements of a $SG : SGr_0$:

$$\begin{aligned} gr(G, nt, et, sm, tm, p, d, vci) &= G & nty(G, nt, et, sm, tm, p, d, vci) &= nt \\ ety(G, nt, et, sm, tm, p, d, vci) &= et & srcm(G, nt, et, sm, tm, p, d, vci) &= sm \\ tgtm(G, nt, et, sm, tm, p, d, vci) &= tm & pe(G, nt, et, sm, tm, p, d, vci) &= p \\ ds(G, nt, et, sm, tm, p, d, vci) &= d & vci(G, nt, et, sm, tm, p, d, vci) &= vci \end{aligned}$$

In the empty $SG (\emptyset_{SG})$ all its eight components are empty:

$$\emptyset_{SG} = (\emptyset_G, \emptyset, \emptyset, \emptyset, \emptyset, \emptyset, \emptyset, \emptyset)$$

Graph functions Ns , Es , src and tgt of def. 7 are considered to be applicable to SGs also. For a $SG : SGr_0$, $Ns SG$ is interpreted to be $Ns(gr SG)$, and likewise for Es , src and tgt .

Function $EsTy SG ets$ gives all edges of SG with edge types ets , $NsTy SG nts$ gives all nodes of SG with node types nts :

$$EsTy SG ets = (ety SG) \sim \langle \langle ets \rangle \rangle \quad NsTy SG nts = (nty SG) \sim \langle \langle nts \rangle \rangle \quad EsW SG = EsTy SG \{ewander\}$$

Several functions yield the edges of different types, namely: (i) EsA (association which includes relation and composition), (ii) EsM (multiplicity), (iii) EsI (inheritance), (iv) EsD (derived), (v) $EsPa$ (path), (vi) $EsVCnt$ (value constraint) and (vii) $EsPaCnt$ (path constraint).

$$\begin{aligned} EsA SG &= EsTy SG \{ae d \mid ae \in \{ecompr, erel\} \wedge d \in \{dbi, duni\}\} & EsI SG &= EsTy SG \{eih\} \\ EsD SG &= EsTy SG \{eder\} & EsPa SG &= EsTy SG \{epath\} & EsM SG &= EsA SG \cup EsD SG \\ EsVCnt SG &= EsTy SG \{evcnt\} & EsPaCnt SG &= EsD SG \cup EsPa SG \end{aligned}$$

Likewise for nodes: (i) NsP (proxy), (ii) $NsVi$ (virtual), (iii) NsN (normal), (iv) $NsVa$ (value) and (v) $NsEther$ (ethereal, includes abstract, virtual and enumeration).

$$\begin{aligned} NsP SG &= NsTy SG \{nprxy\} & NsVi SG &= NsTy SG \{nvirt\} & NsVa SG &= NsTy SG \{nval\} \\ NsN SG &= NsTy SG \{nnrml\} & NsEther SG &= NsTy SG \{nvirt, nabst, nenum\} \end{aligned}$$

Above, $\sim$ is the relation inverse and $\langle \langle \rangle \rangle$ is the relation image (def. 2). $\square$

DEFINITION 18 (INHERITANCE IN SGs). Function $\upharpoonright$ gives the inheritance graph by restricting the given SG to its inheritance edges. The inheritance relation $\prec$ is derived from $\upharpoonright$:

$$\begin{aligned} \upharpoonright : SGr_0 &\rightarrow Gr & \prec : SGr_0 &\rightarrow V \leftrightarrow V \\ \upharpoonright SG &= gr SG \bowtie_{Es} EsI SG & \prec_{SG} &= (\upharpoonright SG) \leftrightarrow \end{aligned}$$

The following provide further machinery: (i) $\preceq$ is the reflexive and transitive closure of $\prec$ (def. 17), (ii) src^* and tgt^* extend graph functions src and tgt (def. 7) to yield relations $E \leftrightarrow V$ between edges and vertices to cater for inheritance, (iii) variants src_M^* and tgt_M^* , used for morphisms, do the same but are restricted to allow association edges only:

$$\begin{aligned} \preceq : SGr_0 &\rightarrow V \leftrightarrow V & src_0^*, src^*, tgt_0^*, tgt^* : SGr_0 &\rightarrow E \leftrightarrow V \\ \preceq SG &= (\prec SG)^* & src_0^* SG es &= es \triangleleft (srcr SG) & tgt_0^* SG es &= es \triangleleft (tgr SG) \\ src^* SG &= src_0^* SG (EsA SG \cup EsPaCnt SG) \circ (\preceq SG) \sim \\ tgt^* SG &= tgt_0^* SG (EsA SG \cup EsPaCnt SG) \circ (\preceq SG) \sim \\ src_M^* SG &= src_0^* SG (EsA SG) \circ (\preceq SG) \sim & tgt_M^* SG &= tgt_0^* SG (EsA SG) \circ (\preceq SG) \sim \end{aligned}$$

Above, $\circ$ is relation composition (def. 2). Functions src^* and tgt^* , which depart from src_0^* and tgt_0^* , say that ancestor edges are also edges of descendants affecting association and constraint edges; src_M^* and tgt_M^* affect association edges only. $\square$

DEFINITION 19 (PARTIAL SGs). Function $srcma$, which totalises function $srcm$, gives source multiplicities of all multiplicity edges; multiplicities of uni-directional composition and relation edges become 1 and $*$ (many), respectively:

$$\begin{aligned} srcma : SGr_0 &\rightarrow E \rightarrow Mult \\ srcma SG &= (srcm_{SG}) \oplus (EsTy_{SG} \{ecompr duni\} \times \{\{1\}\}) \oplus (EsTy_{SG} \{erel duni\} \times \{\{*\}\}) \end{aligned}$$

Predicate *MetysOk* checks if multiplicity edges comply with the multiplicity restrictions of their edges types using relation $\propto$ (def 14):

$$\text{MetysOk } SG \Leftrightarrow \forall e : \text{EsM}_{SG} \bullet (\text{ety}_{SG} e) \propto (\text{srcma}_{SG} e, \text{tgtm}_{SG} e)$$

Predicate *inhOk* says whether an inheritance hierarchy is well-formed. It requires that: (i) inheritance relations comply with the inheritance restrictions of the corresponding node types as captured by $\prec_{NT}$ (def. 13), and (ii) the inheritance graph is acyclic:

$$\text{inhOk } SG \Leftrightarrow (\forall v, v' : \text{Ns}_{SG} \bullet v \prec_{SG} v' \Rightarrow \text{nty}_{SG} v \prec_{NT} \text{nty}_{SG} v') \wedge \odot \dot{\mathfrak{m}}_{SG}$$

Predicate *VCntEsOk* checks the well-formedness of value constraint edges (VCEs): (i) all VCEs have the corresponding information (*vcei* is a total function), (ii) VCEs must constrain association edges only, and (iii) VCEs have either value or proxy nodes as targets.

$$\begin{aligned} \text{VCntEsOk } SG \Leftrightarrow & \text{vcei}_{SG} \in \text{EsVCnt}_{SG} \rightarrow \text{VCI} \wedge \bigcup (\text{map second } ((\text{ran} \circ \text{vcei}) SG)) \subseteq \text{EsA}_{SG} \\ & \wedge (\text{tgt}_{SG}) \downarrow \text{EsVCnt}_{SG} \downarrow \subseteq \text{NsVa}_{SG} \cup \text{NsP}_{SG} \end{aligned}$$

Set of partial SGs, *SGr*, is defined from the *SGr₀* base set:

$$\begin{aligned} \text{SGr} = \{ SG \mid & SG \in \text{SGr}_0 \wedge \{ \text{srcma}_{SG}, \text{tgtm}_{SG} \} \subseteq \text{EsM}_{SG} \rightarrow \text{Mult} \wedge \text{ds}_{SG} \in (\text{antireflexive } \text{EsPa}_{SG}) \\ & \wedge \text{dom } \text{pe}_{SG} = \text{EsPaCnt}_{SG} \wedge \text{MetysOk } SG \wedge \text{inhOk } SG \wedge \text{VCntEsOk } SG \} \end{aligned}$$

Partial SGs are subject to the following constraints: (i) multiplicity edges (set *EsM* above) must have source and target multiplicities (second conjunct); (ii) relation *ds* (dependencies) between path edges is anti-reflexive; (iii) function *pe* has path constraint edges in its domain only; (iv) edge multiplicities comply with the multiplicity restrictions of their types (*MetysOk* above); (i) the SG's inheritance is well-formed (*inhOk* above); (vi) the VCEs are well-formed (*VCntEsOk* above).

Laws. The following laws were proved in Isabelle:

$$\begin{aligned} SG \in \text{SGr} \vdash SG \multimap^* ns \subseteq \text{Es}_{SG} \quad SG \in \text{SGr} \vdash SG \multimap^* ns_1 \cup ns_2 = SG \multimap^* ns_1 \cup SG \multimap^* ns_2 \\ SG \in \text{SGr} ; ns_2 \cap \text{Ns}_{SG} = \emptyset \vdash SG \multimap^* ns_1 \cup ns_2 = SG \multimap^* ns_1 \quad \vdash \emptyset_{SG} \in \text{SGr} \end{aligned}$$

□

DEFINITION 20 (TOTAL SGs). Total SGs must satisfy certain conditions. Predicate *derInhOk* checks the underlying commuting of derived edges and respective edge paths:

$$\text{derInhOk } SG \Leftrightarrow \forall e : \text{EsD}_{SG} \bullet (\text{gr } SG \triangleright_{\text{Es}} \text{esPE } (\text{pe } SG e)) \stackrel{+}{\circ} (\preceq SG) \subseteq (\preceq SG) \circ (\text{gr } SG \triangleright_{\text{Es}} \text{esPE } (\text{pe } SG e)) \stackrel{+}{\circ}$$

where *srcPE* and *tgtPE*, which get source and target node, respectively, of the associated path edge, come from def. 15.

okPEASrc and *okPEATgt* check whether the source or target, respectively, of a path expression atom (PEA) is valid with respect to the extended source (*src**) or target (*tgt**) relations, respectively:

$$\begin{aligned} \text{okPEASrc}(SG, v, e) \Leftrightarrow (e, v) \in \text{src}^*_{SG} \quad \text{okPEASrc}(SG, v, e^{-1}) \Leftrightarrow (e, v) \in \text{tgt}^*_{SG} \\ \text{okPEATgt}(SG, v, e) \Leftrightarrow (e, v) \in \text{tgt}^*_{SG} \quad \text{okPEATgt}(SG, v, e^{-1}) \Leftrightarrow (e, v) \in \text{src}^*_{SG} \end{aligned}$$

Functions $okPEA$, $okPEC$ and $okPE$ check whether a given path expression atom (PEA), compound (PEC), or whole (PE), respectively, is valid with respect to a given $SG : SGr$:

$$\begin{aligned}
okPEA(SG, e) &\Leftrightarrow e \in Es\ SG \quad okPEA(SG, e^{-1}) \Leftrightarrow e \in Es\ SG \\
okPEC(SG, pea) &\Leftrightarrow okPEA(SG, pea) \\
okPEC(SG, v \triangleleft_{PE} pea) &\Leftrightarrow okPEA(SG, pea) \wedge okPEASrc(srcr, tgtr, v, pea) \\
okPEC(SG, pea \triangleright_{PE} e) &\Leftrightarrow okPEA(SG, pea) \wedge okPEATgt(srcr, tgtr, v, pea) \\
okPE(SG, pec) &\Leftrightarrow okPEC(SG, pec) \\
okPE(SG, pec \circ_{PE} pe) &\Leftrightarrow okPEC(SG, pec) \wedge okPE(SG, pe) \\
&\wedge (tgtPEC(SG \bowtie_{Es} EsA_{SG})\ pec \preceq_{SG} srcPE(SG \bowtie_{Es} EsA_{SG})\ pe \\
&\vee srcPE(SG \bowtie_{Es} EsA_{SG})\ pe \preceq_{SG} tgtPEC(SG \bowtie_{Es} EsA_{SG})\ pec)
\end{aligned}$$

The equations above are as follows: (i) the first two say that a PEA is valid provided the encapsulated edge belongs to the given SG, (ii) a PEC holding a PEA is valid provided the PEA is valid, (iii) a domain restriction expression is valid provided the PEA is valid and the pair node, edge is valid with respect to the source, (iii) similarly for the range restriction expression, and finally (iv) a sequence of PEs is valid if they are individually valid and if the target of the first expression is inheritance related to the source of the second expression.

Predicates $isVCEECnt$ and $isVCENCnt$ indicate whether a VCE refers to either an edge or the source node, respectively, which is to say either when an edge is provided as part of the edge information or when such an edge is not provided, respectively:

$$isVCEECnt(SG, vce) \Leftrightarrow (second \circ vcei_{SG})\ vce \neq \emptyset$$

$$isVCENCnt(SG, vce) \Leftrightarrow (second \circ vcei_{SG})\ vce = \emptyset$$

Predicate $commonAncestor$ says whether two given nodes have a common ancestor in the given SG:

$$commonAncestor(SG, n_1, n_2) \Leftrightarrow \exists nt : Ns_{SG} \bullet n_1 \preceq_{SG} nt \wedge n_2 \preceq_{SG} nt$$

Predicate $EsVCntsOk$ indicates whether VCEs are well-formed. There are two cases, either: (i) the VCE constrains an edge, in which case the edge's target node is required to have an ancestor in common with the target of the embedded edge, or (ii) the VCE constrains the source node, in which case the edge's target node must have an ancestor in common with the edge's source node.

$$\begin{aligned}
EsVCntsOk\ SG &\Leftrightarrow \forall vce : EsVCnts_{SG} \bullet \\
&isVCEECnt(SG, vce) \Rightarrow commonAncestor(SG, tgt_{SG}((the \circ second \circ vcei_{SG})\ vce), tgt_{SG}\ vce) \\
&\wedge isVCENCnt(SG, vce) \Rightarrow commonAncestor(SG, src_{SG}\ vce, tgt_{SG}\ vce)
\end{aligned}$$

Predicate $EsCntsOk$ checks the conformance of derived edges (predicate $derInhOk$ above), the validity of path expressions of path edges (function $okPE$, def. 15) and the well-formedness of VCEs in a total setting (predicate $EsVCntsOk$ above):

$$\begin{aligned}
EsCntsOk\ SG &\Leftrightarrow derInhOk\ SG \wedge \forall e : EsPaCnt_{SG} \bullet okPE(gr\ SG \bowtie_{Es} EsA_{SG}, src^*_{SG}, tgt^*_{SG}, pe_{SG}\ e) \\
&\wedge EsVCntsOk\ SG
\end{aligned}$$

A total SG is a partial $SG : SGr$ (def 19) in which: (i) all ethereal nodes (set $NsEther$ of def 17) are inherited, (ii) constraint edges are valid (predicate $EsCntsOk$ above), and (iii) the inheritance graph without virtuals forms a tree (i.e. virtuals apart,

the inheritance must be single). Set $TSGr$ of total SGs is as follows:

$$TSGr = \{SG : SGr \mid NsEthers_{SG} \subseteq \text{ran}(\prec_{SG}) \wedge EsCntsOk_{SG} \wedge (\uparrow_{SG} \ominus_{Ns} NsV_{SG})^{\leftrightarrow} \in \text{tree}\}$$

□

DEFINITION 21 (COMPOSITION OF SGs). The union of SGs ($\cup_{SG}$) is defined as:

$$SG_1 \cup_{SG} SG_2 = (gr_{SG_1} \cup_G gr_{SG_2}, nty_{SG_1} \cup nty_{SG_2}, ety_{SG_1} \cup ety_{SG_2}, \\ srcm_{SG_1} \cup srcm_{SG_2}, tgmt_{SG_1} \cup tgmt_{SG_2}, pe_{SG_1} \cup pe_{SG_2}, ds_{SG_1} \cup ds_{SG_2})$$

SG subsumption ($\odot^{SG}$) subsumes a SG given a substitution of proxies by other SG nodes:

$$_ \odot^{SG} _ : SGr \times (V \leftrightarrow V) \rightarrow SGr \\ SG \odot^{SG} s = \begin{cases} (gr_{SG} \odot s, (\text{dom } s \setminus \text{ran } s) \triangleleft nty_{SG}, ety_{SG}, srcm_{SG}, tgmt_{SG}, pe_{SG}, ds_{SG}) & \text{if } s \in NsP_{SG} \rightarrow NsSG \\ SG & \text{otherwise} \end{cases}$$

This subsumes underlying base graph (def. 8) and removes subsumed nodes from function nty .

SG disjointness is defined from graph disjointness as:

$$\exists_{SGs}(SG_1, SG_2) \Leftrightarrow \exists(gr \ SG_1, gr \ SG_2)$$

Laws. The following laws were proved in Isabelle:

$$\begin{aligned} & \vdash \emptyset_{SG} \cup_{SG} SG = SG \quad \vdash \emptyset_{SG} \odot^{SG} s = \emptyset_{SG} \quad SG \in SGr \vdash SG \odot^{SG} \emptyset = SG \\ & SG_1, SG_2 \in SGr ; \exists_{SGs}(SG_1, SG_2) \vdash (SG_1 \cup_{SG} SG_2) \multimap^* vs = (SG_1 \multimap^* vs) \cup (SG_2 \multimap^* vs) \\ & SG_1, SG_2 \in SGr ; \exists(SG_1, SG_2) \vdash EsTys(SG_1 \cup_{SG} SG_2) \text{ ets} = EsTys \ SG_1 \text{ ets} \cup EsTys \ SG_2 \text{ ets} \\ & SG_1, SG_2 \in SGr ; \exists_{SGs}(SG_1, SG_2) \vdash NsTys(SG_1 \cup_{SG} SG_2) \text{ nts} = NsTys \ SG_1 \text{ nts} \cup NsTys \ SG_2 \text{ nts} \\ & SG_1, SG_2 \in SGr ; \exists_{SGs}(SG_1, SG_2) \vdash EsA(SG_1 \cup_{SG} SG_2) = EsA \ SG_1 \cup_{SG} EsA \ SG_2 \\ & SG_1, SG_2 \in SGr ; \exists_{SGs}(SG_1, SG_2) \vdash EsI(SG_1 \cup_{SG} SG_2) = EsI \ SG_1 \cup_{SG} EsI \ SG_2 \\ & SG_1, SG_2 \in SGr ; \exists_{SGs}(SG_1, SG_2) \vdash EsD(SG_1 \cup_{SG} SG_2) = EsD \ SG_1 \cup_{SG} EsD \ SG_2 \\ & SG_1, SG_2 \in SGr ; \exists_{SGs}(SG_1, SG_2) \vdash EsW(SG_1 \cup_{SG} SG_2) = EsW \ SG_1 \cup_{SG} EsW \ SG_2 \\ & SG_1, SG_2 \in SGr ; \exists_{SGs}(SG_1, SG_2) \vdash EsC(SG_1 \cup_{SG} SG_2) = EsC \ SG_1 \cup_{SG} EsC \ SG_2 \\ & SG_1, SG_2 \in SGr ; \exists_{SGs}(SG_1, SG_2) \vdash NsP(SG_1 \cup_{SG} SG_2) = NsP \ SG_1 \cup_{SG} NsP \ SG_2 \\ & SG_1, SG_2 \in SGr ; \exists_{SGs}(SG_1, SG_2) \vdash NsO(SG_1 \cup_{SG} SG_2) = NsO \ SG_1 \cup_{SG} NsO \ SG_2 \\ & SG_1, SG_2 \in SGr ; \exists_{SGs}(SG_1, SG_2) \vdash NsV(SG_1 \cup_{SG} SG_2) = NsV \ SG_1 \cup_{SG} NsV \ SG_2 \\ & SG_1, SG_2 \in SGr ; \exists_{SGs}(SG_1, SG_2) \vdash \exists(\uparrow \ SG_1, \uparrow \ SG_2) \\ & SG_1, SG_2 \in SGr ; \exists_{SGs}(SG_1, SG_2) \vdash \uparrow(SG_1 \cup_{SG} SG_2) = \uparrow \ SG_1 \cup_G \uparrow \ SG_2 \\ & SG_1, SG_2 \in SGr ; \exists_{SGs}(SG_1, SG_2) \vdash \prec(SG_1 \cup_{SG} SG_2) = \prec_{SG_1} \cup \prec_{SG_2} \\ & SG_1, SG_2 \in SGr ; \exists_{SGs}(SG_1, SG_2) \vdash \preceq(SG_1 \cup_{SG} SG_2) = \preceq_{SG_1} \cup \preceq_{SG_2} \\ & SG_1, SG_2 \in SGr ; \exists_{SGs}(SG_1, SG_2) \vdash src^*(SG_1 \cup_{SG} SG_2) = src^*_{SG_1} \cup src^*_{SG_2} \\ & SG_1, SG_2 \in SGr ; \exists_{SGs}(SG_1, SG_2) \vdash tgt^*(SG_1 \cup_{SG} SG_2) = tgt^*_{SG_1} \cup tgt^*_{SG_2} \\ & SG_1, SG_2 \in SGr ; \exists_{SGs}(SG_1, SG_2) \vdash \odot(\uparrow \ SG_1 \cup_G \uparrow \ SG_2) \Leftrightarrow \odot(\uparrow \ SG_1) \wedge \odot(\uparrow \ SG_2) \\ & SG_1, SG_2 \in SGr ; \exists_{SGs}(SG_1, SG_2) \vdash SG_1 \cup_{SG} SG_2 = SG_2 \cup_{SG} SG_1 \\ & SG_1, SG_2 \in SGr ; \exists_{SGs}(SG_1, SG_2) \vdash SG_1 \cup_{SG} SG_2 \in SGr \end{aligned}$$

□

DEFINITION 22 (SG MORPHISMS). Given $SG_s, SG_t : SGr$, a SG morphism $m : SG_s \rightarrow_{SG} SG_t$ is a pair of functions $m = (fv, fe)$ mapping nodes and edges, respectively. The set of morphisms between the mapped SGs, $SG_s \rightarrow_{SG} SG_t$, is defined as:

$$SG_s \rightarrow_{SG} SG_t = \{ (fv, fe) \mid fv \in N_{SG_s} \rightarrow N_{SG_t} \wedge fe \in Es_{SG_s} \rightarrow Es_{SG_t} \\ \wedge fv \circ src_{SG_t}^* \subseteq src_{SG_t}^* \circ fe \wedge fv \circ tgt_{SG_t}^* \subseteq tgt_{SG_t}^* \circ fe \wedge fv \circ \preceq_{SG_s} \subseteq \preceq_{SG_t} \circ fv \}$$

Only association edges are mapped (set EsA , def. 17, excludes inheritance and constraint edges). Commuting is expressed as subsetting ($\subseteq$ rather than $=$) to cater for inheritance.

Partial SG morphisms are also defined:

$$SG_s \leftrightarrow_{SG} SG_t = \{ (fv, fe) \mid fv \in N_{SG_s} \leftrightarrow N_{SG_t} \wedge fe \in Es_{SG_s} \leftrightarrow Es_{SG_t} \\ \wedge fv \circ (\text{dom } fe \triangleleft src_{SG_t}^*) \subseteq src_{SG_t}^* \circ fe \wedge fv \circ (\text{dom } fe \triangleleft tgt_{SG_t}^*) \subseteq tgt_{SG_t}^* \circ fe \\ \wedge fv \circ \preceq_{SG_s} \subseteq \preceq_{SG_t} \circ fv \}$$

Above, functions fv and fe are allowed to be partial; on the left-hand side of the commuting equations, the source and target functions are restricted on the domain to the edges mapped through fe to ensure that only the edges being mapped are considered in the corresponding commuting.

Relations $\Rightarrow^{SG}$ and $\Rightarrow_p^{SG}$ define total or partial conformance through a SG morphism, respectively:

$$(SG_s, m) \Rightarrow^{SG} SG_t \Leftrightarrow m \in SG_s \rightarrow_{SG} SG_t \quad (SG_s, m) \Rightarrow_p^{SG} SG_t \Leftrightarrow m \in SG_s \leftrightarrow_{SG} SG_t$$

□

DEFINITION 23 (PARTIAL REFINEMENT OF SGs). Partial refinement ($\sqsupseteq^{SG}$) says whether a refined (or concrete) SG refines, through morphism $m : GrM$, a abstract $SG_a : SGr$:

$$(SG_c, m) \sqsupseteq^{SG} SG_a \Leftrightarrow m \in SG_c \rightarrow_{SG} SG_a \wedge (SG_c, m) \sqsupseteq^{SG_0} SG_a$$

Partial refinement requires that: (i) m is a valid morphism from SG_c to SG_a , and (ii) the satisfaction of the conditions associated with $\sqsupseteq^{SG_0}$.

The definition of $\sqsupseteq^{SG_0}$ is as follows:

$$(SG_c, m) \sqsupseteq^{SG_0} SG_a \Leftrightarrow (SG_c, m) \sqsupseteq_{NT} SG_a \wedge (SG_c, m) \sqsupseteq_{ET} SG_a \wedge (SG_c, m) \sqsupseteq_M SG_a \\ \wedge (SG_c, m) \sqsupseteq_{MCnts} SG_a$$

Above, $\sqsupseteq^{SG_0}$ requires: (i) SG_c complies with SG_a 's refinement node- ($\sqsupseteq_{NT}$) and edge-types ($\sqsupseteq_{ET}$) constraints, (ii) SG_c complies with SG_a 's multiplicity refinement constraints ($\sqsupseteq_M$), and (iii) SG_c complies with the multiplicity constraints of SG_a 's derived edges ($\sqsupseteq_{MCnts}$).

$\sqsupseteq_{NT}$ requires that the nodes of a SG_c comply to the node-type refinement constraints of the corresponding nodes in SG_a through relation $\leq_{rNT}$ (def. 13):

$$(SG_c, m) \sqsupseteq_{NT} SG_a \Leftrightarrow \forall n : N_{SG_c} \bullet nty_{SG_c} n \leq_{rNT} (nty_{SG_a} \circ (fv \ m)) n$$

$\sqsupseteq_{ET}$ requires that the edges of a SG_c comply to the edge-type refinement constraints of the corresponding edges in SG_a through relation $\leq_{ET}$ (def. 13):

$$(SG_c, m) \sqsupseteq_{ET} SG_a \Leftrightarrow \forall e : Es_{SG_c} \bullet ety_{SG_c} e \leq_{ET} (ety_{SG_a} \circ (fe \ m)) e$$

Finally, $\sqsupseteq_{\mathcal{M}}$ requires that SG_c 's association edges must comply to the multiplicity refinement constraints of the corresponding edges in SG_a through relation $\leq_{\mathcal{M}}$ (def. 14) to say that refinements can weaken multiplicity constraints:

$$(SG_c, m) \sqsupseteq_{\mathcal{M}} SG_a \Leftrightarrow \forall e : EsAS_{SG_c} \bullet srcma_{SG_c} e \leq_{\mathcal{M}} (srcma_{SG_a} \circ (fE m)) e \\ \wedge tgmt_{SG_c} e \leq_{\mathcal{M}} (tgtm_{SG_a} \circ (fE m)) e$$

Above, function *srcma* (def. 17) totalises *srcm* in order to handle uni-directional edges.

$\sqsupseteq_{\mathcal{MCnts}}$ checks that each derived edge e is refined by considering three cases: (i) the multiplicity needs to be checked because e 's path expression affects instance edges ie and ie' (predicate *caseMultsOk*), (ii) e 's path expression affects either source or target node and the multiplicity of the opposing node in the edge is mandatory or at least 1 (predicates *caseMandatoryT* and *caseMandatoryS*, respectively):

$$(SG_c, m) \sqsupseteq_{\mathcal{MCnts}} SG_a \Leftrightarrow \forall e : EsDS_{SG_a} \bullet \\ \exists peas : PEA ; peae : PEA \mid peas = startEdg(pe SG_a e) \wedge peae = endEdg(pe SG_a e) \bullet \\ \forall ie : (fE m) \sim \{\{ePEA peas\}\} ; ie' : (fE m) \sim \{\{ePEA peae\}\} \bullet \\ caseMultsOk(SG_c, m, SG_a, e, peas, peae, ie, ie') \\ \wedge (caseMandatoryT(SG_c, m, SG_a, e, peae, ie) \vee caseMandatoryS(SG_c, m, SG_a, e, peas, ie'))$$

Predicate *caseMultsOk* checks that the multiplicity constraint of given derived edge e of SG_a is satisfied by start and end instance edges, ie and ie' , respectively, provided they are affected by e 's path expression:

$$caseMultsOk(SG_c, m, SG_a, e, peas, peae, ie, ie') \\ \Leftrightarrow affectedPE(SG_c, m, SG_a, pe SG_a e, e, ie, ie') \\ \Rightarrow smfPEA SG_c peas ie \leq_{\mathcal{M}} srcma SG_a e \wedge tmfPEA SG_c peae ie' \leq_{\mathcal{M}} tgtm SG_a e$$

The functions above, namely, *affectedPE* (checks whether e 's path expression from SG_a affects instance edges ie and ie' in SG_c) *smfPEA* and *tmfPEA* are from def. 24. The constraint says that if the instance edges are affected by the constraint of the derived edge, then they must comply to the constraint.

Predicates *caseMandatoryT* and *caseMandatoryS* require that either start or end node is affected and the opposing node matches the type node, if the multiplicity constraint on the opposing node is mandatory (at least 0):

$$caseMandatoryT(SG_c, m, SG_a, e, peae, ie) \\ \Leftrightarrow (affectedPEStart(SG_c, m, SG_a, pe SG_a e, e, ie) \wedge mks 1 \leq_{\mathcal{M}} (tgtm SG_a) e) \\ \Rightarrow (fV m)(tPEA SG_c peae ie) = tgt SG_a e \\ caseMandatoryS(SG_c, m, SG_a, e, peas, ie) \\ \Leftrightarrow (affectedPEEnd(SG_c, m, SG_a, pe SG_a e, e, ie) \wedge mks 1 \leq_{\mathcal{M}} (srcma SG_a) e) \\ \Rightarrow (fV m)(sPEA SG_c peas ie) = src SG_a e$$

□

DEFINITION 24 (REFINEMENT OF MULTIPLICITY CONSTRAINTS OF DERIVED EDGES IN SGs). In a refinement, concrete SGs are required to comply to the multiplicity constraints imposed by the derived edges of their abstract counter-parts; this involves checking that the constraints imposed upon the paths of the derived edges are satisfied. Several functions support this. The following functions obtain either the source or target function (*sPEA* and *tPEA*) or the source or target multiplicity

function (*smfPEA* and *tmfPEA*) relative to direction of the encapsulated edge (whether it is inverted or not):

$$\begin{aligned}
 & sPEA, tPEA : SGr \rightarrow PEA \rightarrow (E \rightarrow V) \quad smfPEA, tmfPEA : SGr \rightarrow PEA \rightarrow (E \rightarrow Mult) \\
 & sPEA \, SG \, e = src \, SG \quad sPEA \, SG \, e^{-1} = tgt \, SG \quad tPEA \, SG \, e = tgt \, SG \quad tPEA \, SG \, e^{-1} = src \, SG \\
 & smfPEA \, SG \, e = srcma \, SG \quad smfPEA \, SG \, e^{-1} = tgtm \, SG \\
 & tmfPEA \, SG \, e = tgtm \, SG \quad tmfPEA \, SG \, e^{-1} = srcma \, SG
 \end{aligned}$$

Predicates *affectedPEAStart* and *affectedPEAEnd* indicate when an edge (*ie*) of a concrete SG (SG_c) is affected by a particular path edge atom expression (*pea* of set *PEA* of def. 15) embedded in an edge (*e*) of the abstract SG (SG_a), at either ends of the path (start or end):

$$\begin{aligned}
 & affectedPEAStart(SG_c, m, SG_a, pea, e, ie) \Leftrightarrow ie \in (fE \, m) \sim (\{ \{ ePEA \, pea \} \}) \\
 & \quad \wedge (fV \, m)(sPEA \, SG_c \, pea \, ie) = sPEA \, SG_a \, pea \, e \\
 & affectedPEAEnd(SG_c, m, SG_a, pea, e, ie) \\
 & \quad \Leftrightarrow ie \in (fE \, m) \sim (\{ \{ ePEA \, pea \} \}) \wedge (fV \, m)(tPEA \, SG_c \, pea \, ie) = tPEA \, SG_a \, pea \, e
 \end{aligned}$$

Predicates *affectedPECStart* and *affectedPECEnd* indicate when an edge (*ie*) of a concrete SG (SG_c) is affected by a particular path edge composite expression (set *PEC* of def. 15) embedded in a derived edge (*e*) of the abstract SG (SG_a), at either ends of the path (start or end):

$$\begin{aligned}
 & affectedPECStart(SG_c, m, SG_a, eat \, pea, e, ie) \Leftrightarrow affectedPEAStart(SG_c, m, SG_a, pea, e, ie) \\
 & affectedPECStart(SG_c, m, SG_a, v \triangleleft_{PE} \, pea, e, ie) \Leftrightarrow affectedPEAStart(SG_c, m, SG_a, pea, e, ie) \\
 & \quad \wedge \exists v' : (fV \, m) \sim (\{ \{ v \} \}) \bullet (sPEA \, SG_c \, pea \, ie, v') \in \preceq \, SG_c \\
 & affectedPECStart(SG_c, m, SG_a, pea \triangleright_{PE} \, v, e, ie) \Leftrightarrow affectedPEAStart(SG_c, m, SG_a, pea, e, ie) \\
 & \quad \wedge \exists v' : (fV \, m) \sim (\{ \{ v \} \}) \bullet (tPEA \, SG_c \, pea \, ie, v') \in \preceq \, SG_c \\
 & affectedPECEnd(SG_c, m, SG_a, eat \, pea, e, ie) \Leftrightarrow affectedPEAEnd(SG_c, m, SG_a, pea, e, ie) \\
 & affectedPECEnd(SG_c, m, SG_a, v \triangleleft_{PE} \, pea, e, ie) \\
 & \quad \Leftrightarrow affectedPEAEnd(SG_c, m, SG_a, pea, e, ie) \wedge \exists v' : (fV \, m) \sim (\{ \{ v \} \}) \bullet (sPEA \, SG_c \, pea \, ie, v') \in \preceq \, SG_c \\
 & affectedPECEnd(SG_c, m, SG_a, pea \triangleright_{PE} \, v, e, ie) \\
 & \quad \Leftrightarrow affectedPEAEnd(SG_c, m, SG_a, pea, e, ie) \wedge \exists v' : (fV \, m) \sim (\{ \{ v \} \}) \bullet (tPEA \, SG_c \, pea \, ie, v') \in \preceq \, SG_c
 \end{aligned}$$

Predicates *affectedPEStart* and *affectedPEEnd* indicate when an edge (*ie*) of a concrete SG (SG_c) is affected by a particular path edge expression (set *PE* of def. 15) embedded in a derived edge (*e*) of the abstract SG (SG_a), at either ends of the path (start or end):

$$\begin{aligned}
 & affectedPEStart(SG_c, m, SG_a, pec, e, ie) \Leftrightarrow affectedPECStart(SG_c, m, SG_a, pec, e, ie) \\
 & affectedPEStart(SG_c, m, SG_a, pec \circ_{PE} \, pe, e, ie) \Leftrightarrow affectedPECStart(SG_c, m, SG_a, pec, e, ie) \\
 & affectedPEEnd(SG_c, m, SG_a, pec, e, ie) \Leftrightarrow affectedPECEnd(SG_c, m, SG_a, pec, e, ie) \\
 & affectedPEEnd(SG_c, m, SG_a, pec \circ_{PE} \, pe, e, ie) \Leftrightarrow affectedPEEnd(SG_c, m, SG_a, pec, e, ie)
 \end{aligned}$$

Finally, predicate *affectedPE*, handles complete path expressions made up of many composites; it indicate when an edge (*ie*) of a concrete SG (SG_c) is affected by a particular path edge expression (set *PE* of def. 15) embedded in a derived edge (*e*)

of the abstract SG (SG_a):

$$\begin{aligned}
& affectedPE(SG_c, m, SG_a, pec, e, ie, ie') \\
& \Leftrightarrow ie = ie' \wedge affectedPECStart(SG_c, m, SG_a, pec, e, ie) \wedge affectedPECEnd(SG_c, m, SG_a, pec, e, ie) \\
& affectedPE(SG_c, m, SG_a, pec_1 \circ_{PE} pec_2, e, ie, ie') \\
& \Leftrightarrow tPEA\ SG_c\ (endEdgC\ pec_1)\ ie = sPEA\ SG_c\ (startEdgC\ pec_2)\ ie' \\
& \quad \wedge affectedPECStart(SG_c, m, SG_a, pec_1, e, ie) \wedge affectedPECEnd(SG_c, m, SG_a, pec_2, e, ie') \\
& affectedPE(SG_c, m, SG_a, pec \circ_{PE} pe, e, ie, ie') \\
& \Leftrightarrow affectedPECStart(SG_c, m, SG_a, pec, e, ie) \\
& \quad \wedge \exists ie'' : E \mid tPEA\ SG_c\ (endEdgC\ pec)\ ie = sPEA\ SG_c\ (startEdg\ pe)\ ie'' \bullet \\
& \quad affectedPE(SG_c, m, SG_a, pe, e, ie'', ie')
\end{aligned}$$

Three cases are considered above: (i) the path expression is made up of a single composite, in which case both instance edges, ie and ie' , must be the same, and the composite must be affected at both start and end; (ii) the path expression is made up of one composite followed by another, in which case both instance edges, ie and ie' must be connected, the two edges must be affected by the two composites at start and end, respectively; (iii) the path expression is made up of one composite followed by another path expression, in which case the first composite must be affected at the start, the first instance edge ie must be connected to the start edge of the path expression pe by some edge ie'' , and the remaining path expression pe must be affected. $\square$

DEFINITION 25 (EXTRACTING INSTANCE INFORMATION). Several functions extract instance information from typing morphisms. They extract: a set of nodes which are instances of given a set of meta- (or type) nodes (ins), a set of edges which are instances of a given set of meta-edges (ies), an instance graph restricted to the edges of a certain edge-type ($igRMEs$):

$$\begin{aligned}
ins(m, SG, mns) &= (fV\ m) \sim ((\prec\ SG) \sim (mns)) \\
ies(m, mes) &= (fE\ m) \sim (mes) \\
igRMEs(GwT, mes) &= GwT^G \bowtie_{Es} iesOf(GwT^T, mes)
\end{aligned}$$

Above, ins uses SG 's inheritance relation; information is derived from the inverse morphisms. $\square$

DEFINITION 26 (TOTAL REFINEMENT OF SGs). Total refinement establishes a refinement relation between a concrete $SG_c : SGr$ and an abstract $SG_a : SGr$ through morphism $m : GrM$:

$$(SG_c, m) \sqsupset^{SG} SG_a \Leftrightarrow m \in SG_c \rightarrow_{SG} SG_a \wedge (SG_c, m) \sqsupset^{SG_0} SG_a$$

This requires that (in the left-to-right order of the conjuncts): (i) morphism m is valid, and (ii) the conditions of total refinement are met.

Relation $\sqsupset^{SG_0}$ is defined as follows:

$$(SG_c, m) \sqsupset^{SG_0} SG_a \Leftrightarrow (SG_c, m) \sqsupset^{SG_0} SG_a \wedge (SG_c, m) \sqsupset_{AEs} SG_a \wedge m \sqsupset_{ANNs} SG_a$$

This requires that (in the left-to-right order of the conjuncts): (i) partial refinement's conditions are met, and (ii) SG_a 's association edges (iii) and normal nodes are adequately refined.

Predicate $\sqsupset_{AEs}$ requires that each association edge of SG_a is adequately refined in SG_c , which excludes inheritance edges (as they are not mapped to):

$$(SG_c, m) \sqsupset_{AEs} SG_a \Leftrightarrow \forall e : EsA_{SG_a} \bullet (SG_a, e) \text{ OkRefinedIn } (SG_c, m)$$

Relation `OkRefinedIn` checks that the instance relation restricted to a particular meta-edge is not empty, and maps source and target elements.:

$$\begin{aligned}
 (SG_a, me) \text{OkRefinedIn } (SG_c, m) &\Leftrightarrow \\
 \exists r : V &\leftrightarrow V ; s, t : \mathbf{P} V \mid r = \preceq_{SG_c} \circ \text{igRMEs}((gr\ SG_c, m), SG_a, \{me\}) \circ \preceq_{SG_c} \sim \\
 \wedge s &= \text{insOf}(m, SG_a, \text{src}_{SG_a}(\{me\})) \setminus (\text{NsEther}_{SG_c} \setminus \text{dom } r) \\
 \wedge t &= \text{insOf}(m, SG_a, \text{tgt}_{SG_a}(\{me\})) \setminus (\text{NsEther}_{SG_c} \setminus \text{ran } r) \bullet r \in s \leftrightarrow t \wedge r \neq \emptyset
 \end{aligned}$$

Predicate $\sqsubset_{\text{ANNs}}$ requires all normal nodes, or one of their ancestors, to be instantiated:

$$m \sqsubset_{\text{ANNs}} SG_a \Leftrightarrow \forall nn : \text{NsTy}_{SG_a} \{nnrml\} \bullet (\preceq_{SG_a})(\{nn\}) \cap \text{ran}(fV\ m) \neq \emptyset$$

□

DEFINITION 27 (MULTIPLICITY CHECKING). Predicate `rMOk` check whether a relation $r : V \leftrightarrow V$ over vertices, with a source and target sets $s, t : \mathbf{P} V$, complies with source and target multiplicities $m_s, m_t : \text{Mult}$ (def. 14). `rMOk` is defined on a case by case basis; rbounded checks whether a relation is within multiplicity bounds; below, $mm \in \text{MultMany}$, $mr \in \text{MultRange}$ and $me \in \text{MultEither}$ (def. 14):

$$\begin{aligned}
 \text{rbounded}(r, s, m) &\Leftrightarrow \forall x : s \bullet \#(r(\{x\})) \leq m \\
 \text{eitherbounded}(r, s, ms) &\Leftrightarrow \forall x : s \bullet \#(r(\{x\})) \leq ms \\
 rMOk(r, s, t, \{1\}, \{1\}) &\Leftrightarrow r \in s \rightarrow t \\
 rMOk(r, s, t, \{(0, 1)\}, \{1\}) &\Leftrightarrow r \in s \rightarrow t \\
 rMOk(r, s, t, \{1\}, \{(0, 1)\}) &\Leftrightarrow r \sim \in t \rightarrow s \\
 rMOk(r, s, t, mm, \{1\}) &\Leftrightarrow r \in s \rightarrow t \\
 rMOk(r, s, t, \{1\}, mm) &\Leftrightarrow r \sim \in t \rightarrow s \\
 rMOk(r, s, t, mr, \{1\}) &\Leftrightarrow r \in s \rightarrow t \wedge \text{rbounded}(r \sim, t, \text{the } mr) \\
 rMOk(r, s, t, \{1\}, mr) &\Leftrightarrow r \sim \in t \rightarrow s \wedge \text{rbounded}(r, s, \text{the } mr) \\
 rMOk(r, s, t, me, \{1\}) &\Leftrightarrow r \in s \rightarrow t \wedge \text{eitherbounded}(r \sim, t, me) \\
 rMOk(r, s, t, \{1\}, me) &\Leftrightarrow r \sim \in t \rightarrow s \wedge \text{eitherbounded}(r, s, me) \\
 rMOk(r, s, t, \{(0, 1)\}, \{(0, 1)\}) &\Leftrightarrow r \in s \leftrightarrow t \\
 rMOk(r, s, t, mm, \{(0, 1)\}) &\Leftrightarrow r \in s \leftrightarrow t \\
 rMOk(r, s, t, \{(0, 1)\}, mm) &\Leftrightarrow r \sim \in t \leftrightarrow s \\
 rMOk(r, s, t, mr, \{(0, 1)\}) &\Leftrightarrow r \in s \leftrightarrow t \wedge \text{rbounded}(r \sim, t, \text{the } mr) \\
 rMOk(r, s, t, \{(0, 1)\}, mr) &\Leftrightarrow r \sim \in t \leftrightarrow s \wedge \text{rbounded}(r, s, \text{the } mr) \\
 rMOk(r, s, t, me, \{(0, 1)\}) &\Leftrightarrow r \in s \leftrightarrow t \wedge \text{eitherbounded}(r \sim, t, me) \\
 rMOk(r, s, t, \{(0, 1)\}, me) &\Leftrightarrow r \sim \in t \leftrightarrow s \wedge \text{eitherbounded}(r, s, me) \\
 rMOk(r, s, t, mm_1, mm_2) &\Leftrightarrow r \in s \leftrightarrow t \\
 rMOk(r, s, t, mm, mr) &\Leftrightarrow r \in s \leftrightarrow t \wedge \text{rbounded}(r, s, \text{the } mr) \\
 rMOk(r, s, t, mr, mm) &\Leftrightarrow r \in s \leftrightarrow t \wedge \text{rbounded}(r \sim, t, \text{the } mr) \\
 rMOk(r, s, t, mm, me) &\Leftrightarrow r \in s \leftrightarrow t \wedge \text{eitherbounded}(r, s, me) \\
 rMOk(r, s, t, me, mm) &\Leftrightarrow r \in s \leftrightarrow t \wedge \text{eitherbounded}(r \sim, t, me) \\
 rMOk(r, s, t, mr_1, mr_2) &\Leftrightarrow r \in s \leftrightarrow t \wedge \text{rbounded}(r, s, \text{the } mr_2) \wedge \text{rbounded}(r \sim, t, \text{the } mr_1) \\
 rMOk(r, s, t, me_1, me_2) &\Leftrightarrow r \in s \leftrightarrow t \wedge \text{eitherbounded}(r, s, me_2) \wedge \text{eitherbounded}(r \sim, t, me_1)
 \end{aligned}$$

□

DEFINITION 28 (MORPHISMS FROM GRAPHS TO SGs). Given $G : Gr$ and $SG : SGr$, a G - SG morphism $m : G \rightarrow_{G2SG} SG$ is a pair of functions $m = (fv, fe)$ mapping nodes and edges respectively. The set of such morphisms is defined as:

$$G \rightarrow_{G2SG} SG = \{(fv, fe) \mid fv \in Ns_G \rightarrow Ns_{SG} \wedge fe \in Es_G \rightarrow EsA_{SG} \mid \\ fv \circ src_G \subseteq src^*_{SG} \circ fe \wedge fv \circ tgt_G \subseteq tgt^*_{SG} \circ fe\}$$

Above, the target edges comprise association edges only (set EsA , def. 17).

Relation $\Rightarrow^{GwT}$ provides an alternative formulation for graphs with typing $GwT : GrwT$ (def. 11):

$$GwT \Rightarrow^{GwT} SG \Leftrightarrow GwT^T \in GwT^G \rightarrow_{G2SG} SG$$

□

DEFINITION 29 (AUXILIARY FUNCTIONS OF PATH EXPRESSIONS). Function $rPEA$ builds a relation from a path expression atom through the graph edge-restriction operator $\bowtie_{Es}$ (def.8), where $e \in E$:

$$rPEA : GrwT \times SGr \times PEA \rightarrow (V \leftrightarrow V) \\ rPEA(GwT, SG, e) = (GwT^G \bowtie_{Es} ies(GwT^T, \{e\}))^{**} \\ PEA(GwT, SG, e^{-1}) = rPEA(GwT, SG, e) \sim$$

Above, functions ins and ies yield the instances of a given node or edge type, respectively (def. 25).

Function rPE builds a relation from a given path expression, where $pea \in PEA$:

$$rPE : GrwT \times SGr \times PE \rightarrow (V \leftrightarrow V) \\ rPE(GwT, SG, pea) = rPEA(GwT, SG, pea) \\ rPE(GwT, SG, v \triangleleft_{PE} pea) = ins(GwT^T, SG, \{v\}) \triangleleft rPEA(GwT, SG, pea) \\ rPE(GwT, SG, pea \triangleright_{PE} v) = rPEA(GwT, SG, pea) \triangleright ins(GwT^T, SG, \{v\}) \\ rPE(GwT, SG, pe_1 \circ_{PE} pe_2) = rPE(GwT, SG, pe_1) \cup rPE(GwT, SG, pe_2)$$

Function $ape : SGr \rightarrow E \rightarrow PE$ totalises function pe (gives path expressions of constraint edges, def. 17), to all multiplicity edges:

$$ape SG = \{(e, e) \mid e \in EsM SG\} \oplus pe SG$$

The path expression of a multiplicity edge is the edge itself, or the edge's path expression (function pe).

Function $multComp : Mult \times Mult \rightarrow Mult$ gives the sequential composition of two multiplicities, where $mm_1, mm_2 : MultMany$, and $m_1, m_2 : Mult$:

$$multComp(mm_1, mm_2) = \{*\} \quad multComp(m_1, m_2) = \{0\} \Leftrightarrow m_1 = \{0\} \vee m_2 = \{0\} \\ multComp(m_1, \{1\}) = m_1 \quad multComp(\{1\}, m_2) = m_2 \\ multComp(\{(0, 1)\}, m_2) = \{0\} \cup m_2 \quad multComp(m_1, \{(0, 1)\}) = \{0\} \cup m_1$$

Function $\text{src}^* \text{MEMOk} : \text{SGr} \times E \rightarrow E \leftrightarrow V$ gives extended source relation specific to a particular meta-edge, derived from function src_{PE}^* (gives extended source relation of a path expression, def. 29):

$$\text{src}^* \text{MEMOk}(\text{SG}, \text{me}) = \text{src}_{\text{PE}}^*(\text{SG}, \text{ape SG me}) \triangleright (\text{src}_{\text{SG}}^* \langle \{ \text{me} \} \rangle)$$

Function $\text{tgt}^* \text{MEMOk} : \text{SGr} \times E \rightarrow E \leftrightarrow V$ gives extended target relation specific to a particular meta-edge, derived from function tgt_{PE}^* (gives extended target relation of a path expression, def. 29):

$$\text{tgt}^* \text{MEMOk}(\text{SG}, \text{me}) = \text{tgt}_{\text{PE}}^*(\text{SG}, \text{ape SG me}) \triangleright (\text{tgt}_{\text{SG}}^* \langle \{ \text{me} \} \rangle)$$

Predicate MEMOk checks whether edge instances comply to the corresponding multiplicity constraints using the relation obtained from rMEMOk :

$$\begin{aligned} (\text{SG}, \text{me}, \text{pe}) \text{MEMOk GwT} &\Leftrightarrow \exists r : V \leftrightarrow V ; s, t : \mathbf{P} V \mid r = \text{rMEMOk}(\text{SG}, \text{me}, \text{GwT}) \\ &\wedge s = \text{ins}(\text{GwT}^T, \text{SG}, \text{src}^* \text{MEMOk}(\text{SG}, \text{me}) \langle \{ \text{srcPE}(\text{ape SG me}) \} \rangle) \\ &\wedge t = \text{ins}(\text{GwT}^T, \text{SG}, \text{tgt}^* \text{MEMOk}(\text{SG}, \text{me}) \langle \{ \text{tgtPE}(\text{ape SG me}) \} \rangle) \\ &\bullet \text{rMok}(r, s, t, \text{smPE SG}(\text{ape SG me}), \text{tmPE SG}(\text{ape SG me})) \end{aligned}$$

Above, predicate rMok (def. 27) checks if the relation derived from the given path expression (through function rMEMOk , def. 29) with appropriate source and target nodes (derived through function ins , def. 25) complies with both source and target SG multiplicities of the meta-edge or its path expression.

Predicate $\ni_{\text{FI}}$ checks that the instance graph excludes direct instances of SG ethereal nodes (includes types abstract, virtual and enum), which involves taking the inversion of the type morphism:

$$\text{GwT} \ni_{\text{FI}} \text{SG} \Leftrightarrow ((fV \circ ty) \text{GwT}) \sim (\langle \text{NsEther SG} \rangle) = \emptyset$$

Predicate $\ni_{\text{PNS}}$ checks that instances of the same compound do not share parts:

$$\text{GwT} \ni_{\text{PNS}} \text{SG} \Leftrightarrow \forall ec : \{ \text{ecomp dbi}, \text{ecomp duni} \} \bullet \text{igRMEs}(\text{GwT}, \{ ec \}) \stackrel{+}{\bullet} \in \text{injrel}$$

Relation obtained from instance graph restricted to composition edges (function igRMEs) must be injective to disallow sharing of part instances.

Finally, $\ni_{\text{Cnts}}$ checks that the instance complies with certain constraints imposed by the type, namely that the instance satisfies: the type's numeric constraints and the type's value edge constraints:

$$\text{GwT} \ni_{\text{Cnts}} \text{SG} \Leftrightarrow \text{INumbersOk GwT} \wedge \text{IVCEsOk}(\text{SG}, \text{GwT})$$

Predicate INumbersOk checks that the constraints concerning natural numbers, integers and reals are satisfied, which means that the numbers extracted from the nodes marked as instances of some numeric set must indeed be members of the corresponding numeric set:

$$\begin{aligned} \text{INumbersOk GwT} &\Leftrightarrow \text{INsOk}(\text{SG}, \text{GwT}) \wedge \text{IZsOk}(\text{SG}, \text{GwT}) \wedge \text{IRsOk}(\text{SG}, \text{GwT}) \\ \text{INsOk GwT} &\Leftrightarrow \forall n\text{nat} : (fV(\text{GwT}^T)) \sim (\langle \{ n\text{NatS} \} \rangle) \bullet \exists n : \mathbb{N} \bullet n \in \text{toZ } n\text{nat} \\ \text{IZsOk GwT} &\Leftrightarrow \forall n\text{int} : (fV(\text{GwT}^T)) \sim (\langle \{ n\text{IntS} \} \rangle) \bullet \exists n : \mathbb{Z} \bullet n \in \text{toZ } n\text{int} \\ \text{IRsOk GwT} &\Leftrightarrow \forall n\text{real} : (fV(\text{GwT}^T)) \sim (\langle \{ n\text{RealS} \} \rangle) \bullet \exists x : \mathbb{R} \bullet x \in \text{toR } n\text{real} \end{aligned}$$

Predicate *IVCEsOk* checks that each VCE satisfies the required constraints, depending on the type of VCE, either edge or node:

$$\begin{aligned} \text{IVCEsOk}(SG, GwT) &\Leftrightarrow \forall vce : \text{EsVCnt}_{SG} \bullet \\ &\quad \text{isVCEECnt}(SG, vce) \Rightarrow \text{satisfiesVCEECnt}(SG, GwT, vce) \\ &\quad \wedge \text{isVCENCnt}(SG, vce) \Rightarrow \text{satisfiesVCENCnt}(SG, GwT, vce) \end{aligned}$$

Predicate *satisfiesVCEECnt* checks that the corresponding arithmetic constraint is satisfied for those appropriate edges which are instances of the VCE's embedded edge

$$\begin{aligned} \text{satisfiesVCEECnt}(SG, GwT, vce) &\Leftrightarrow \\ &\quad \forall ie : fE(GwT^T) \sim ((\text{second} \circ \text{vcei}_{SG}) vce) \mid fV GwT^T(\text{src } GwT^G ie) = \text{src}_{SG} vce \bullet \\ &\quad \text{satisfiesCnt}(SG, GwT^T, \text{tgt } GwT^G ie, (\text{first} \circ \text{vcei}_{SG}) vce, \text{tgt}_{SG} vce) \end{aligned}$$

Predicate *satisfiesVCENCnt* checks that the corresponding constraint is satisfied for each instance of the VCE's source node:

$$\begin{aligned} \text{satisfiesVCENCnt}(SG, GwT, vce) &\Leftrightarrow \forall in : fV(GwT^T) \sim (\{\text{src}_{SG} vce\}) \bullet \\ &\quad \text{satisfiesCnt}(SG, GwT^T, in, (\text{first} \circ \text{vcei}_{SG}) vce, \text{tgt}_{SG} vce) \end{aligned}$$

A constraint is satisfied for a given $SG : SGr$, morphism $t : GrM$, instance node source $ns : V$, operator $op : SGVCEOP$ (def. 16) and type node target $nt : V$, provided the two numbers extracted from the nodes satisfy the required constraint derived from the operator op , or the op is an equality and the type mapping of ns matches nt , and ns and nt are values:

$$\begin{aligned} \text{satisfiesCnt}(SG, t, ns, op, nt) &\Leftrightarrow ns \in \text{dom}(fV t) \\ &\quad \wedge (\exists n_1, n_2 : \mathbb{A} \mid n_1 \in \text{toNum}(SG, ns, (fV t) ns) \wedge n_2 \in \text{toNum}(SG, nt, nt) \bullet (n_1, n_2) \in rOp op \\ &\quad \vee op = eq \wedge (fV t) ns = nt \wedge nt \in NsVa) \end{aligned}$$

Function *toNum* extracts integer or real number of given node ns , depending on the numeric type of its type node nt in given SG :

$$\text{toNum}(SG, ns, nt) = \begin{cases} \text{to}\mathbb{Z} ns & \text{if } nt \preceq_{SG} nNatS \vee nt \preceq_{SG} nIntS \\ \text{to}\mathbb{R} n & \text{if } nt \preceq_{SG} nRealS \\ \emptyset & \text{otherwise} \end{cases}$$

Finally, function *rOp* obtains the relation that is required to exist between two numbers for the given operator op (of set *SGVCEOP*, def 16):

$$\begin{aligned} rOp eq &= \{n_1, n_2 : \mathbb{A} \mid n_1 = n_2\} & rOp neq &= \{n_1, n_2 : \mathbb{A} \mid n_1 \neq n_2\} \\ rOp leq &= \{n_1, n_2 : \mathbb{A} \mid n_1 \leq n_2\} & rOp geq &= \{n_1, n_2 : \mathbb{A} \mid n_1 \geq n_2\} \\ rOp lt &= \{n_1, n_2 : \mathbb{A} \mid n_1 < n_2\} & rOp gt &= \{n_1, n_2 : \mathbb{A} \mid n_1 > n_2\} \end{aligned}$$

□

DEFINITION 31 (EXTRA TYPING FOR SGs). A $SG_s : SGr$ is compatible with respect to extra typing with $SG_t : SGr$ via morphism m , written $(SG_s, m) \dashv^{\text{SG}} SG_t$, whenever the following holds:

$$(SG_s, m) \dashv^{\text{SG}} SG_t \Leftrightarrow m \in SG_s \rightarrow_{SG} SG_t \wedge (SG_s, m) \dashv_{\mathcal{M}} SG_t \wedge m \dashv_{NT} SG_t \wedge (SG_s, m) \dashv_{ET} SG_t$$

The following functions deal with references: (i) $\overset{G}{\hookrightarrow}$ builds the references graph, (ii) $\hookrightarrow$ builds the references partial function from the references graph:

$$\begin{aligned} \overset{G}{\hookrightarrow} : Fr_0 &\rightarrow Gr & \hookrightarrow : Fr_0 &\rightarrow V \leftrightarrow V \\ \overset{G}{\hookrightarrow} F &= ((NsP \circ fSG)F \cup fRNs F, EsR F, srcR F, tgtR F) & \hookrightarrow F &= (\overset{G}{\hookrightarrow} F)^{\leftrightarrow} \end{aligned}$$

□

DEFINITION 33 (UNION OF FRAGMENTS). The union of fragments $F_1, F_2 : Fr$, written $F_1 \cup_F F_2$, is the union of the fragment's components:

$$F_1 \cup_F F_2 = (fSG F_1 \cup_{SG} fSG F_2, EsR F_1 \cup EsR F_2, srcR F_1 \cup srcR F_2, tgtR F_1 \cup tgtR F_2)$$

The generalised union $\bigcup_F$ yields the union of a set of fragments; it is defined recursively as:

$$\bigcup_F : \mathbf{P} Fr_0 \rightarrow Fr_0 \quad \bigcup_F \{\} = \emptyset_F \quad \bigcup_F (\{F\} \cup Fs) = F \cup_F (\bigcup_F Fs)$$

□

DEFINITION 34 (FRAGMENT RESOLUTION). Given a fragment $F : Fr_0$, $\bullet$ yields the resolved fragment in which proxies are substituted by the references through graph subsumption. Several functions are involved: (i) $\rightsquigarrow$ gives subsumptions' substitution by restricting partial function $\hookrightarrow$ to resolvable proxies with inner references, (ii) $\bullet^{SG}$ yields resolved SG, (iii) $\bullet$ gives new reference edges of resolved fragment and actual resolved fragment (iv) the actual resolution is achieved through subsumption ($\odot^{SG}$, def. 21):

$$\begin{aligned} \rightsquigarrow : Fr_0 &\rightarrow V \rightarrow V & \rightsquigarrow F &= (\hookrightarrow F) \triangleright (fLNs F) \\ \bullet^{SG} : Fr_0 &\rightarrow SGr & rEsR : Fr_0 &\rightarrow \mathbf{P} E, \bullet : Fr_0 \rightarrow Fr_0 \\ \bullet^{SG} F &= (fSG F) \odot^{SG} (\rightsquigarrow F) & rEsR F &= \text{dom}((srcR F) \triangleright \text{dom}(\rightsquigarrow F)) \\ \bullet F &= (\bullet^{SG} F, rEsR F, (rEsR F) \triangleleft (srcR F), (rEsR F) \triangleleft (tgtR F)) \end{aligned}$$

□

DEFINITION 35 (PARTIAL FRAGMENTS). Set of acyclic fragments Fr_a includes all base fragments (def. 32) with acyclic reference graphs. Partial fragments, set Fr , includes all acyclic fragments with partially resolved SGs:

$$Fr_a = \{F \mid F \in Fr_0 \wedge \odot(\overset{G}{\hookrightarrow} F)\} \quad Fr = \{F \mid F \in Fr_a \wedge \bullet^{SG} F \in SGr\}$$

The following predicates, used in the laws that follow, say whether: (i) two fragments are mutually disjoint ($\boxminus_F$), (ii) a set of fragments is mutually disjoint ($\boxplus_F$), (iii) the flow of references goes from one fragment to another ($\subseteq^{rs}$), and (iv) the flow of references between two fragments is one-way only ($\Rightarrow$), meaning that one fragment references another but not the other way round:

$$\begin{aligned} \boxminus_F(F_1, F_2) &\Leftrightarrow fLNs F_1 \cap fLNs F_2 = \emptyset \wedge fEs F_1 \cap fEs F_2 = \emptyset \\ \boxplus_F Fs &\Leftrightarrow \forall i, j : \text{dom } Fs \mid i \neq j \bullet \boxminus_F(Fs i, Fs j) \\ F_1 \subseteq^{rs} F_2 &\Leftrightarrow \text{ran}(tgtR F_1) \cap fNs F_2 \neq \emptyset \quad F_1 \Rightarrow F_2 \Leftrightarrow F_1 \subseteq^{rs} F_2 \wedge \neg(F_2 \subseteq^{rs} F_1) \end{aligned}$$

Laws.

$$\begin{aligned}
& F_1 \in Fr_0 ; F_2 \in Fr_0 ; \exists_F(F_1, F_2) \vdash \exists_{SGs}(fSG F_1, fSG F_2) \quad F \in Fr_a \vdash \overset{G}{\leftrightarrow} F \in Gr \\
& F_1 \in Fr ; F_2 \in Fr ; \exists_F(F_1, F_2) ; (F_1 \Rightarrow F_2 \vee F_2 \Rightarrow F_1) \vdash F_1 \cup_F F_2 \in Fr \\
& F_1 \cup_F F_2 \in Fr ; \exists_F(F_1, F_2) ; (F_1 \Rightarrow F_2 \vee F_2 \Rightarrow F_1) \vdash F_1 \in Fr \wedge F_2 \in Fr \\
& F \in Fr \vdash \bullet^{SG} F = (fSG \circ \bullet) F \quad \vdash \leftrightarrow F \in ((NsP \circ fSG) F) \rightarrow V \quad F \in Fr \vdash \bullet F \in Fr
\end{aligned}$$

□

DEFINITION 36 (TOTAL FRAGMENTS). Set TFr includes acyclic fragments with local references only (predicate $refsLocal$) and whose underlying resolved SG is total (set $TSGr$, def. 20):

$$refsLocal F \Leftrightarrow fRNs F \subseteq fLN s F \quad TFr = \{F \mid F \in Fr_a \wedge refsLocal F \wedge \bullet^{SG} F \in TSGr\}$$

□

DEFINITION 37 (FRAGMENT MORPHISMS). A fragment morphism $m : F_s \rightarrow_F F_t$ is a pair of functions $m = (fv, fe)$ mapping nodes and edges respectively. The set of fragment morphisms is defined as:

$$\begin{aligned}
& F_s \rightarrow_F F_t = \{(fv, fe) \mid fv \in fLN s_{F_s} \rightarrow fLN s_{F_t} \wedge fe \in fEsC_{F_s} \rightarrow fEsC_{F_t} \\
& \wedge (\bullet^{SG} F_s, (fv, fe) \Rightarrow_\bullet (F_s, F_t)) \Rightarrow^{SG} \bullet^{SG} F_t\}
\end{aligned}$$

Fragment morphisms, which map the local nodes and connection edges of fragments (functions $fLN s$ and $fEsC$, def. 35) to exclude reference and inheritance edges, rely on fragment resolution; the morphism's nodes mapping is resolved through function $\Rightarrow_\bullet$; the mappings are then required to be in the set of SG morphisms of the two resolved fragments' SGs (obtained through function $\bullet^{SG}$).

Morphism resolution is defined as:

$$m \Rightarrow_\bullet (F_s, F_t) = ((\rightsquigarrow_{F_s}^\oplus \boxtimes fLN s_{F_s}) \sim \circ (fv \ m) \circ (\rightsquigarrow_{F_t}^\oplus \boxtimes fLN s_{F_t}), fe \ m)$$

Above, the resolution function $\rightsquigarrow$ (def. 34) is stretched by using the relation override closure $^\oplus$ (def. 4).

The relation between two fragments $F_s, F_t : Fr$ through morphism $m : GrM$ is defined as:

$$(F_s, m) \Rightarrow^F F_t \Leftrightarrow m \in F_s \rightarrow_F F_t$$

□

DEFINITION 38 (PARTIAL FRAGMENT REFINEMENT). A concrete fragment $F_c : Fr$ partially refines an abstract fragment $F_a : Fr$ via a morphism $m : GrM$, from concrete to abstract, written $(F_c, m) \sqsupseteq^F F_a$, whenever the following holds:

$$(F_c, m) \sqsupseteq^F F_a \Leftrightarrow (F_c, m) \Rightarrow^F F_a \wedge (\bullet^{SG} F_c, m \Rightarrow_\bullet (F_c, F_a)) \sqsupseteq^{SG_0} \bullet^{SG} F_a$$

The above says: (i) F_c is related to F_a through morphism m (def. 37), (ii) SGs of resolved fragments satisfy extra conditions of partial refinement between SGs (def. 23). □

DEFINITION 39 (TOTAL FRAGMENT REFINEMENT). A concrete fragment $F_c : Fr$ totally refines an abstract fragment $F_a : Fr$ via morphism $m : GrM$, from concrete to abstract, written $(F_c, m) \sqsupset F_a$, whenever the following holds:

$$(F_c, m) \sqsupset F_a \Leftrightarrow (F_c, m) \Rightarrow^F F_a \wedge \{F_c, F_a\} \subseteq TFr \wedge (\bullet^{SG} F_c, m \Rightarrow_\bullet (F_c, F_a)) \sqsupset^{SG_0} \bullet^{SG} F_a$$

The above says: (i) fragment F_c is related to F_a through morphism m (def. 37), (ii) both fragments F_c and F_a are total, (iii) SGs of resolved fragments satisfy extra conditions of total refinement (def. 26). $\square$

DEFINITION 40 (FRAGMENTS AS TYPES). The compliance of a graph with a typing morphism $GwT : GrwT$ (def. 11) to its fragment type $F : Fr$, written, $GwT \ni^F F$, is defined as:

$$GwT \ni^F F \Leftrightarrow GwT \ni^{SG} \odot^{SG} F$$

This reduces typing by a fragment to typing by the resolved fragment's SG. $\square$

DEFINITION 41 (EXTRA TYPING FOR FRAGMENTS). Extra-type compatibility of a source fragment $F_s : Fr$ with respect to a target fragment $F_t : Fr$, written $F_s \dashv^F F_t$, is defined as:

$$F_s \dashv^F F_t \Leftrightarrow \text{fet } F_s \neq \emptyset_{GM} \wedge (\odot^{SG}_{F_s, \text{fet } F_s} \dashv^{SG} (\odot^{SG}_{F_t}))$$

The compatibility conditions are as follows: (i) F_s 's extra typing morphism must not be empty and (ii) the SGs of the resolved fragments must be extra-type compatible ($\dashv^{SG}$).

Extra typing compliance of a $Gwet : GrwET$ (def. 12), typed by a fragment $F_s : Fr$, to a $Gwt : GrwT$ (def. 11), typed by a fragment $F_t : Fr$, written $(Gwet, F_s) \models^F (Gwt, F_t)$, is defined as:

$$\begin{aligned} (Gwet, F_s) \models^F (Gwt, F_t) &\Leftrightarrow Gwet^{Gw} \ni^F F_s \wedge Gwt \ni^F F_t \\ &\wedge \text{domg}(Gwet^{ET}) =_p \text{domg}((\text{fet } F_s) \circ_G (Gwet^T)) \wedge Gwet^{ET} \in (Gwet^G) \rightarrow_G (Gwt^G) \wedge F_s \dashv^F F_t \end{aligned}$$

This states that: (i) $Gwet$'s GwT is typed by F_s — $Gwet^{Gw} \ni^F F_s$ —, (ii) Gwt is typed by F_t — $Gwt \ni^F F_t$ —, (iii) the domain of $Gwet$'s extra typing morphism is the domain of the morphism obtained by composing F_s 's extra-type morphism with $Gwet$'s counterpart — $\text{domg}(Gwet^{ET}) =_p \text{domg}((\text{fet } F_s) \circ_G (Gwet^T))$ —, (iv) $Gwet$'s extra typing morphism is a partial morphism from $Gwet$ to Gwt — $Gwet^{ET} \in Gwet^G \rightarrow_G Gwt^G$ —, and (v) F_s is extra-type compatible with F_t — $F_s \dashv^F F_t$. $\square$

DEFINITION 42 (GLOBAL FRAGMENT GRAPHS). A $GFG : GFGr$ is a graph — $GFGr \subseteq Gr$ (def. 7). Set of well-formed GFGs includes all those graphs which are acyclic after the self edges are removed:

$$GFGr = \{G : Gr \mid \odot(G \triangleright_{Es} (Es \ G \setminus EsId \ G))\}$$

Relation $\rightsquigarrow$ gives fragments referenced by a particular fragment through the transitive closure:

$$_ \rightsquigarrow : GFGr \rightarrow V \leftrightarrow V \quad GFG \rightsquigarrow = (GFG \leftrightarrow)^+$$

$\square$

DEFINITION 43 (MODELS). A model is a pair $M = (GFG, fd)$ comprising a $GFG : GFGr$ (def. 42) and a total function $fd : Ns \ GFG \rightarrow Fr$ which maps GFG nodes representing fragments to their fragment definitions (set Fr , def. 35). The set of base models is defined as:

$$Mdl_0 = \{(GFG, fd) \mid GFG \in GFGr \wedge fd \in Ns \ GFG \rightarrow Fr \wedge \boxplus_F fd\}$$

All fragments of the model are required to be mutually disjoint — conjunct $\boxplus_F fd$ (see def. 35 for $\boxplus_F$).

Projection functions $mGFG$ and mFD extract the components of a model. Function $mUFs$ yields union of all fragments of a model, and $from$ gives fragment provenance of any model node:

$$\begin{aligned} mGFG : Mdl_0 &\rightarrow GFGr & mFD : Mdl_0 &\rightarrow V \leftrightarrow Fr & mUFs : Mdl_0 &\rightarrow Fr & from : Mdl_0 &\rightarrow V \leftrightarrow V \\ mGFG(GFG, fd) &= GFG & mFD(GFG, fd) &= fd \\ mUFs M &= \bigcup_F(\text{ran } mFD_M) & from M v &= (\mu \text{ vf} : (Ns \circ mGFG)M \mid v \in fLNs(mFD_M \text{ vf})) \end{aligned}$$

Predicate $\uparrow M$ says whether the model's fragments comply with the GFG. Each proxy of the model and its referent must be consistent with the $\rightsquigarrow$ relation (def. 42) which captures the referencing flow:

$$\begin{aligned} \uparrow M &\Leftrightarrow \exists UF : Fr_0 \mid UF = mUFs M \bullet \\ \forall p : (NsP \circ fSG)UF \bullet (from M p, from M(\rightsquigarrow UF p)) &\in ((- \rightsquigarrow) \circ mGFG)M \end{aligned}$$

Set of valid models Mdl includes those whose union of fragments is total — $(mUFs M) \in TFr$ — and whose underlying referencing complies with the model's GFG — $\uparrow M$.

$$Mdl = \{M \mid M \in Mdl_0 \wedge (mUFs M) \in TFr \wedge \uparrow M\}$$

From a model, it is possible to obtain the fragment resulting from resolving the union of the model's fragments, called the model resolution fragment, through function $\odot^M : Mdl \rightarrow Fr$:

$$\odot^M = \odot \circ mUFs$$

Laws.

$$M \in Mdl \vdash \odot^M M \in TFr$$

□

DEFINITION 44 (MODEL MORPHISMS). Given models $M_s, M_t : Mdl$, a fragment morphism $m : M_s \rightarrow_M M_t$, such that $m \in GrM$ (def. 9) defines a mapping from the nodes and edges of the fragments of M_s into their M_t counter-parts. The set of morphisms between two models is defined as:

$$M_s \rightarrow_M M_t = \{m \mid m \in GrM \wedge \exists UF_s, UF_t : Fr_0 \mid UF_s = mUFs M_s \wedge UF_t = mUFs M_t \bullet m \in UF_s \rightarrow_F UF_t\}$$

The set of morphisms between the two models is the morphisms between the two fragments with the union of the fragments of each model.

The relation between two models $M_s, M_t : Mdl$ via a set of morphisms $ms : \mathbf{P} GrM$ is defined as:

$$(M_s, ms) \Rightarrow^M M_t \Leftrightarrow \bigcup_{GM} ms \in M_s \rightarrow_M M_t$$

□

DEFINITION 45 (MODEL REFINEMENT). A model $M_c : Mdl$ refines another $M_a : Mdl$, through a set of morphisms $ms : \mathbf{P} GrM$, where each morphism maps elements of M_c into M_a , written $(M_c, ms) \sqsupset^M M_a$, provided the following holds:

$$(M_c, ms) \sqsupset^M M_a \Leftrightarrow \exists UF_c, UF_a : Fr_0 \mid UF_c = mUFs M_c \wedge UF_a = mUFs M_a \bullet (UF_c, \bigcup_{GM} ms) \sqsupset^F UF_a$$

Above, union of fragments of M_c must refine union of fragments of M_a via morphism $\bigcup_{GM} ms$. □

DEFINITION 46 (MODELS AS TYPES). A graph with typing $GwT : GrwT$ (def. 11) is a compliant instance of a type model $M : Mdl$, written $GwT \ni^M M$, provided the following holds:

$$GwT \ni^M M \Leftrightarrow GwT \ni^F mUFs M$$

GwT must comply to the union of fragments of M , obtained through function $mUFs$ (def. 43). $\square$

DEFINITION 47 (EXTRA TYPING FOR MODELS). A source model $M_s : Mdl$ is extra-type compatible with a target model $M_t : Mdl$, written $M_s \dashv^M M_t$, whenever the unions of the models' fragments are extra-type compatible:

$$M_s \dashv^M M_t \Leftrightarrow mUFs M_s \dashv^F mUFs M_t$$

Likewise for extra-type compliance, which reduces compliance between models to compliance between the union of the models' fragments:

$$(GwET, M_s) \Vdash^M (GwT, M_t) \Leftrightarrow (GwET, mUFs M_s) \Vdash^F (GwT, mUFs M_t)$$

$\square$